

# *pnpn* and Other Devices

# 17

## CHAPTER OBJECTIVES

To become familiar with the characteristics and areas of application of

- Silicon-controlled rectifiers (SCRs)
- Silicon-controlled switches (SCSs)
- Gate turn-off switches (GTO)
- Light-activated SCR (LASCR)
- Shockley diodes and diacs
- Triacs
- Phototransistors and opto-isolators
- Unijunction and programmable unijunction transistors

## 17.1 INTRODUCTION

In Chapter 17, a number of important devices not discussed in detail in earlier chapters are introduced. The two-layer semiconductor diode has led to three-, four-, and even five-layer devices. A family of four-layer *pnpn* devices will first be considered: the SCR (silicon-controlled rectifier), the SCS (silicon-controlled switch), the GTO (gate turn-off switch), the LASCR (light-activated SCR), and then an increasingly important device—the UJT (unijunction transistor). Those four-layer devices with a control mechanism are commonly referred to as *thyristors*, although the term is most frequently applied to the SCR. The chapter closes with an introduction to the phototransistor, opto-isolators, and the PUT (programmable unijunction transistor).

## *pnpn* DEVICES

### 17.2 SILICON-CONTROLLED RECTIFIER

Within the family of *pnpn* devices, the silicon-controlled rectifier is of greatest interest. It was first introduced in 1956 by Bell Telephone Laboratories. Some of the more common areas of application for SCRs include relay controls, time-delay circuits, regulated power suppliers, static switches, motor controls, choppers, inverters, cycloconverters, battery chargers, protective circuits, heater controls, and phase controls.

In recent years, SCRs have been designed to *control* powers as high as 10 MW with individual ratings as high as 2000 A at 1800 V. Its frequency range of application has also been extended to about 50 kHz, permitting some high-frequency applications such as induction heating and ultrasonic cleaning.

### 17.3 BASIC SILICON-CONTROLLED RECTIFIER OPERATION

As the terminology indicates, the SCR is a rectifier constructed of silicon material with a third terminal for control purposes. Silicon was chosen because of its high temperature and power capabilities. The basic operation of the SCR is different from that of the fundamental two-layer semiconductor diode in that a third terminal, called a *gate*, determines when the rectifier switches from the open-circuit to the short-circuit state. It is not enough to simply forward-bias the anode-to-cathode region of the device. In the conduction region, the dynamic resistance of the SCR is typically  $0.01 \Omega$  to  $0.1 \Omega$ . The reverse resistance is typically  $100 \text{ k}\Omega$  or more.

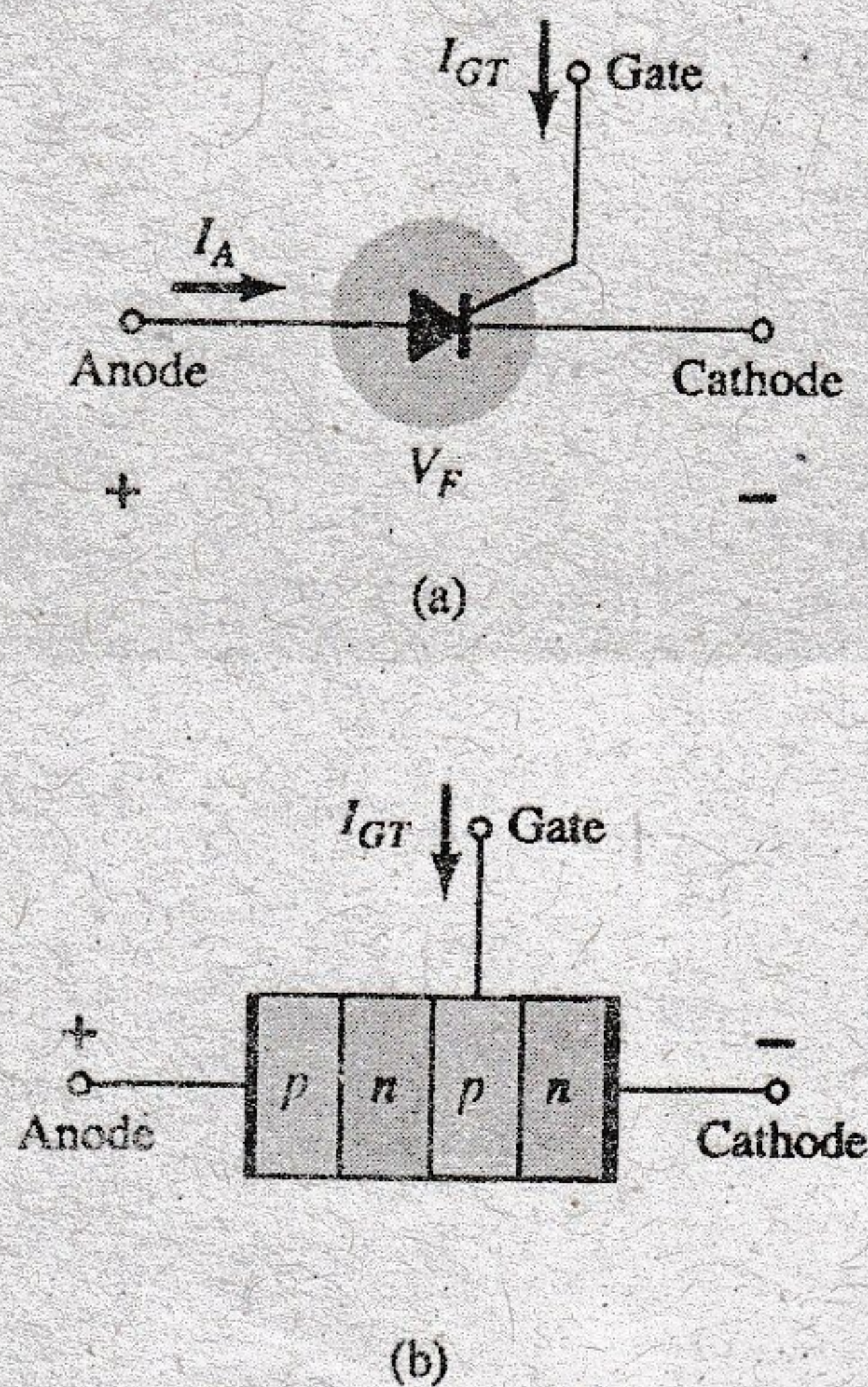
The graphic symbol for the SCR is shown in Fig. 17.1 with the corresponding connections to the four-layer semiconductor structure. As indicated in Fig. 17.1a, if forward conduction is to be established, the anode must be positive with respect to the cathode. This is not, however, a sufficient criterion for turning the device on. A pulse of sufficient magnitude must also be applied to the gate to establish a turn-on gate current, represented symbolically by  $I_{GT}$ .

A more detailed examination of the basic operation of an SCR is best effected by splitting the four-layer *pnpn* structure of Fig. 17.1b into two three-layer transistor structures as shown in Fig. 17.2a and then considering the resultant circuit of Fig. 17.2b.

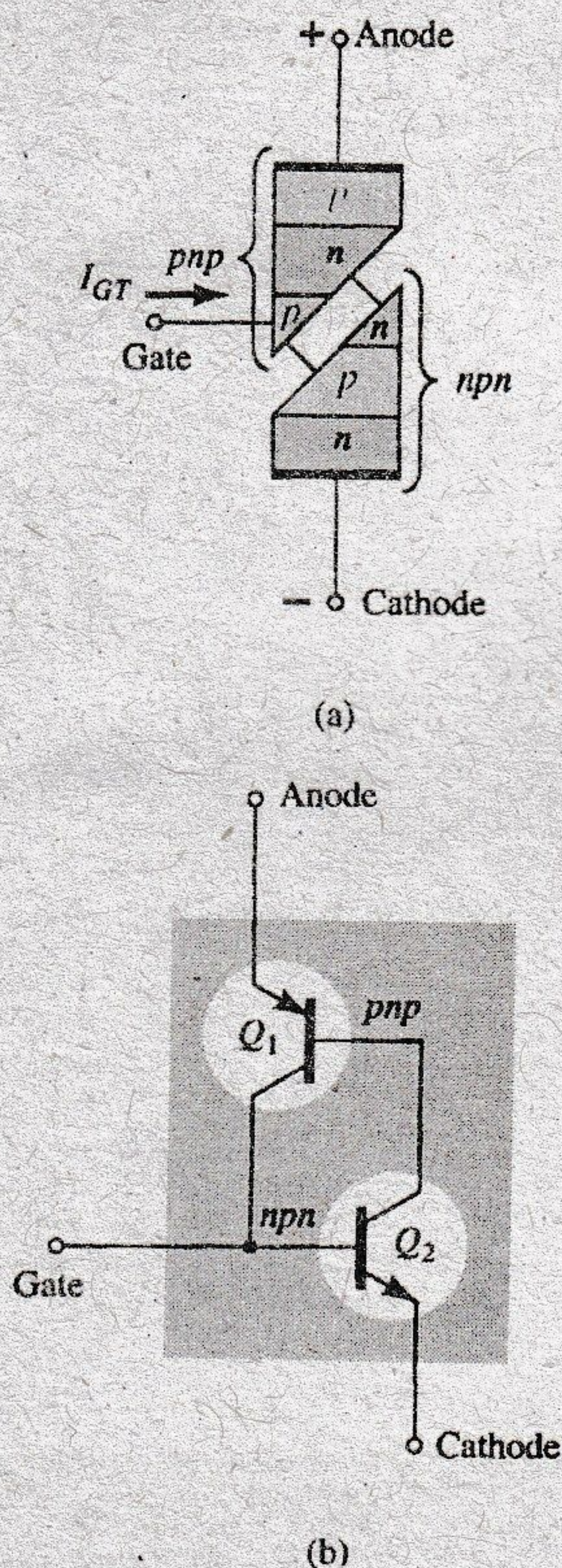
Note that one transistor for Fig. 17.2 is an *nnp* device, whereas the other is a *pnp* transistor. For discussion purposes, the signal shown in Fig. 17.3a will be applied to the gate of the circuit of Fig. 17.2b. During the interval  $0 \rightarrow t_1$ ,  $V_{gate} = 0 \text{ V}$ , the circuit of Fig. 17.2b will appear as shown in Fig. 17.3b ( $V_{gate} = 0 \text{ V}$  is equivalent to the gate terminal being grounded as shown in the figure). For  $V_{BE2} = V_{gate} = 0 \text{ V}$ , the base current  $I_{B2} = 0$ , and  $I_{C2}$  will be approximately  $I_{CO}$ . The base current of  $Q_1$ ,  $I_{B1} = I_{C2} = I_{CO}$ , is too small to turn  $Q_1$  on. Both transistors are therefore in the "off" state, resulting in a high impedance between the collector and the emitter of each transistor and the open-circuit representation for the controlled rectifier as shown in Fig. 17.3c.

At  $t = t_1$ , a pulse of  $V_G$  volts will appear at the SCR gate. The circuit conditions established with this input are shown in Fig. 17.4a. The potential  $V_G$  was chosen sufficiently large to turn  $Q_2$  on ( $V_{BE2} = V_G$ ). The collector current of  $Q_2$  will then rise to a value sufficiently large to turn  $Q_1$  on ( $I_{B1} = I_{C2}$ ). As  $Q_1$  turns on,  $I_{C1}$  will increase, resulting in a corresponding increase in  $I_{B2}$ . The increase in base current for  $Q_2$  will result in a further increase in  $I_{C2}$ . The net result is a regenerative increase in the collector current of each transistor. The resulting anode-to-cathode resistance ( $R_{SCR} = V/I_A$ ) is then small because  $I_A$  is large, resulting in the short-circuit representation for the SCR as indicated in Fig. 17.4b. The regenerative action described above results in SCRs having typical turn-on times of  $0.1 \mu\text{s}$  to  $1 \mu\text{s}$ . However, high-power devices in the range  $100 \text{ A}$  to  $400 \text{ A}$  may have  $10\text{-}25\text{-}\mu\text{s}$  turn-on times.

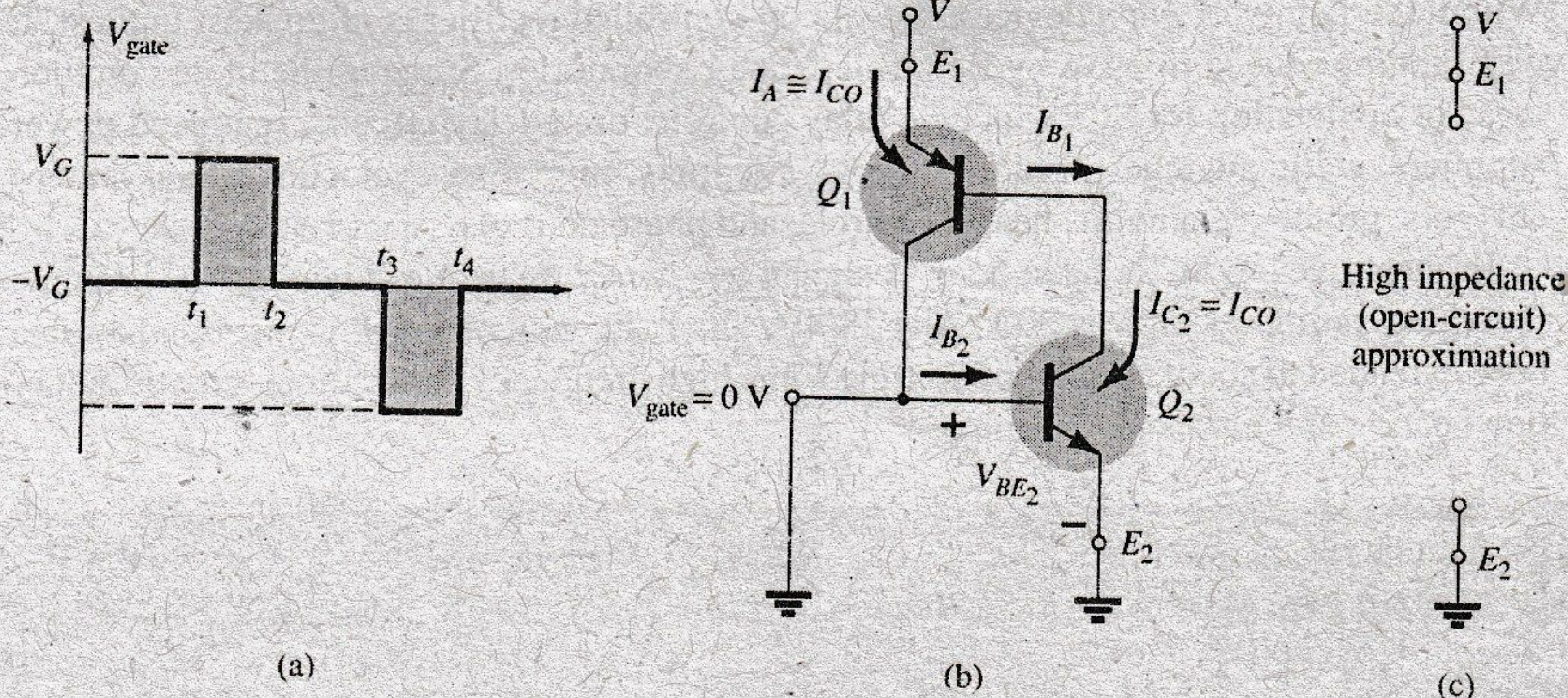
In addition to gate triggering, SCRs can also be turned on by significantly raising the temperature of the device or raising the anode-to-cathode voltage to the breakover value shown on the characteristics of Fig. 17.7.



**FIG. 17.1**  
(a) SCR symbol; (b) basic construction.



**FIG. 17.2**  
SCR two-transistor equivalent circuit.



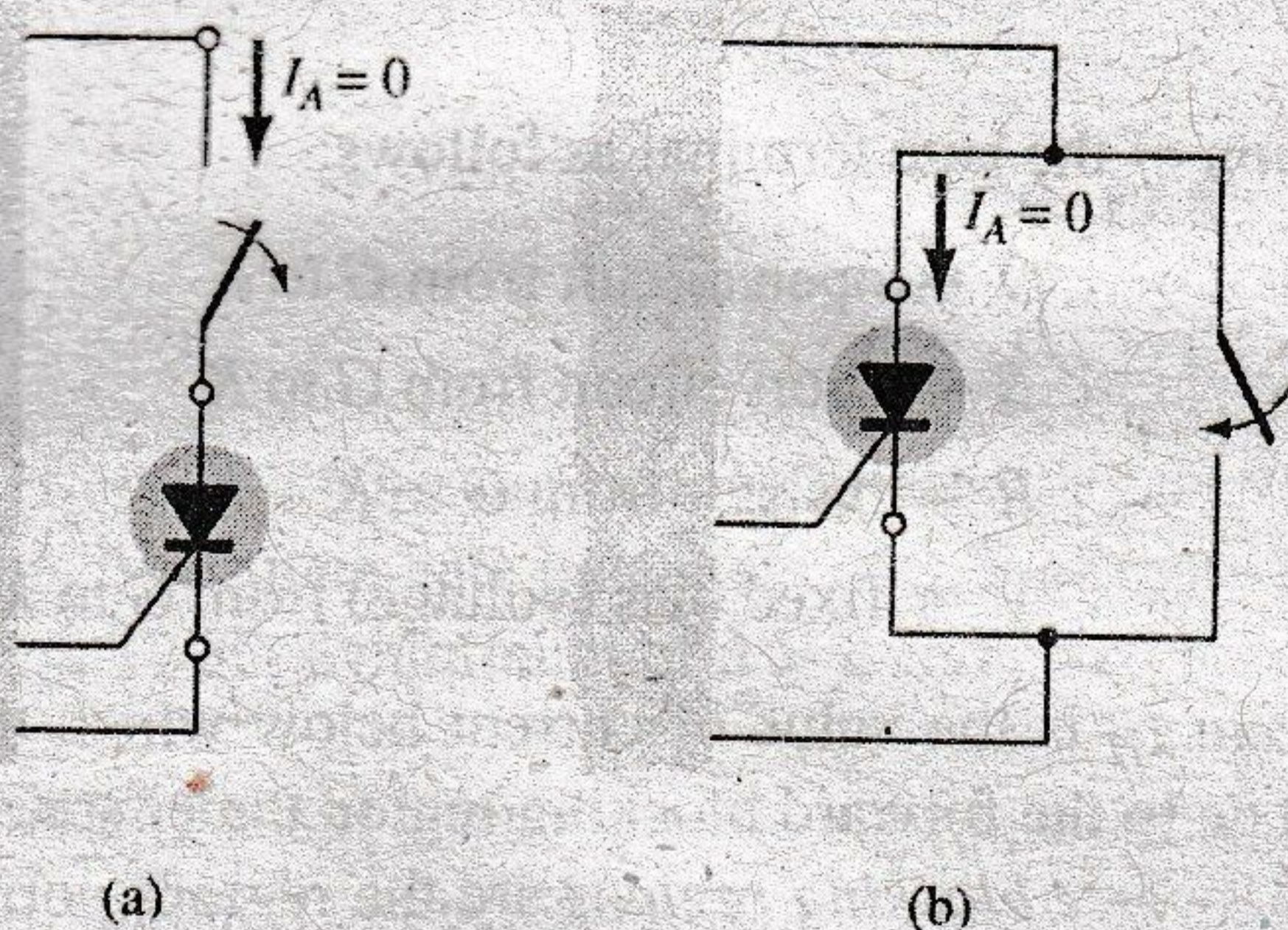
**FIG. 17.3**  
"Off" state of the SCR.

The next question of concern is: How long is the turn-off time and how is turn-off accomplished? An SCR *cannot* be turned off by simply removing the gate signal, and only a special few can be turned off by applying a negative pulse to the gate terminal as shown in Fig. 17.3a at  $t = t_3$ .

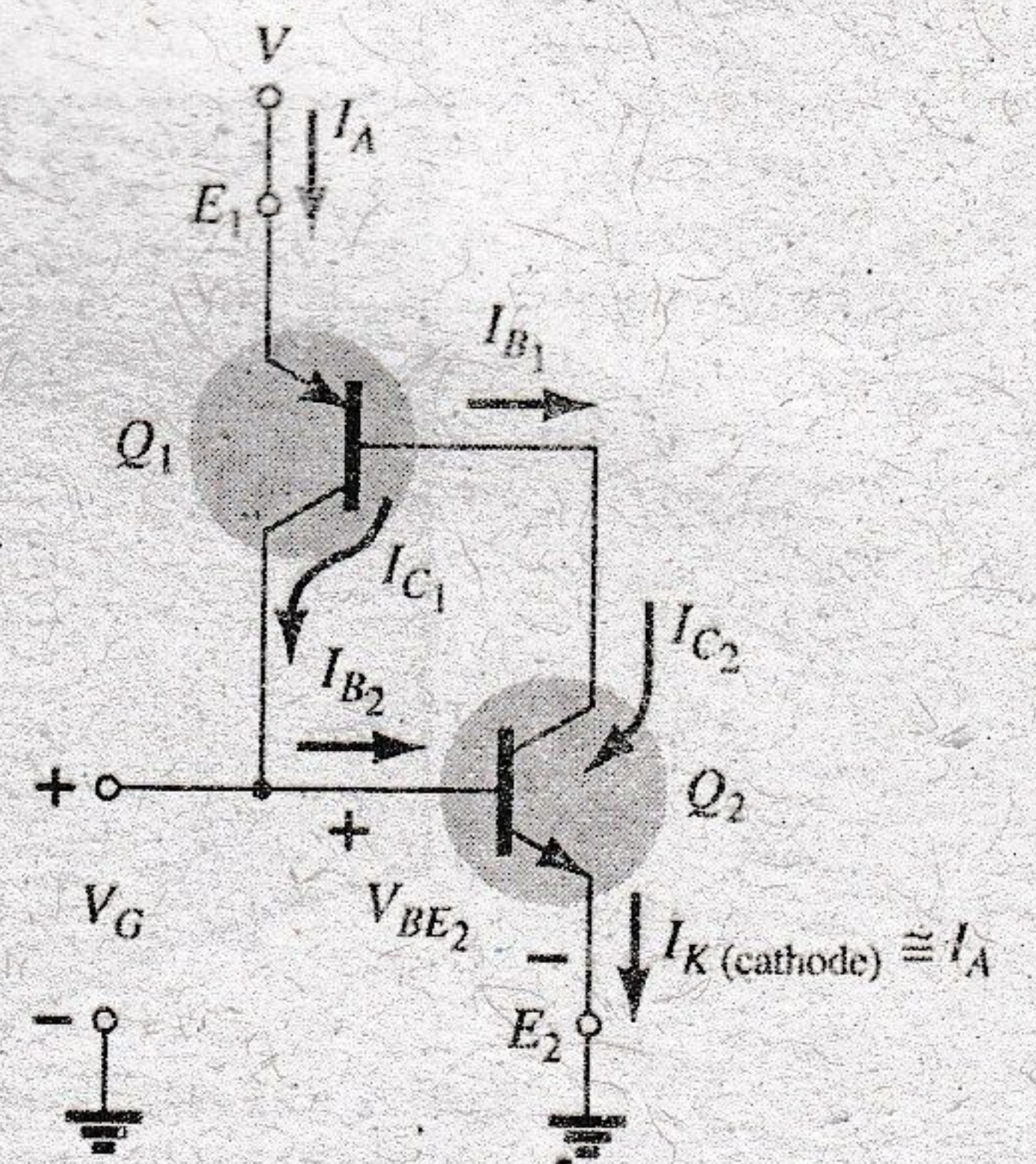
**The two general methods for turning off an SCR are categorized as anode current interruption and forced commutation.**

The two possibilities for current interruption are shown in Fig. 17.5. In Fig. 17.5a,  $I_A$  is zero when the switch is opened (series interruption), whereas in Fig. 17.5b, the same condition is established when the switch is closed (shunt interruption).

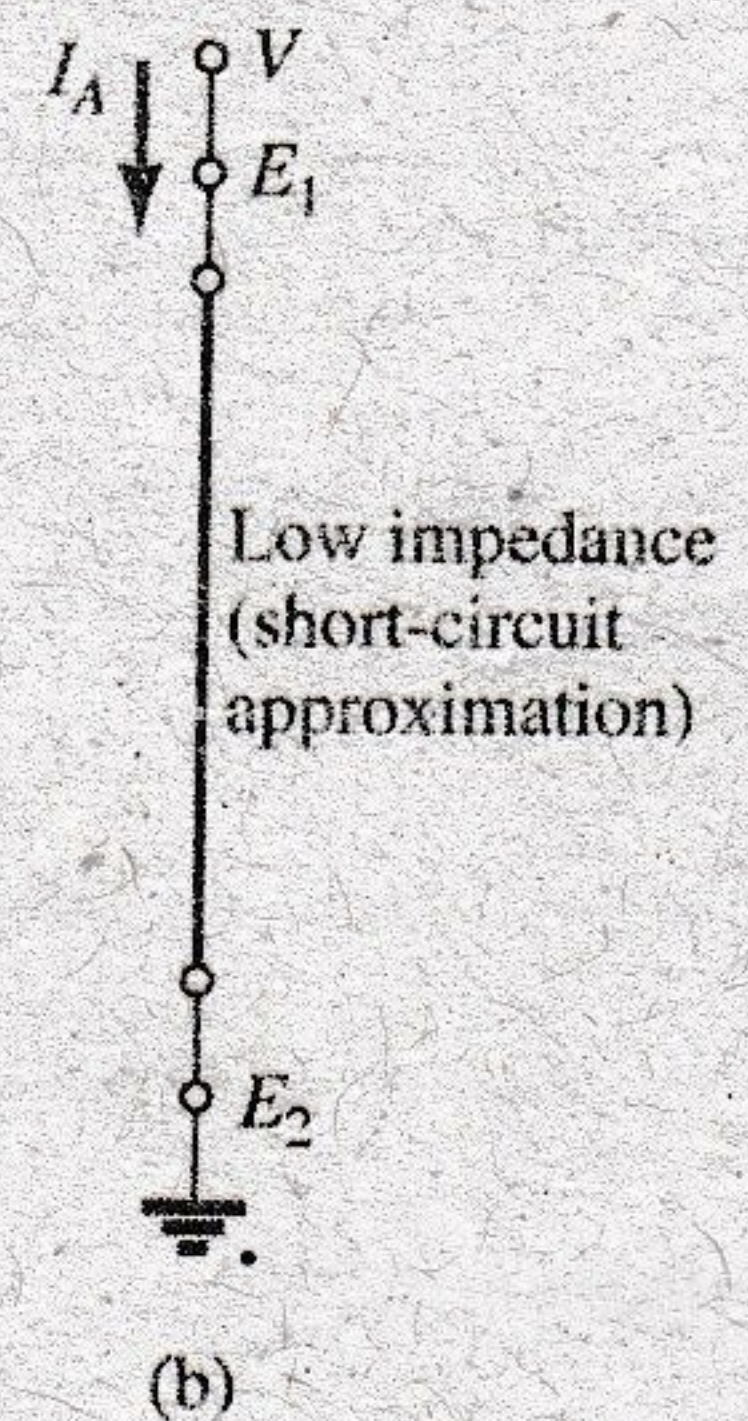
Forced commutation is the "forcing" of current through the SCR in the direction opposite to forward conduction. There is a wide variety of circuits for performing this function, a number of which can be found in the manuals of major manufacturers in this area. One of the more basic types is shown in Fig. 17.6. As indicated in the figure, the turn-off circuit consists of an *npn* transistor, a dc battery  $V_B$ , and a pulse generator. During SCR conduction, the transistor is in the "off" state, that is,  $I_B = 0$ , and the collector-to-emitter impedance is very high (for all practical purposes an open circuit). This high impedance will isolate the turn-off circuitry from affecting the operation of the SCR. For turn-off conditions, a positive pulse is applied to the base of the transistor, turning it heavily on, resulting in a very low impedance from collector to emitter (short-circuit representation). The battery potential will then appear directly across the SCR as shown in Fig. 17.6b, forcing current through it in the reverse direction for turn-off. Turn-off times of SCRs are typically  $5 \mu s$  to  $30 \mu s$ .



**FIG. 17.5**  
Anode current interruption.

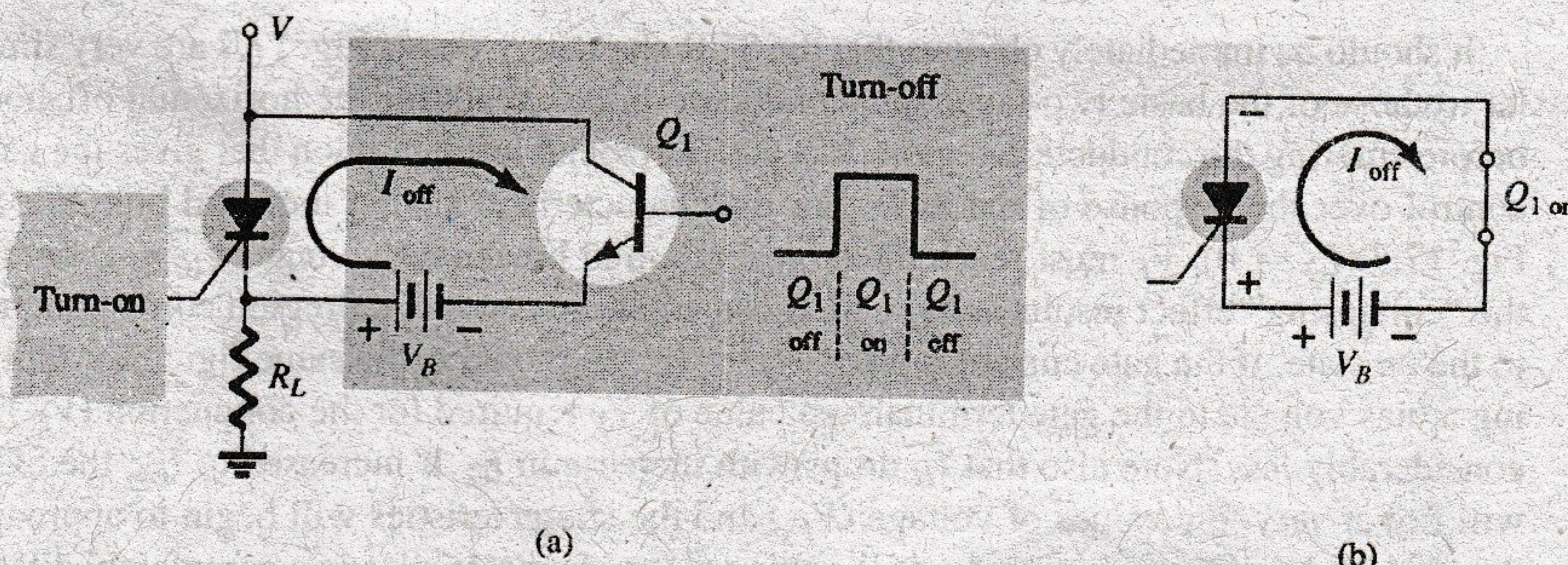


(a)



(b)

**FIG. 17.4**  
"On" state of the SCR.



(a)

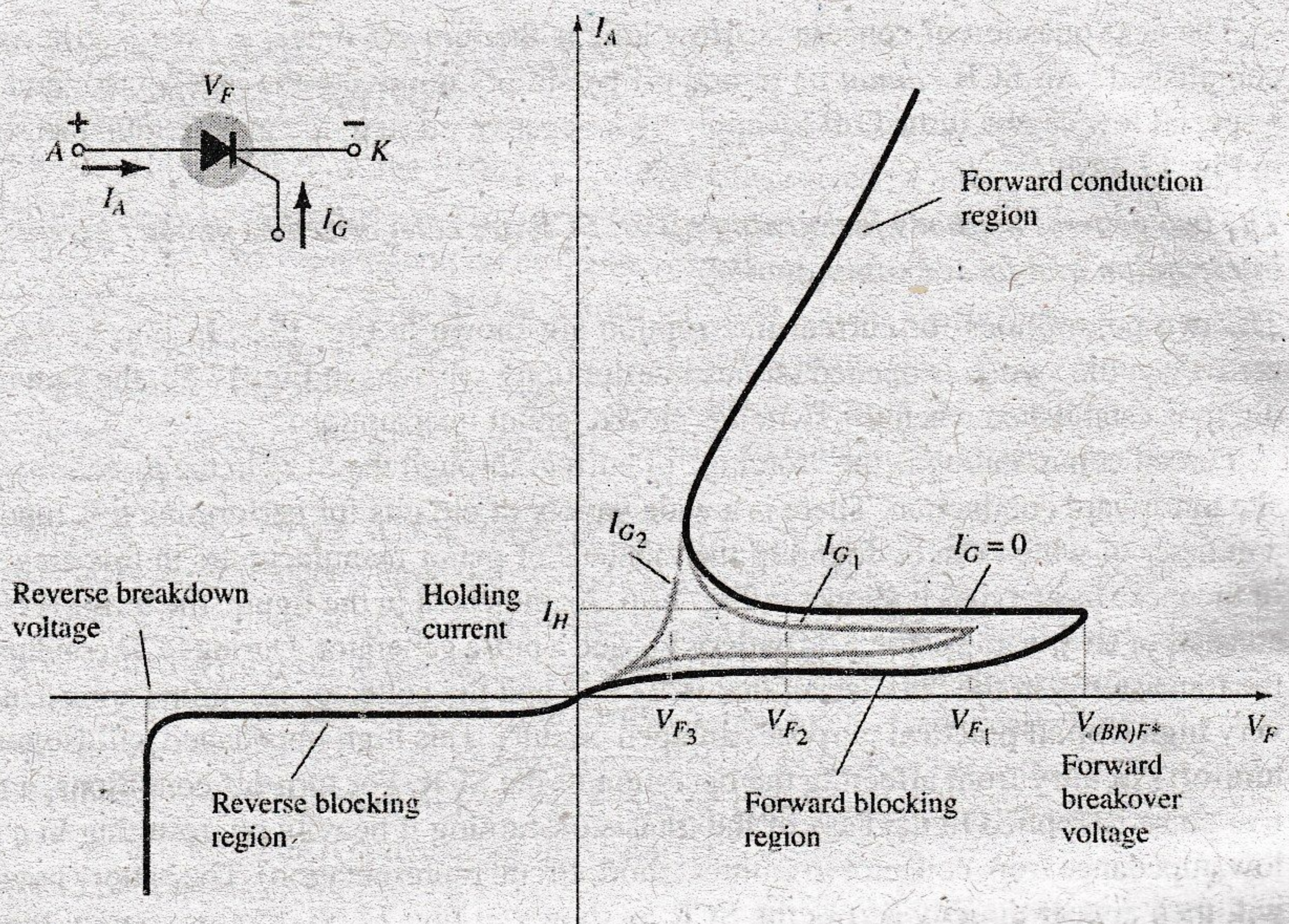
(b)

**FIG. 17.6**  
Forced-commutation technique.

## 17.4 SCR CHARACTERISTICS AND RATINGS

The characteristics of an SCR are provided in Fig. 17.7 for various values of gate current. The currents and voltages of usual interest are indicated on the characteristic. A brief description of each follows.

1. *Forward breakover voltage*  $V_{(BR)F^*}$  is the voltage above which the SCR enters the conduction region. The asterisk (\*) denotes the letter to be added, which is dependent



**FIG. 17.7**  
SCR characteristics.

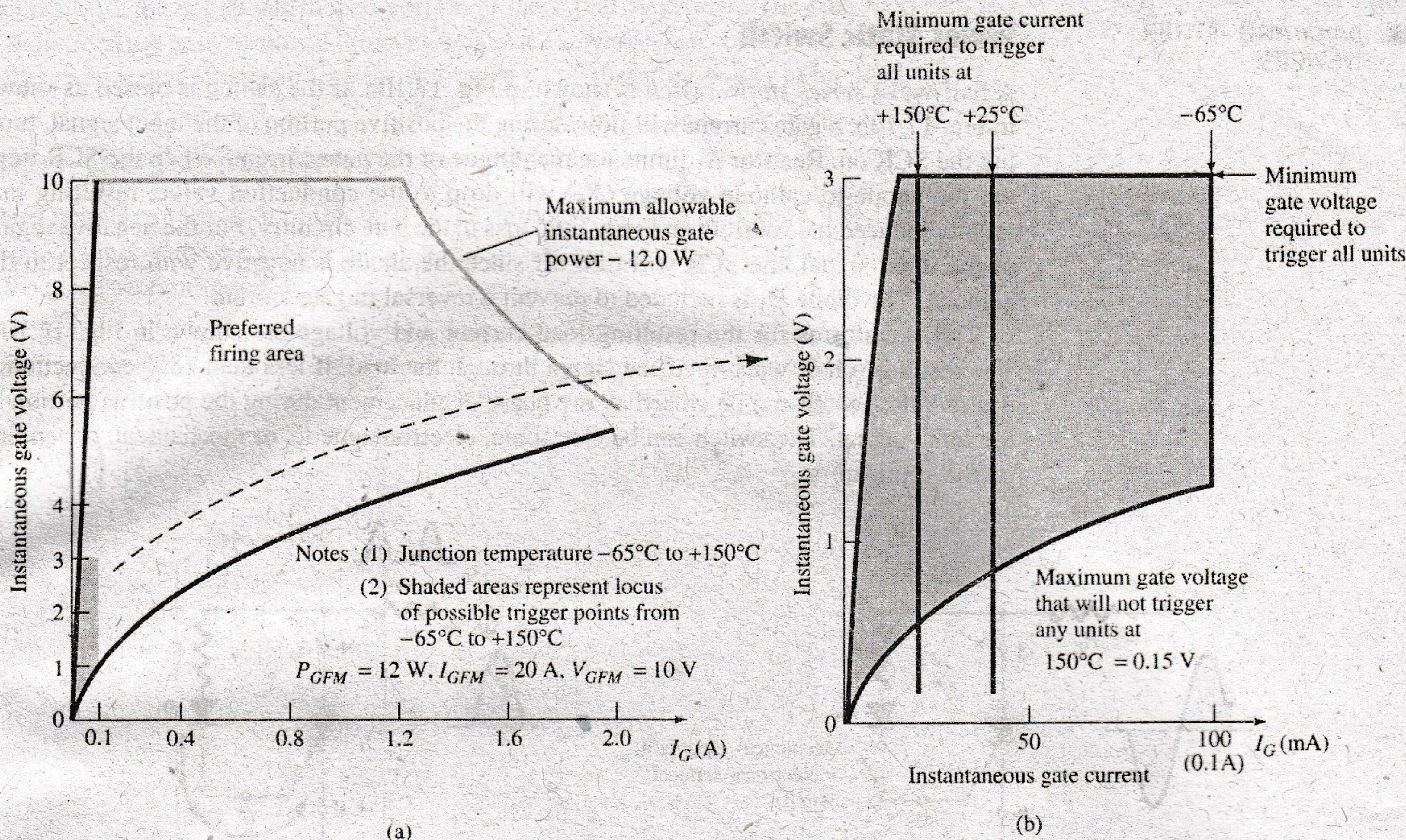
on the condition of the gate terminal as follows:

- $O$  = open circuit from  $G$  to  $K$
- $S$  = short circuit from  $G$  to  $K$
- $R$  = resistor from  $G$  to  $K$
- $V$  = fixed bias (voltage) from  $G$  to  $K$

2. *Holding current*  $I_H$  is the value of current below which the SCR switches from the conduction state to the forward blocking region under stated conditions.
3. *Forward and reverse blocking regions* are the regions corresponding to the open-circuit condition for the controlled rectifier that *block* the flow of charge (current) from anode to cathode.
4. *Reverse breakdown voltage* is equivalent to the Zener or avalanche region of the fundamental two-layer semiconductor diode.

It should be immediately obvious that the SCR characteristics of Fig. 17.7 are very similar to those of the basic two-layer semiconductor diode except for the horizontal offshoot before entering the conduction region. It is this horizontal jutting region that gives the gate control over the response of the SCR. For the characteristic having the solid blue line in Fig. 17.7 ( $I_G = 0$ ),  $V_F$  must reach the largest required breakover voltage ( $V_{(BR)F^*}$ ) before the "collapsing" effect results and the SCR can enter the conduction region corresponding to the *on* state. If the gate current is increased to  $I_{G1}$ , as shown in the same figure by applying a bias voltage to the gate terminal, the value of  $V_F$  required for the conduction ( $V_{F1}$ ) is considerably less. Note also that  $I_H$  drops with increase in  $I_G$ . If increased to  $I_{G2}$ , the SCR will fire at very low values of voltage ( $V_{F3}$ ) and the characteristics will begin to approach those of the basic  $p-n$  junction diode. Looking at the characteristics in a completely different sense; for a particular  $V_F$  voltage, say  $V_{F2}$  (Fig. 17.7), we see that if the gate current is increased from  $I_G = 0$  to  $I_{G1}$  or more, the SCR will fire.

The gate characteristics are provided in Fig. 17.8. The characteristics of Fig. 17.8b are an expanded version of the shaded region of Fig. 17.8a. In Fig. 17.8a, the three gate ratings of greatest interest,  $P_{GFM}$ ,  $I_{GFM}$ , and  $V_{GFM}$ , are indicated. Each is included on the characteristics in the same manner employed for the transistor. Except for portions of the shaded region, any combination of gate current and voltage that falls within this region will fire any SCR in the series of components for which these characteristics are provided. Temperature will determine which sections of the shaded region must be avoided. At  $-65^\circ\text{C}$  the minimum current that will trigger the series of SCRs is 100 mA, whereas at  $+150^\circ\text{C}$  only

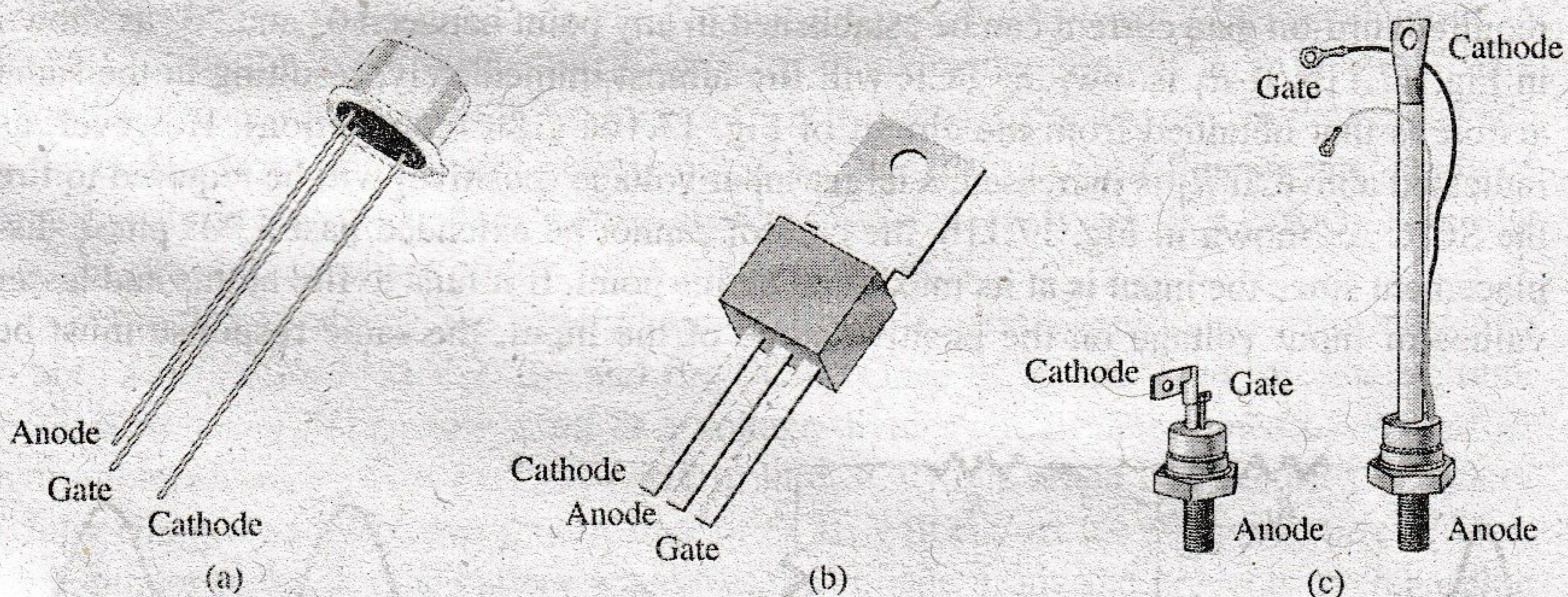


**FIG. 17.8**  
SCR gate characteristics (GE series C38).

20 mA is required. The effect of temperature on the minimum gate voltage is usually not indicated on curves of this type since gate potentials of 3 V or more are usually obtained easily. As indicated on Fig. 17.8b, a minimum of 3 V is indicated for all units for the temperature range of interest.

Other parameters usually included on the specification sheet of an SCR are the turn-on time  $t_{on}$ , turn-off time  $t_{off}$ , junction temperature  $T_J$ , and case temperature  $T_C$ , all of which by now should be to some extent self-explanatory.

The case construction and terminal identification of SCRs vary with the application. The case-construction techniques and the terminal identification of a number of SCRs are provided in Fig. 17.9.



**FIG. 17.9**  
SCR case construction and terminal identification.

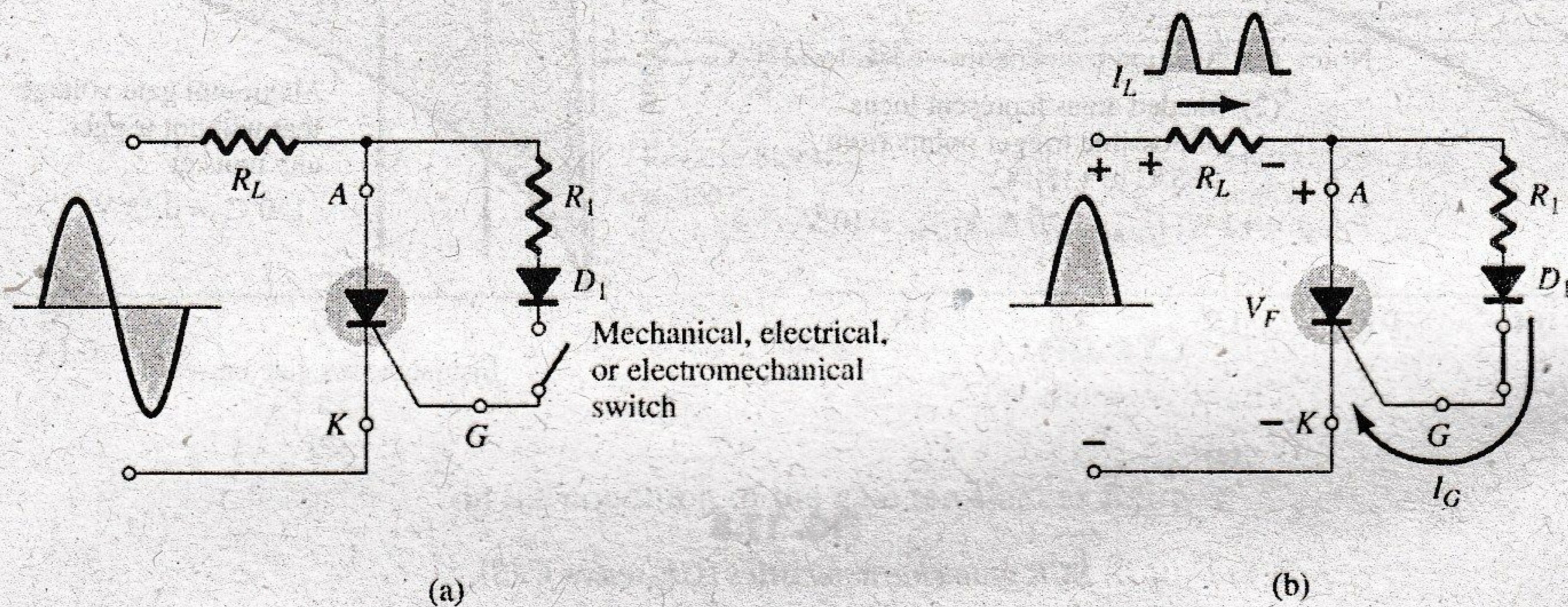
## 17.5 SCR APPLICATIONS

Some of the possible applications for the SCR are listed in the introduction to the SCR (Section 17.2). In this section, we consider five: a static switch, a phase-control system, a battery charger, a temperature controller, and a single-source emergency-lighting system.

### Series Static Switch

A half-wave *series static switch* is shown in Fig. 17.10a. If the switch is closed as shown in Fig. 17.10b, a gate current will flow during the positive portion of the input signal, turning the SCR on. Resistor  $R_1$  limits the magnitude of the gate current. When the SCR turns on, the anode-to-cathode voltage ( $V_F$ ) will drop to the conduction value, resulting in a greatly reduced gate current and very little loss in the gate circuitry. For the negative region of the input signal, the SCR will turn off since the anode is negative with respect to the cathode. The diode  $D_1$  is included to prevent a reversal in gate current.

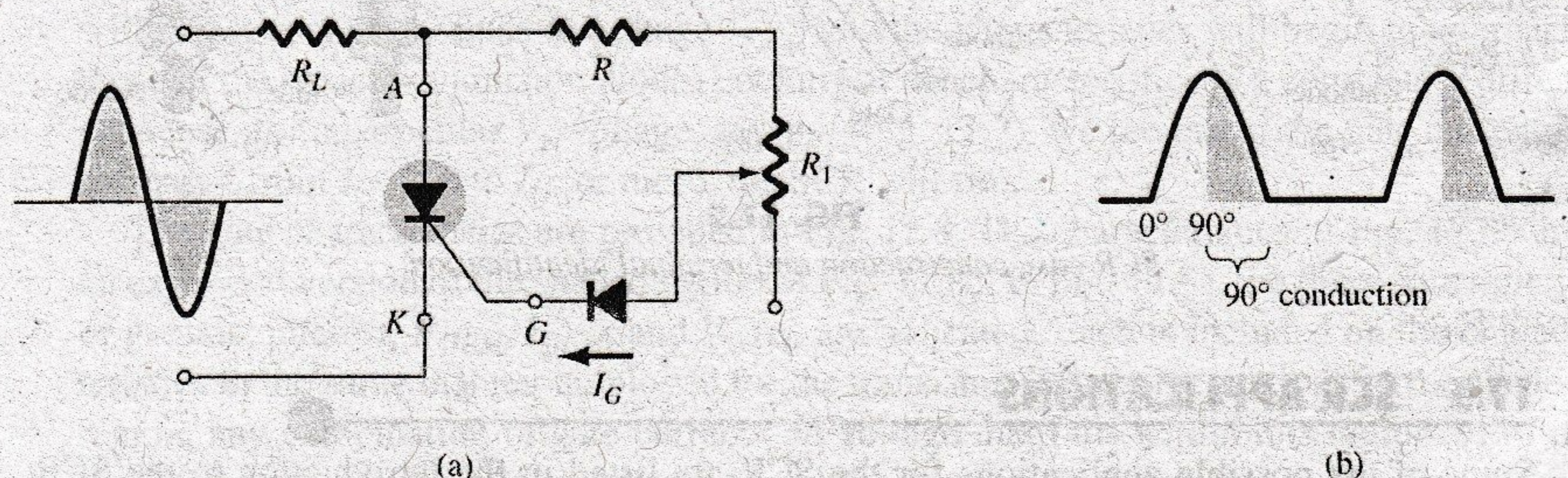
The waveforms for the resulting load current and voltage are shown in Fig. 17.10b. The result is a half-wave-rectified signal through the load. If less than  $180^\circ$  conduction is desired, the switch can be closed at any phase displacement during the positive portion of the input signal. The switch can be electronic, electromagnetic, or mechanical, depending on the application.



**FIG. 17.10**  
*Half-wave series static switch.*

### Variable-Resistance Phase Control

A circuit capable of establishing a conduction angle between  $90^\circ$  and  $180^\circ$  is shown in Fig. 17.11a. The circuit is similar to that of Fig. 17.10a except for the addition of a variable resistor and the elimination of the switch. The combination of the resistors  $R$  and  $R_1$  will limit the gate current during the positive portion of the input signal. If  $R_1$  is set to its maximum value, the gate current may never reach turn-on magnitude. As  $R_1$  is decreased from the maximum, the gate current will increase from the same input voltage. In this way, the required turn-on gate current can be established in any point between  $0^\circ$  and  $90^\circ$  as shown in Fig. 17.11b. If  $R_1$  is low, the SCR will fire almost immediately, resulting in the same action as that obtained from the circuit of Fig. 17.10a ( $180^\circ$  conduction). However, as indicated above, if  $R_1$  is increased, a larger input voltage (positive) will be required to fire the SCR. As shown in Fig. 17.11b, the control cannot be extended past a  $90^\circ$  phase displacement since the input is at its maximum at this point. If it fails to fire at this and lesser values of input voltage on the positive slope of the input, the same response must be



**FIG. 17.11**  
*Half-wave variable-resistance phase control.*

expected from the negatively sloped portion of the signal waveform. The operation here is normally referred to in technical terms as *half-wave variable-resistance phase control*. It is an effective method of controlling the rms current and therefore power to the load.

### Battery-Charging Regulator

A third popular application of the SCR is in a *battery-charging regulator*. The fundamental components of the circuit are shown in Fig. 17.12. The control circuit has been blocked off for discussion purposes.

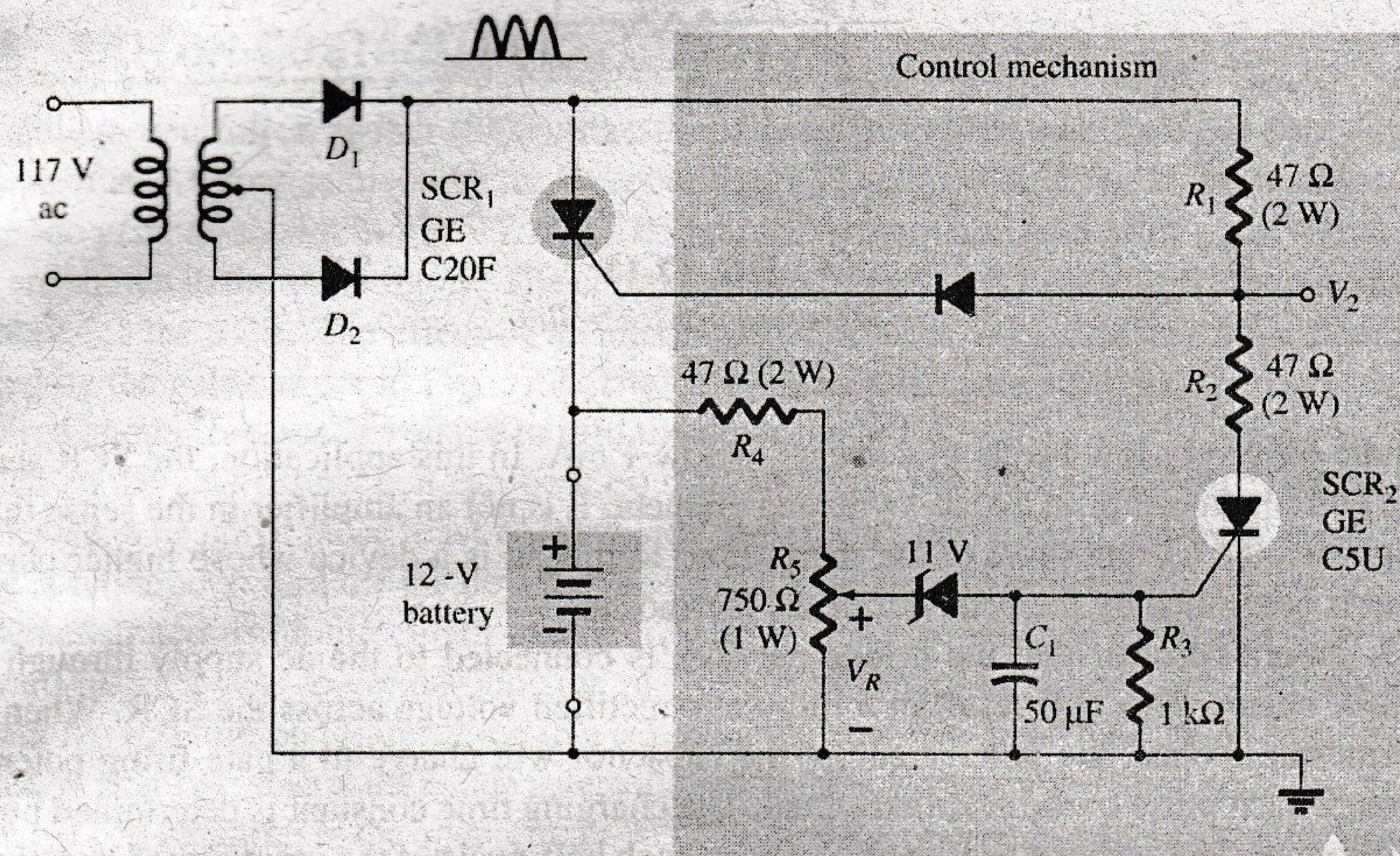


FIG. 17.12

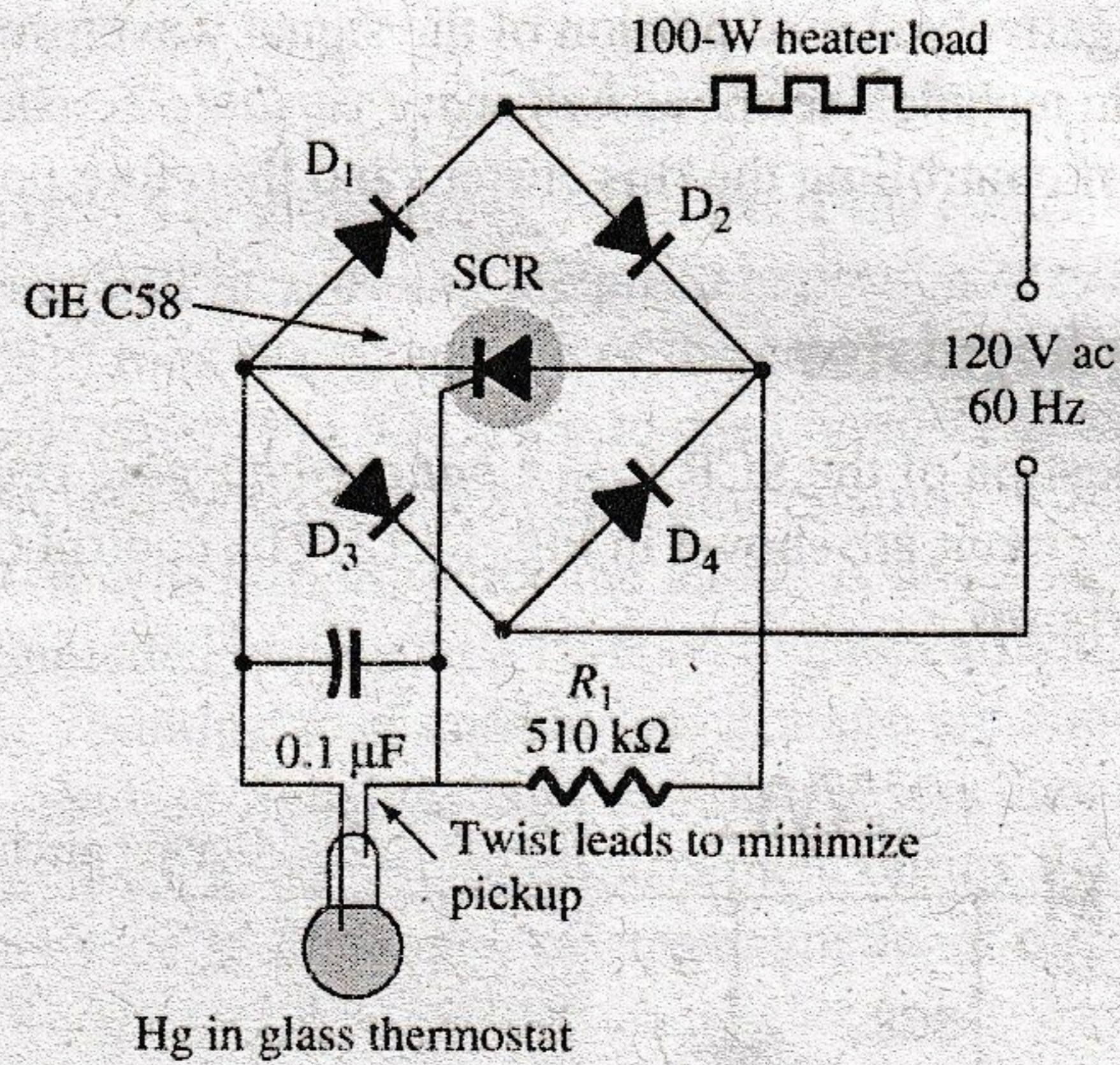
Battery-charging regulator.

As indicated in the figure,  $D_1$  and  $D_2$  establish a full-wave-rectified signal across  $SCR_1$  and the 12-V battery to be charged. At low battery voltages,  $SCR_2$  is in the "off" state for reasons to be explained shortly. With  $SCR_2$  open, the  $SCR_1$  controlling circuit is exactly the same as the series static switch control discussed earlier in this section. When the full-wave-rectified input is sufficiently large to produce the required turn-on gate current (controlled by  $R_1$ ),  $SCR_1$  will turn on and charging of the battery will commence. At the start of charging, the low battery voltage will result in a low voltage  $V_R$  as determined by the simple voltage-divider circuit. Voltage  $V_R$  is in turn too small to cause 11.0-V Zener conduction. In the "off" state, the Zener is effectively an open circuit, maintaining  $SCR_2$  in the "off" state since the gate current is zero. The capacitor  $C_1$  is included to prevent any voltage transients in the circuit from accidentally turning on  $SCR_2$ . Recall from your fundamental study of circuit analysis that the voltage cannot change instantaneously across a capacitor. In this way,  $C_1$  prevents transient effects from affecting the SCR.

As charging continues, the battery voltage rises to a point where  $V_R$  is sufficiently high to both turn on the 11.0-V Zener and fire  $SCR_2$ . Once  $SCR_2$  has fired, the short-circuit representation for  $SCR_2$  will result in a voltage-divider circuit determined by  $R_1$  and  $R_2$  that will maintain  $V_2$  at a level too small to turn  $SCR_1$  on. When this occurs, the battery is fully charged and the open-circuit state of  $SCR_1$  will cut off the charging current. Thus the regulator recharges the battery whenever the voltage drops and prevents overcharging when it is fully charged.

### Temperature Controller

The schematic diagram of a 100-W heater control using an SCR appears in Fig. 17.13. It is designed such that the 100-W heater will turn on and off as determined by thermostats. Mercury-in-glass thermostats are very sensitive to temperature change. In fact, they can sense changes as small as  $0.1^\circ\text{C}$ . They are limited in application, however, in that they can



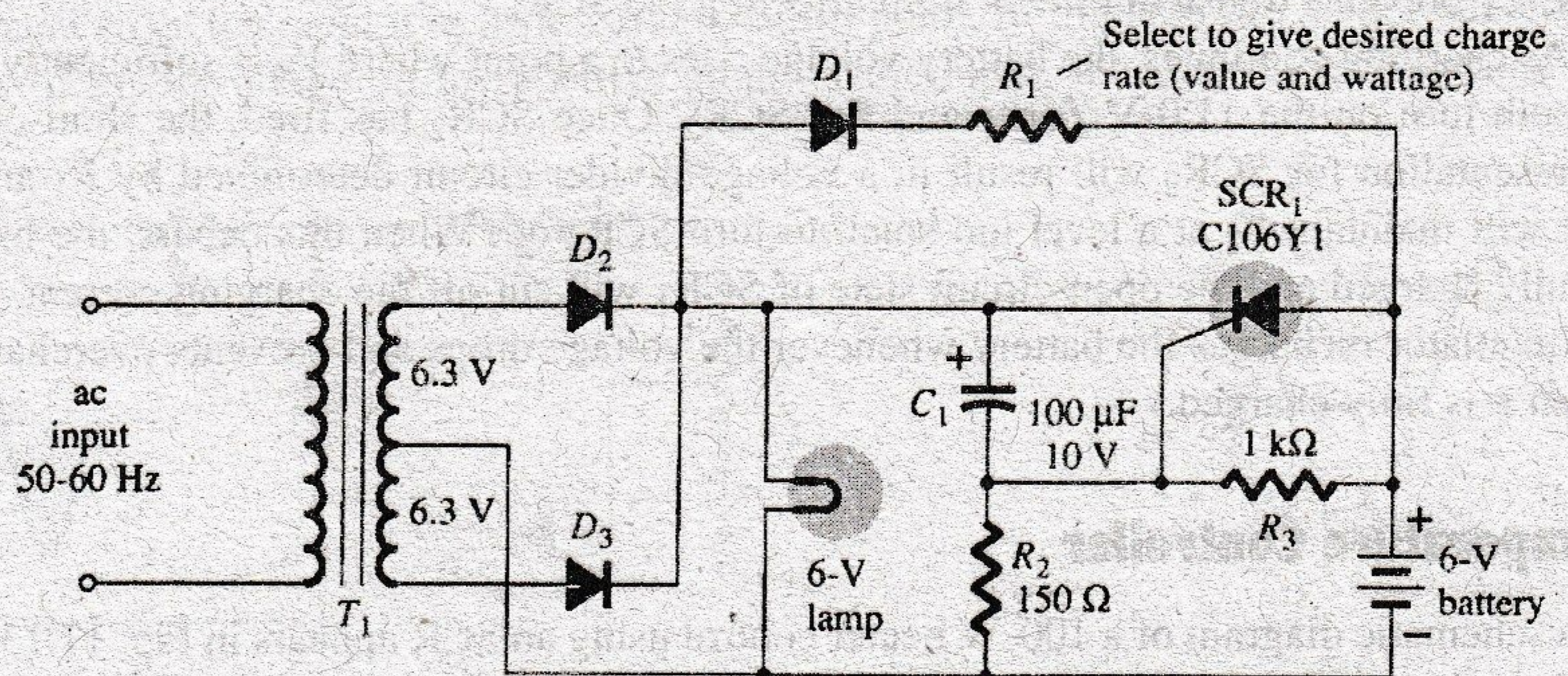
**FIG. 17.13**  
Temperature controller.

handle only very low levels of current—below 1 mA. In this application, the SCR serves as a current amplifier in a load-switching element. It is not an amplifier in the sense that it magnifies the current level of the thermostat. Rather, it is a device whose higher current level is controlled by the behavior of the thermostat.

It should be clear that the bridge network is connected to the ac supply through the 100-W heater. This will result in a full-wave-rectified voltage across the SCR. When the thermostat is open, the voltage across the capacitor will charge to a gate-firing potential through each pulse of the rectified signal. The charging time constant is determined by the  $RC$  product. This will trigger the SCR during each half-cycle of the input signal, permitting a flow of charge (current) to the heater. As the temperature rises, the conductive thermostat will short-circuit the capacitor, eliminating the possibility of the capacitor charging to the firing potential and triggering the SCR. The 510-k $\Omega$  resistor will then contribute to maintaining a very low current (less than 250  $\mu$ A) through the thermostat.

### Emergency-Lighting System

The last application for the SCR to be described is shown in Fig. 17.14. It is a single-source emergency-lighting system that will maintain the charge on a 6-V battery to ensure its availability and also provide dc energy to a bulb if there is a power shortage. A full-wave-rectified signal will appear across the 6-V lamp due to diodes  $D_2$  and  $D_1$ . The capacitor  $C_1$  will charge to a voltage slightly less than a difference between the peak value of the full-wave-rectified signal and the dc voltage across  $R_2$  established by the 6-V battery. In any event, the cathode of SCR<sub>1</sub> is higher than the anode, and the gate-to-cathode voltage is negative, ensuring that the SCR is nonconducting. The battery is charged



**FIG. 17.14**  
Single-source emergency-lighting system.



through  $R_1$  and  $D_1$  at a rate determined by  $R_1$ . Charging will only take place when the anode of  $D_1$  is more positive than its cathode. The dc level of the full-wave-rectified signal will ensure that the bulb is lit when the power is on. If the power should fail, the capacitor  $C_1$  will discharge through  $D_1$ ,  $R_1$ , and  $R_3$  until the cathode of  $SCR_1$  is less positive than the anode. At the same time, the junction of  $R_2$  and  $R_3$  will become positive and establish sufficient gate-to-cathode voltage to trigger the SCR. Once fired, the 6-V battery discharges through the  $SCR_1$  and energizes the lamp and maintains its illumination. Once power is restored, the capacitor  $C_1$  recharges and reestablishes the nonconducting state of  $SCR_1$  as described above.

## 17.6 SILICON-CONTROLLED SWITCH

The silicon-controlled switch (SCS), like the silicon-controlled rectifier, is a four-layer  $pnpn$  device. All four semiconductor layers of the SCS are available due to the addition of an anode gate, as shown in Fig. 17.15a. The graphic symbol and transistor equivalent circuit are shown in the same figure. The characteristics of the device are essentially the same as those for the SCR. The effect of an anode gate current is very similar to that demonstrated by the gate current in Fig. 17.7: The higher the anode gate current, the lower is the required anode-to-cathode voltage to turn the device on.

The anode gate connection can be used to turn the device either on or off. To turn on the device, a negative pulse must be applied to the anode gate terminal, whereas a positive pulse is required to turn off the device. The need for the type of pulse indicated above can be demonstrated using the circuit of Fig. 17.15c. A negative pulse at the anode gate will forward-bias the base-to-emitter junction of  $Q_1$ , turning it on. The resulting heavy collector current  $I_{C1}$  will turn on  $Q_2$ , resulting in a regenerative action and the "on" state for the SCS device. A positive pulse at the anode gate will reverse-bias the base-to-emitter junction of  $Q_1$ , turning it off, resulting in the open-circuit "off" state of the device. In general, the triggering (turn-on) anode gate current is larger in magnitude than the required cathode gate current. For one representative SCS device, the triggering anode gate current is 1.5 mA, whereas the required cathode gate current is 1  $\mu$ A. The required turn-on gate current at either terminal is affected by many factors, including the operating temperature, the anode-to-cathode voltage, the load placement, and the type of cathode, gate-to-cathode, and anode gate-to-anode connection (short-circuit, open-circuit, bias, load, etc.). Tables, graphs, and curves are normally available for each device to provide the type of information indicated above.

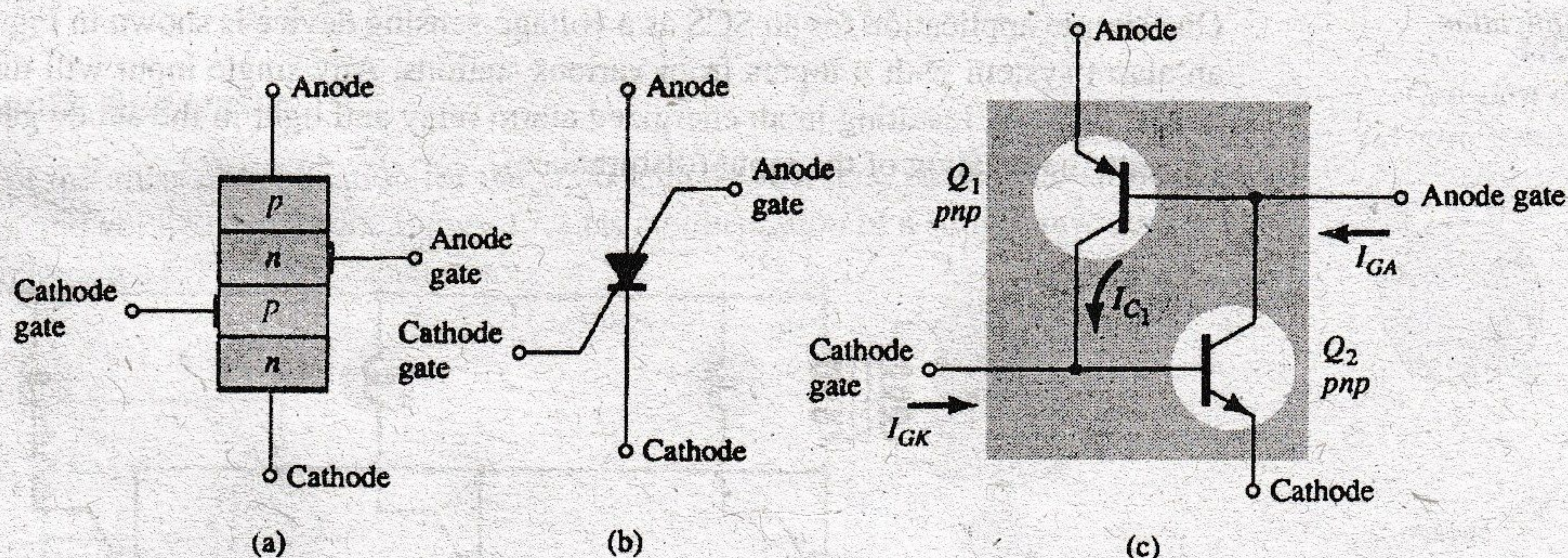
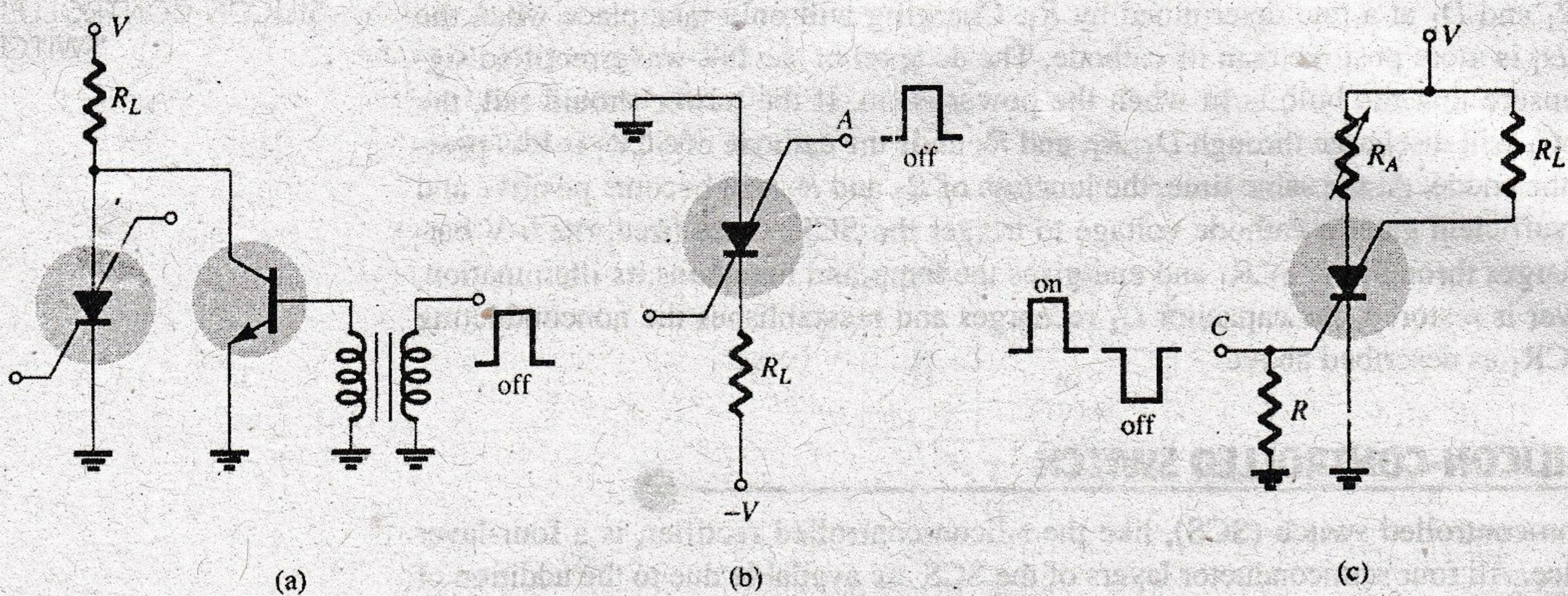


FIG. 17.15

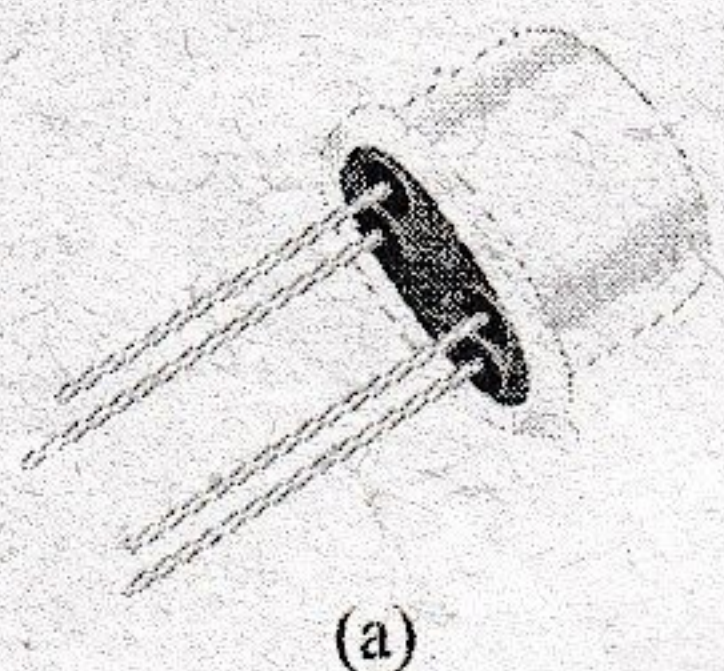
Silicon-controlled switch (SCS): (a) basic construction; (b) graphic symbol; (c) equivalent transistor circuit.

Three of the more fundamental types of turn-off circuits for the SCS are shown in Fig. 17.16. When a pulse is applied to the transformer of Fig. 17.16a, the transistor conducts heavily, resulting in a low-impedance ( $\approx$  short-circuit) characteristic between collector and emitter. This low-impedance branch diverts anode current away from the SCS, dropping it below the holding value and consequently turning it off. Similarly, the positive pulse at the anode gate of Fig. 17.16b will turn the SCS off by the mechanism described earlier in this section. The circuit of Fig. 17.16c can be turned either off or on by a pulse of the proper magnitude

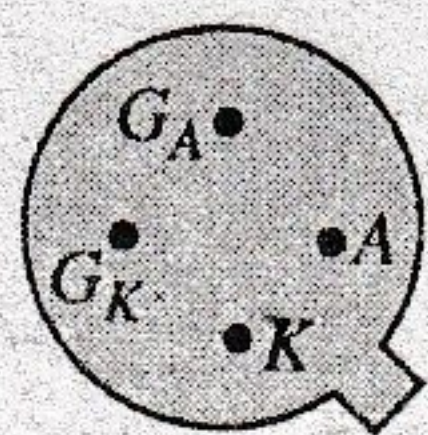


**FIG. 17.16**

*SCS turn-off techniques.*



(a)



(b)

**FIG. 17.17**

*Silicon-controlled switch (SCS):*  
(a) device; (b) terminal identification.

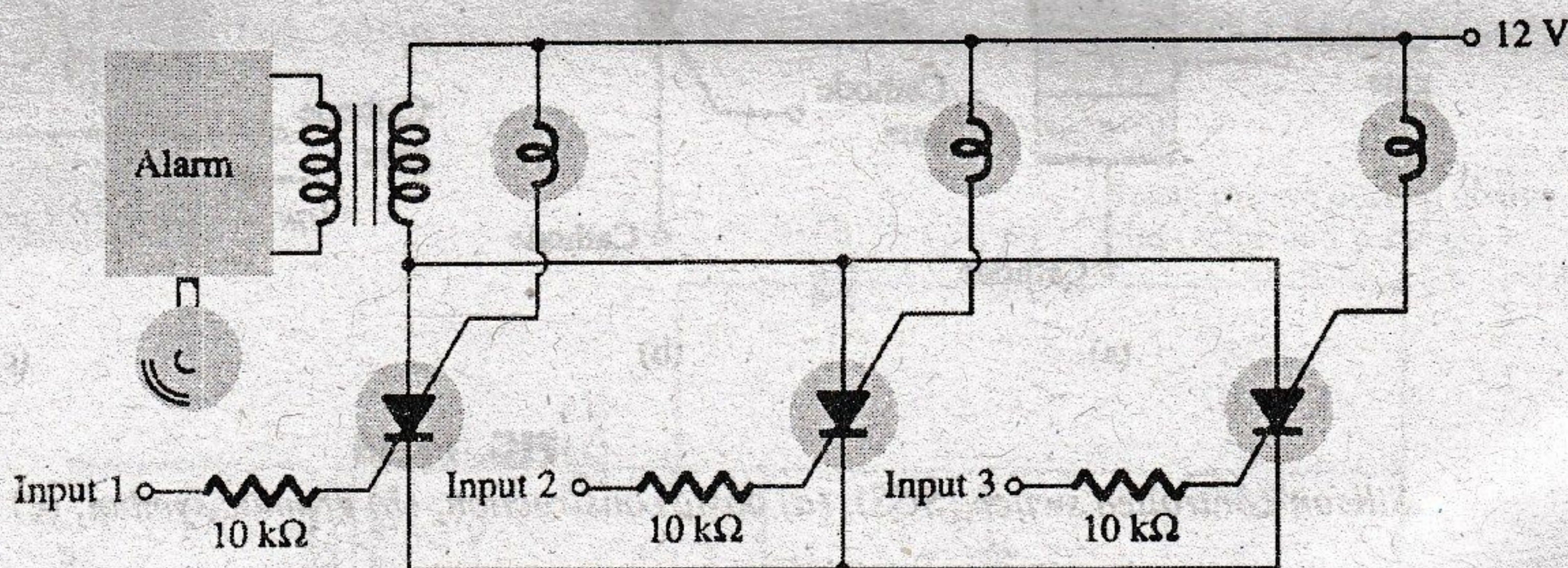
at the cathode gate. The turn-off characteristic is possible only if the correct value of  $R_A$  is employed. It will control the amount of regenerative feedback, the magnitude of which is critical for this type of operation. Note the variety of positions in which the load resistor  $R_L$  can be placed. There are a number of other possibilities, which can be found in any comprehensive semiconductor handbook or manual.

An advantage of the SCS over a corresponding SCR is the reduced turn-off time, typically within the range  $1 \mu\text{s}$  to  $10 \mu\text{s}$  for the SCS and  $5 \mu\text{s}$  to  $30 \mu\text{s}$  for the SCR. Some of the remaining advantages of the SCS over an SCR include increased control and triggering sensitivity and a more predictable firing situation. At present, however, the SCS is limited to low power, current, and voltage ratings. Typical maximum anode currents range from 100 mA to 300 mA with dissipation (power) ratings of 100 mW to 500 mW.

The terminal identification of an SCS is shown in Fig. 17.17 with a packaged SCS.

### Voltage Sensor

Some of the more common areas of application include a wide variety of computer circuits (counters, registers, and timing circuits), pulse generators, voltage sensors, and oscillators. One simple application for an SCS as a voltage-sensing device is shown in Fig. 17.18. It is an alarm system with  $n$  inputs from various stations. Any single input will turn that particular SCS on, resulting in an energized alarm relay and light in the anode gate circuit to indicate the location of the input (disturbance).



**FIG. 17.18**

*SCS alarm circuit.*

### Alarm Circuit

One additional application of the SCS is in the alarm circuit of Fig. 17.19.  $R_S$  represents a temperature-, light-, or radiation-sensitive resistor, that is, an element whose resistance

will decrease with the application of any of the three energy sources listed above. The cathode gate potential is determined by the divider relationship established by  $R_S$  and the variable resistor. Note that the gate potential is at approximately 0 V if  $R_S$  equals the value set by the variable resistor since both resistors will have 12 V across them. However, if  $R_S$  decreases, the potential of the junction will increase until the SCS is forward-biased, causing the SCS to turn on and energize the alarm relay.

The 100-k $\Omega$  resistor is included to reduce the possibility of an accidental triggering of the device through a phenomenon known as the *rate effect*. It is caused by the stray capacitance levels between gates. A high-frequency transient can establish sufficient base current to turn the SCS on accidentally. The device is reset by pressing the reset button, which opens the conduction path of the SCS and reduces the anode current to zero.

### 17.7 GATE TURN-OFF SWITCH

The gate turn-off switch (GTO) is the third *pnpn* device to be introduced in this chapter. Like the SCR, however, it has only three external terminals, as indicated in Fig. 17.20a. Its graphical symbol is shown in Fig. 17.20b. Although the graphical symbol is different from that of either the SCR or the SCS, the transistor equivalent is exactly the same and the characteristics are similar.

The most obvious advantage of the GTO over the SCR or SCS is the fact that it can be turned on *or* off by applying the proper pulse to the cathode gate (without the anode gate and associated circuitry required for the SCS). A consequence of this turn-off capability is an increase in the magnitude of the required gate current for triggering. For an SCR and GTO of similar maximum rms current ratings, the gate-triggering current of a particular SCR is 30  $\mu$ A, whereas the triggering current of the GTO is 20 mA. The turn-off current of a GTO is slightly larger than the required triggering current. The maximum rms current and dissipation ratings of GTOs manufactured today are limited to about 3 A and 20 W, respectively.

A second very important characteristic of the GTO is improved switching characteristics. The turn-on time is similar to that of the SCR (typically 1  $\mu$ s), but the turn-off time of about the *same* duration (1  $\mu$ s) is much smaller than the typical turn-off time of an SCR (5  $\mu$ s to 30  $\mu$ s). The fact that the turn-off time is similar to the turn-on time rather than considerably larger permits the use of this device in high-speed applications.

A typical GTO and its terminal identification are shown in Fig. 17.21. The GTO gate input characteristics and turn-off circuits can be found in a comprehensive manual or specification sheet. The majority of the SCR turn-off circuits can also be used for GTOs.

### Sawtooth Generator

Some of the areas of application for the GTO include counters, pulse generators, multivibrators, and voltage regulators. Figure 17.22 is an illustration of a simple sawtooth generator employing a GTO and a Zener diode.

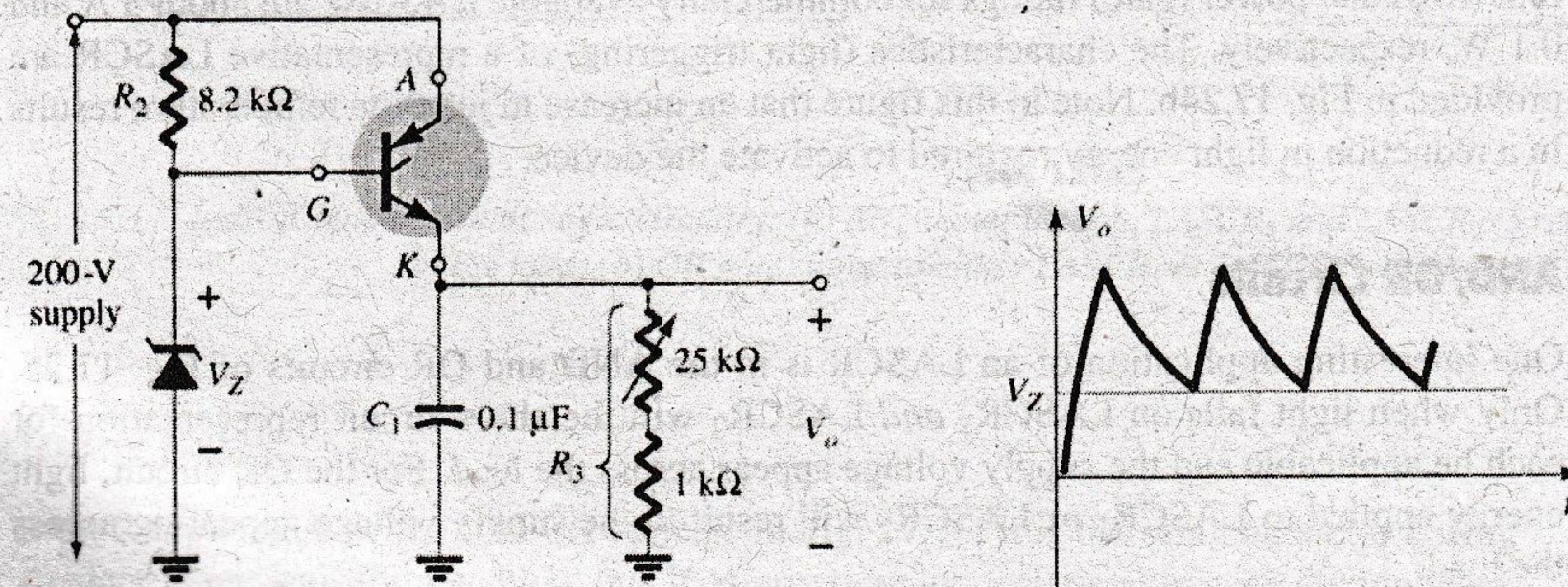


FIG. 17.22  
GTO sawtooth generator.

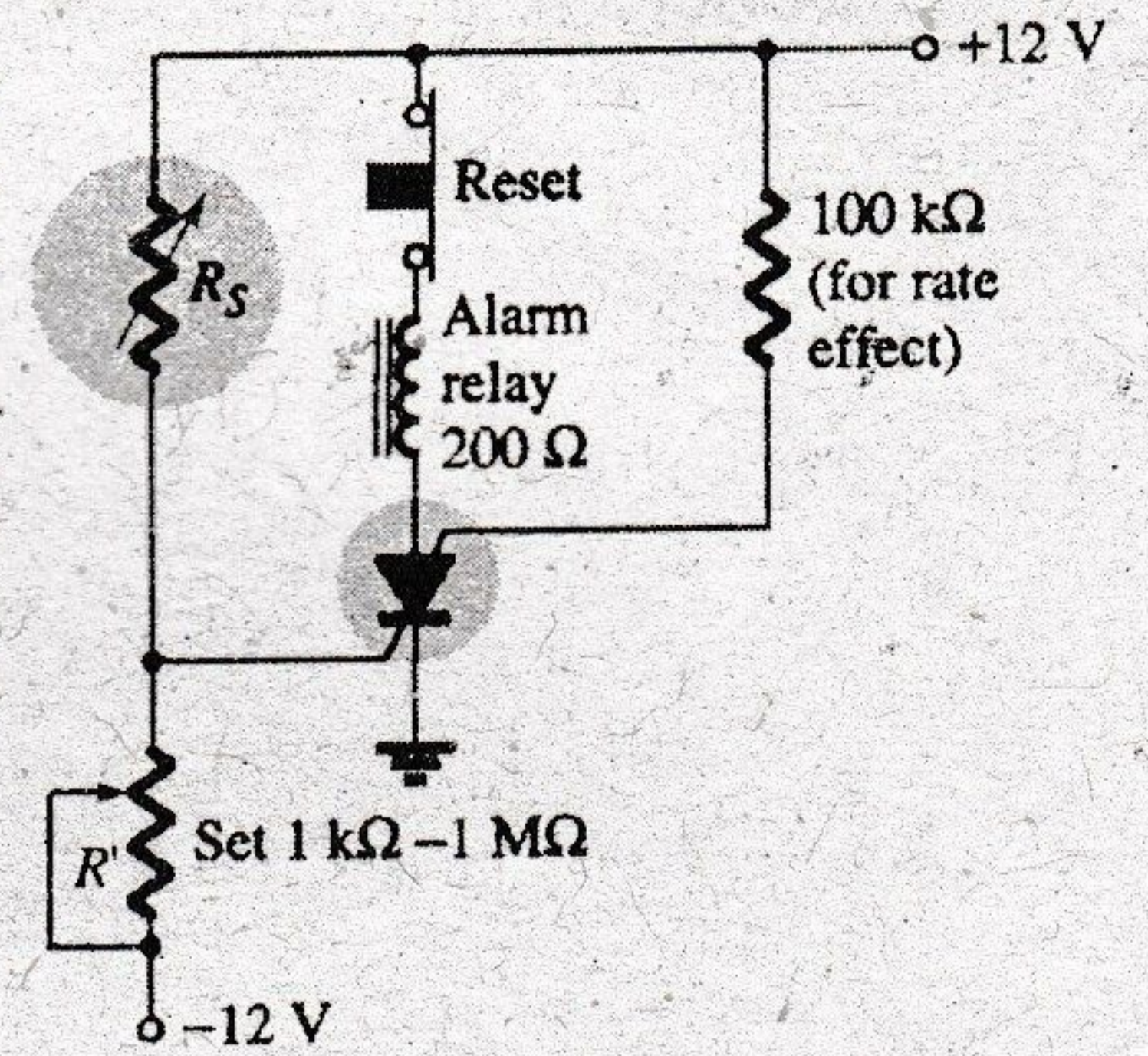
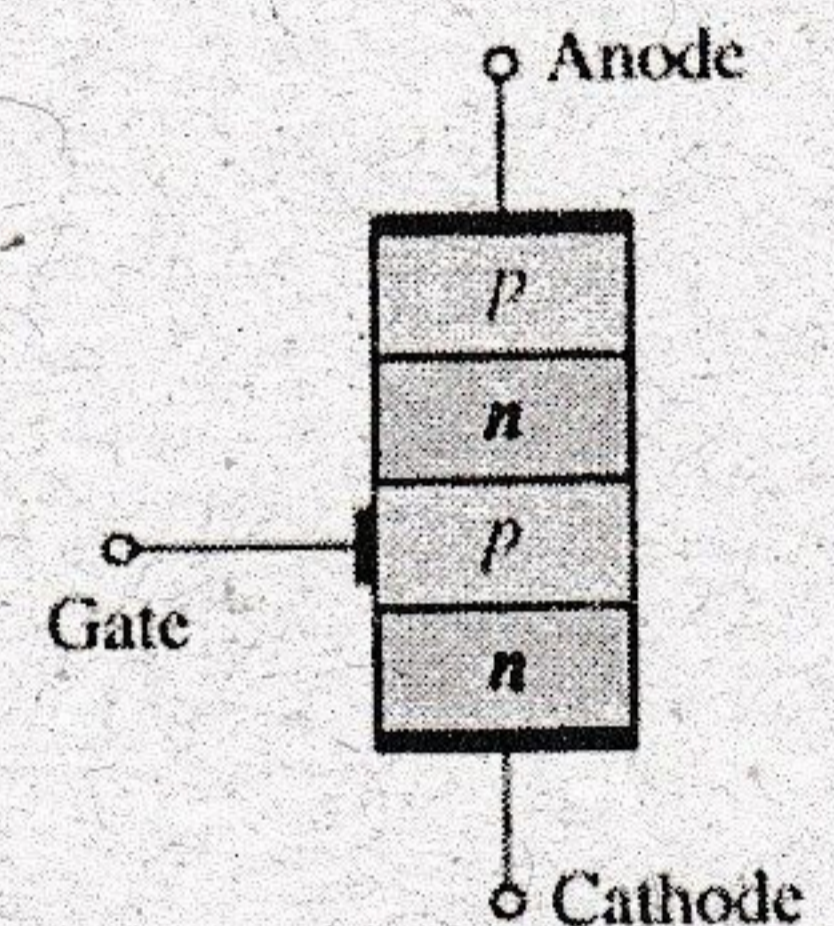
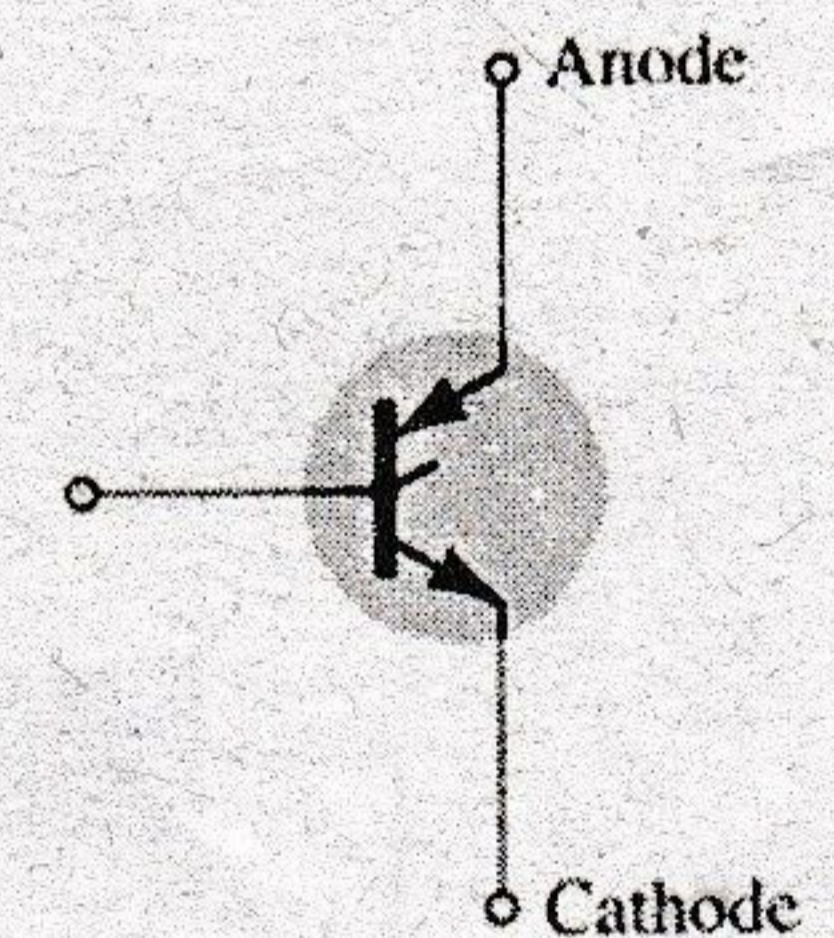


FIG. 17.19  
Alarm circuit.



(a)



(b)

FIG. 17.20  
Gate turn-off switch (GTO):  
(a) basic construction; (b) symbol.

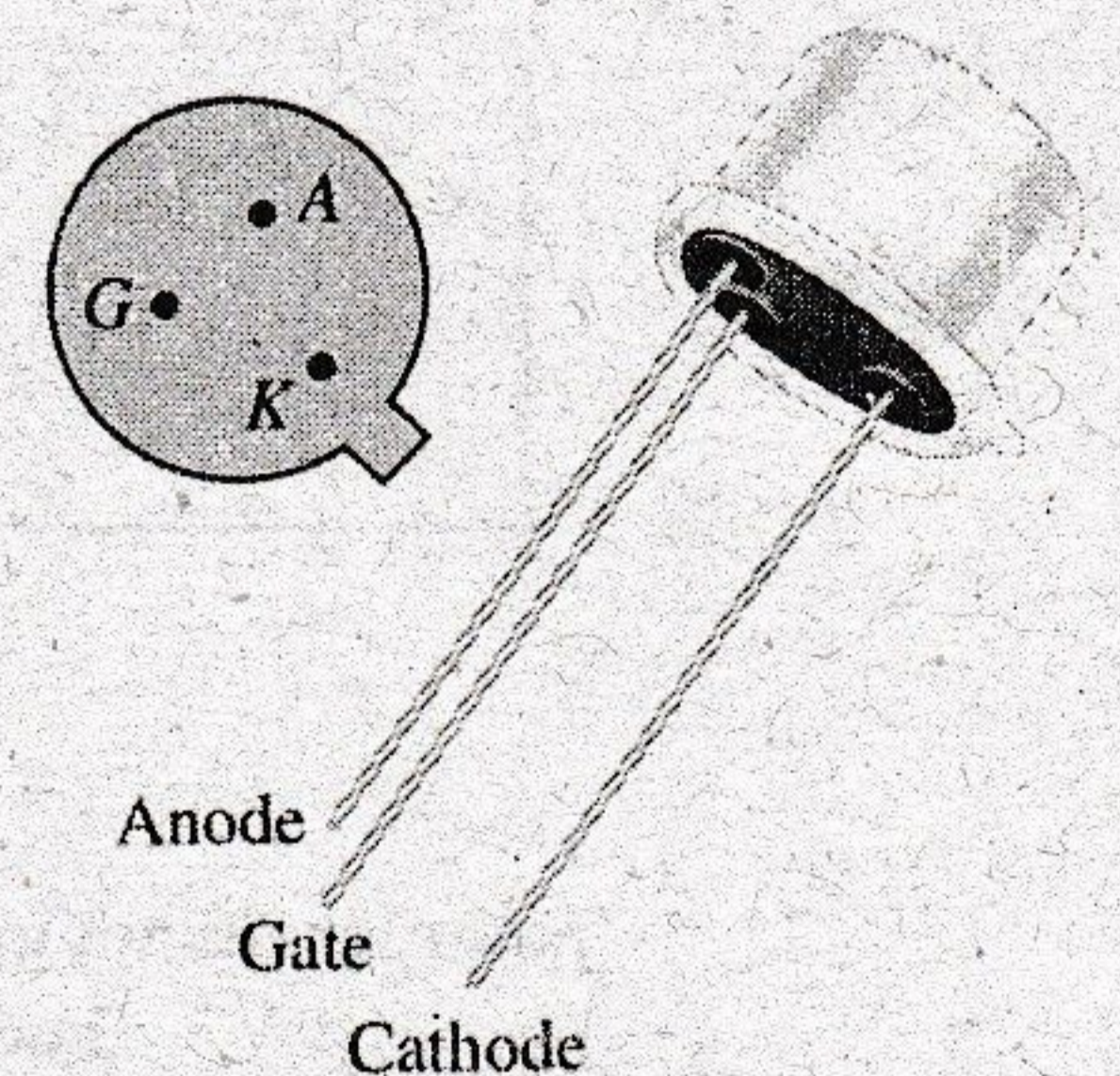
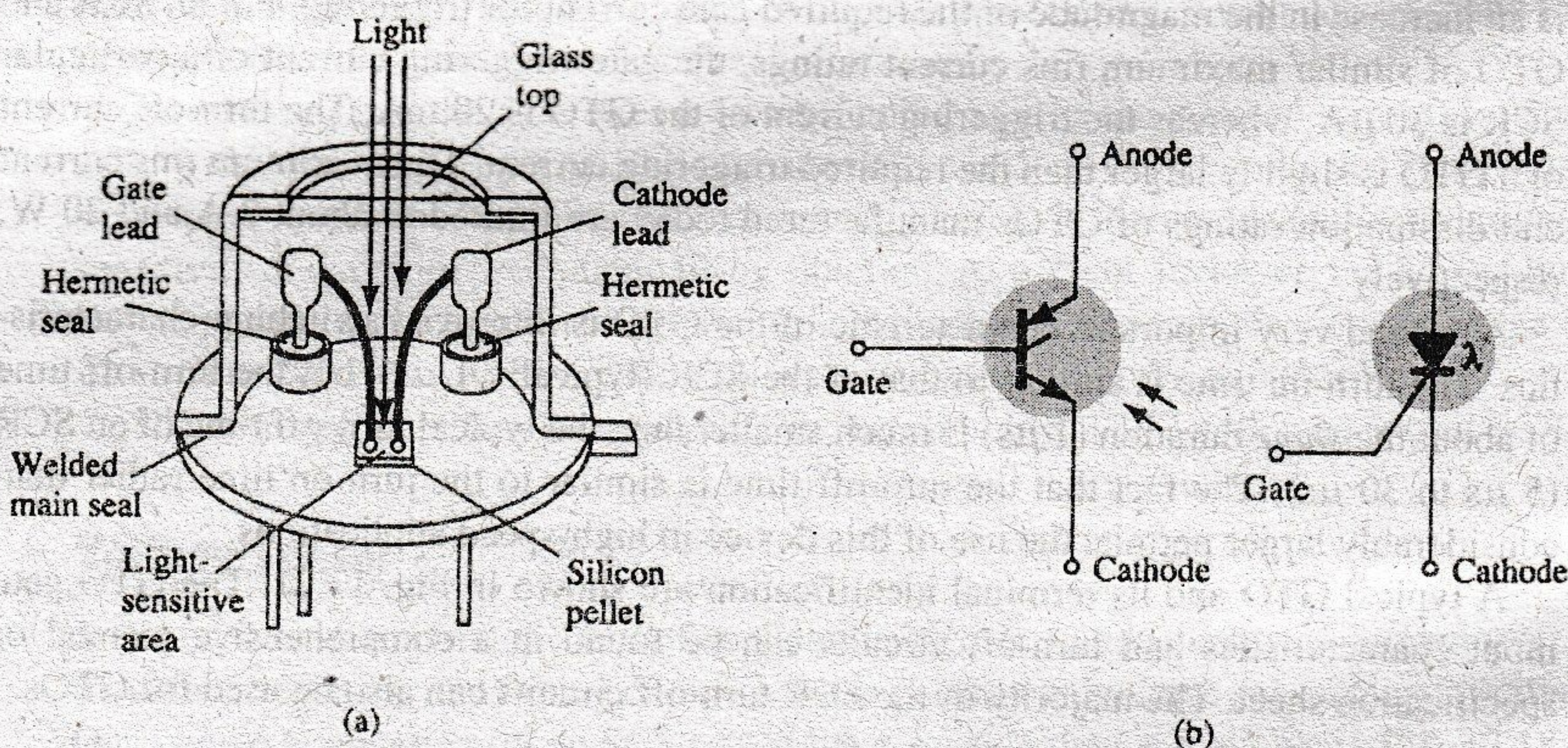


FIG. 17.21  
Typical GTO and its terminal identification.

When the supply is energized, the GTO will turn on, resulting in the short-circuit equivalent from anode to cathode. The capacitor  $C_1$  will then begin to charge toward the supply voltage as shown in Fig. 17.22. As the voltage across the capacitor  $C_1$  charges above the Zener potential, a reversal in gate-to-cathode voltage will result, establishing a reversal in gate current. Eventually, the negative gate current will be large enough to turn the GTO off. Once the GTO turns off, resulting in the open-circuit representation, the capacitor  $C_1$  will discharge through the resistor  $R_3$ . The discharge time will be determined by the circuit time constant  $\tau = R_3 C_1$ . The proper choice of  $R_3$  and  $C_1$  will result in the sawtooth waveform of Fig. 17.22. Once the output potential  $V_o$  drops below  $V_Z$ , the GTO will turn on and the process will repeat.

## 17.8 LIGHT-ACTIVATED SCR

The next in the series of *pnpn* devices is the light-activated SCR (LASCR). As indicated by the terminology, it is an SCR whose state is controlled by the light falling on a silicon semiconductor layer of the device. The basic construction of an LASCR is shown in Fig. 17.23a. As indicated in Fig. 17.23a, a gate lead is also provided to permit triggering the device using typical SCR methods. Note also in the figure that the mounting surface for the silicon pellet is the anode connection for the device. The graphical symbols most commonly employed for the LASCR are provided in Fig. 17.23b. The terminal identification and a typical LASCR appear in Fig. 17.24a.



**FIG. 17.23**

*Light-activated SCR (LASCR): (a) basic construction; (b) symbols.*

Some of the areas of application for the LASCR include optical light controls, relays, phase control, motor control, and a variety of computer applications. The maximum current (rms) and power (gate) ratings for commercially available LASCRs are about 3 A and 0.1 W, respectively. The characteristics (light triggering) of a representative LASCR are provided in Fig. 17.24b. Note in this figure that an increase in junction temperature results in a reduction in light energy required to activate the device.

### AND/OR Circuits

One interesting application of an LASCR is in the AND and OR circuits of Fig. 17.25. Only when light falls on LASCR<sub>1</sub> and LASCR<sub>2</sub> will the short-circuit representation for each be applicable and the supply voltage appear across the load. For the OR circuit, light energy applied to LASCR<sub>1</sub> or LASCR<sub>2</sub> will result in the supply voltage appearing across the load.

The LASCR is most sensitive to light when the gate terminal is open. Its sensitivity can be reduced and controlled somewhat by the insertion of a gate resistor, as shown in Fig. 17.25.

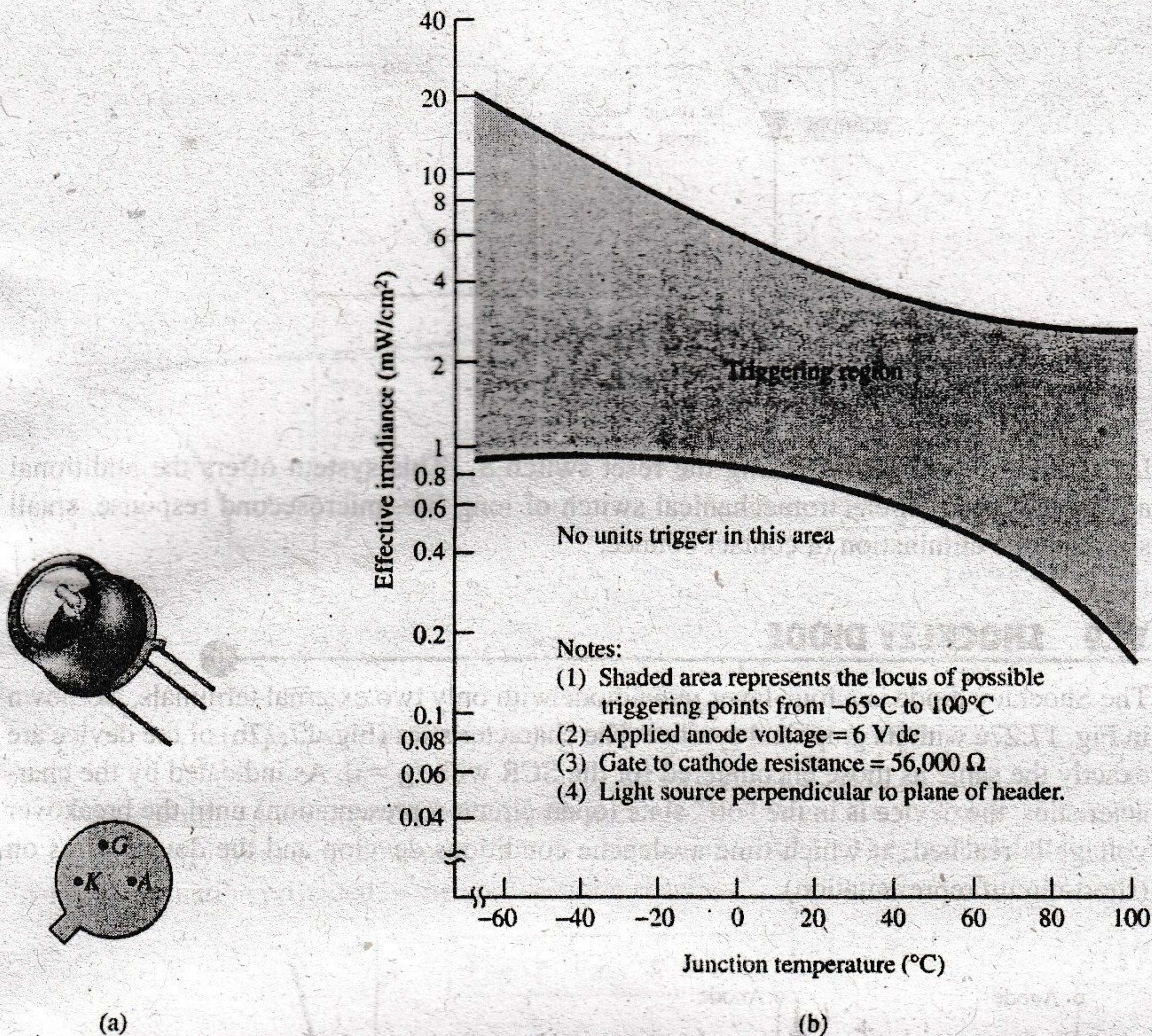


FIG. 17.24

LASCR: (a) appearance and terminal identification; (b) light-triggering characteristics.

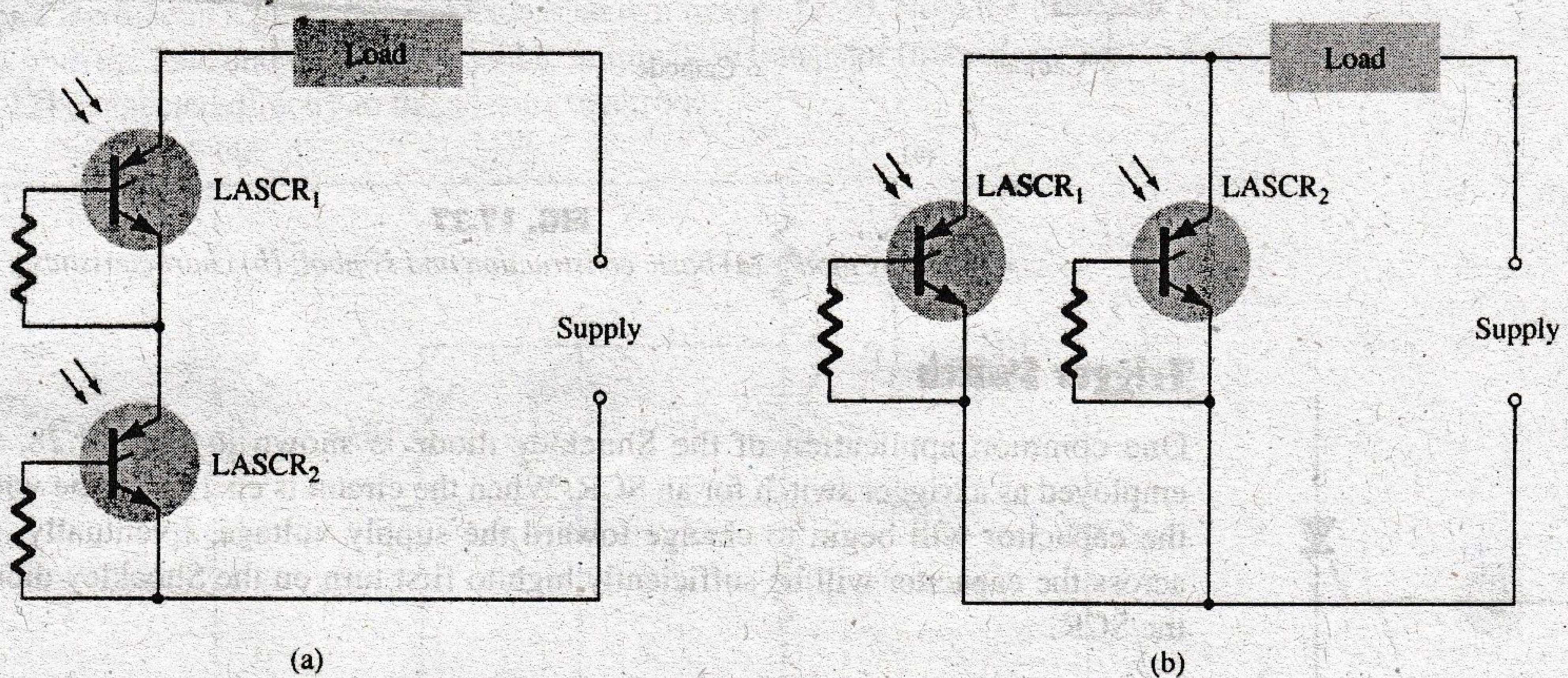
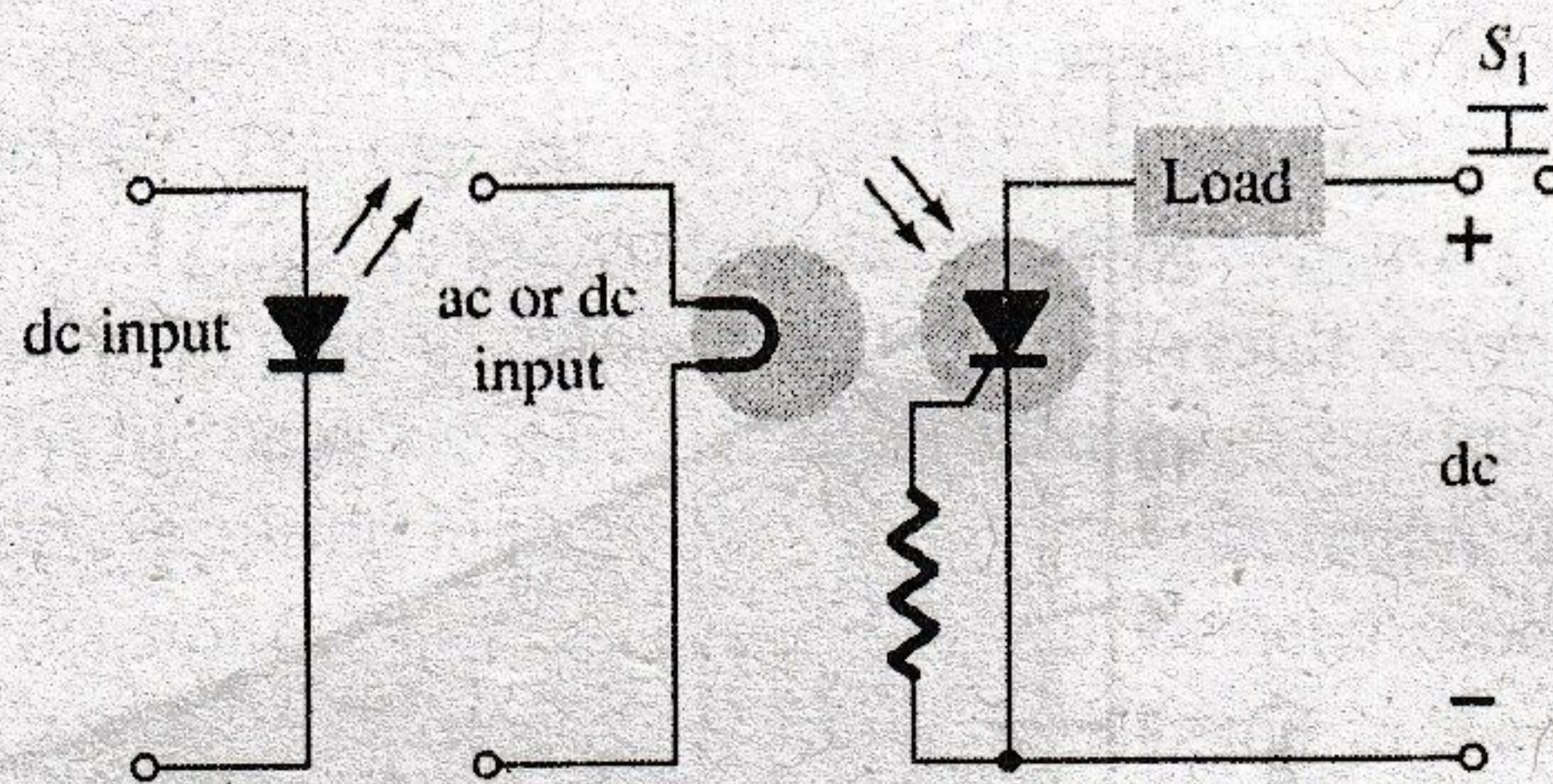


FIG. 17.25

LASCR optoelectronic logic circuitry: (a) AND gate: input to LASCR<sub>1</sub> and LASCR<sub>2</sub> is required for energization of the load; (b) OR gate: input to either LASCR<sub>1</sub> or LASCR<sub>2</sub> will energize the load.

### Latching Relay

A second application of the LASCR appears in Fig. 17.26. It is the semiconductor analog of an electromechanical relay. Note that it offers complete isolation between the input and the switching element. The energizing current can be passed through a light-emitting diode or a lamp, as shown in the figure. The incident light will cause the LASCR to turn on and permit a flow of charge (current) through the load as established by the dc supply. The

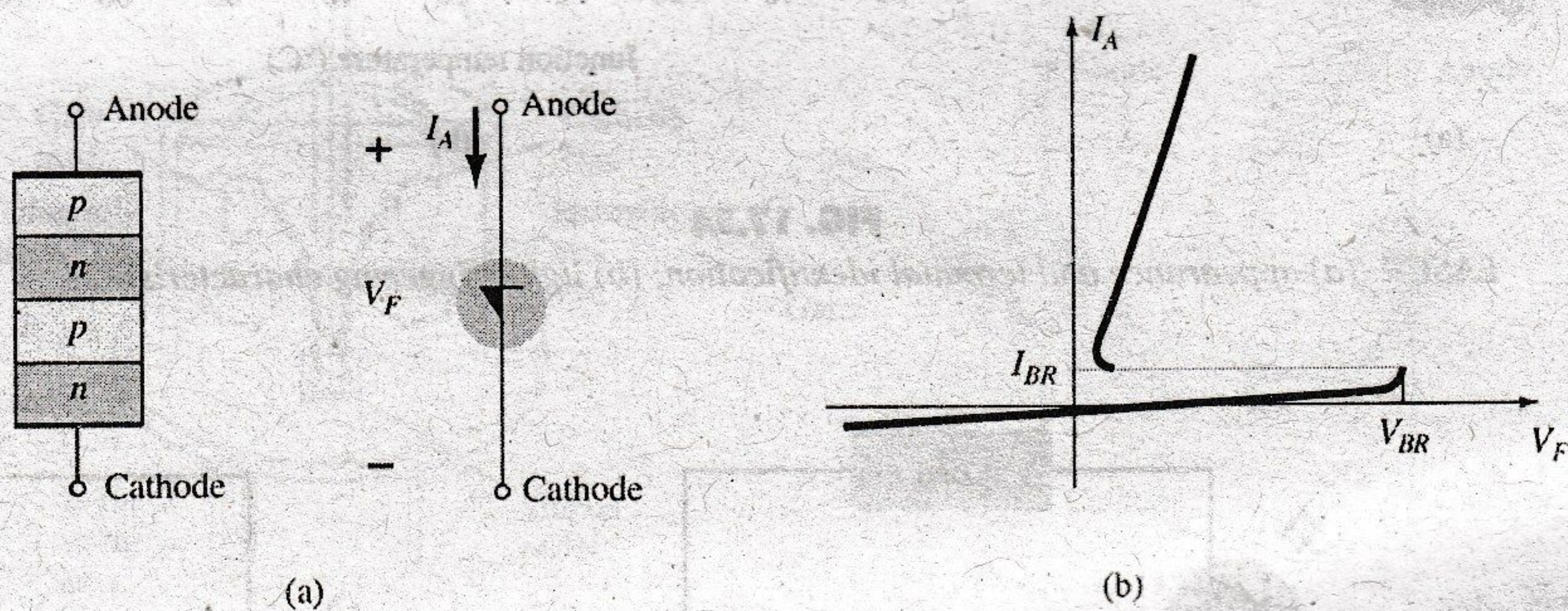


**FIG. 17.26**  
Latching relay.

LASCRL can be turned off using the reset switch  $S_1$ . This system offers the additional advantages over an electromechanical switch of long life, microsecond response, small size, and the elimination of contact bounce.

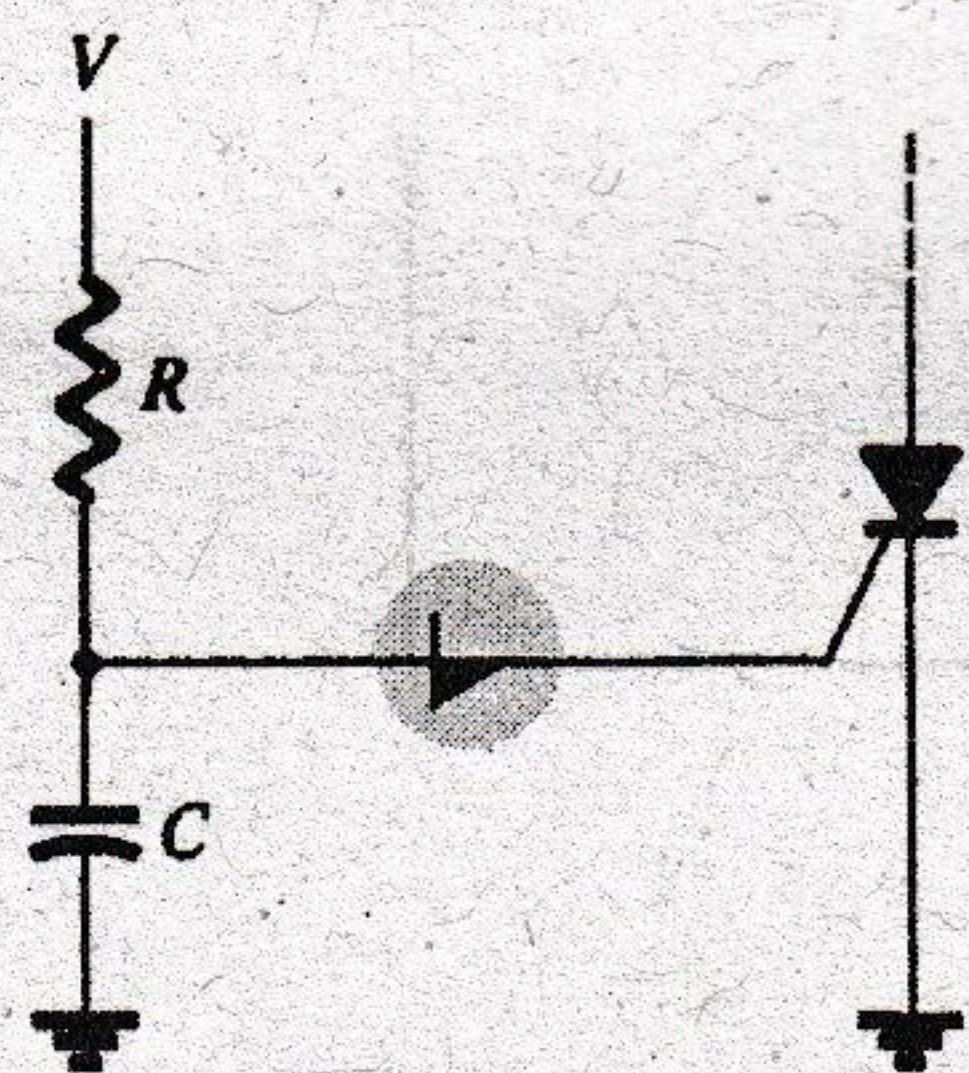
### 17.9 SHOCKLEY DIODE

The Shockley diode is a four-layer *pnpn* diode with only two external terminals, as shown in Fig. 17.27a with its graphical symbol. The characteristics (Fig. 17.27b) of the device are exactly the same as those encountered for the SCR with  $I_G = 0$ . As indicated by the characteristics, the device is in the "off" state (open-circuit representation) until the breakover voltage is reached, at which time avalanche conditions develop and the device turns on (short-circuit representation).



**FIG. 17.27**

Shockley diode: (a) basic construction and symbol; (b) characteristics.



**FIG. 17.28**  
Shockley diode application—  
trigger switch for an SCR.

### Trigger Switch

One common application of the Shockley diode is shown in Fig. 17.28, where it is employed as a trigger switch for an SCR. When the circuit is energized, the voltage across the capacitor will begin to change toward the supply voltage. Eventually, the voltage across the capacitor will be sufficiently high to first turn on the Shockley diode and then the SCR.

### 17.10 DIAC

The diac is basically a two-terminal parallel-inverse combination of semiconductor layers that permits triggering in either direction. The characteristics of the device, presented in Fig. 17.29a, clearly demonstrate that there is a breakover voltage in either direction. This possibility of an *on* condition in either direction can be used to its fullest advantage in ac applications.

The basic arrangement of the semiconductor layers of the diac is shown in Fig. 17.29b, along with its graphical symbol. Note that neither terminal is referred to as the cathode. Instead, there is an anode 1 (or electrode 1) and an anode 2 (or electrode 2). When anode 1 is positive with respect to anode 2, the semiconductor layers of particular interest are  $p_1n_2p_2$  and  $n_3$ . For anode 2 positive with respect to anode 1, the applicable layers are  $p_2n_2p_1$  and  $n_3$ .

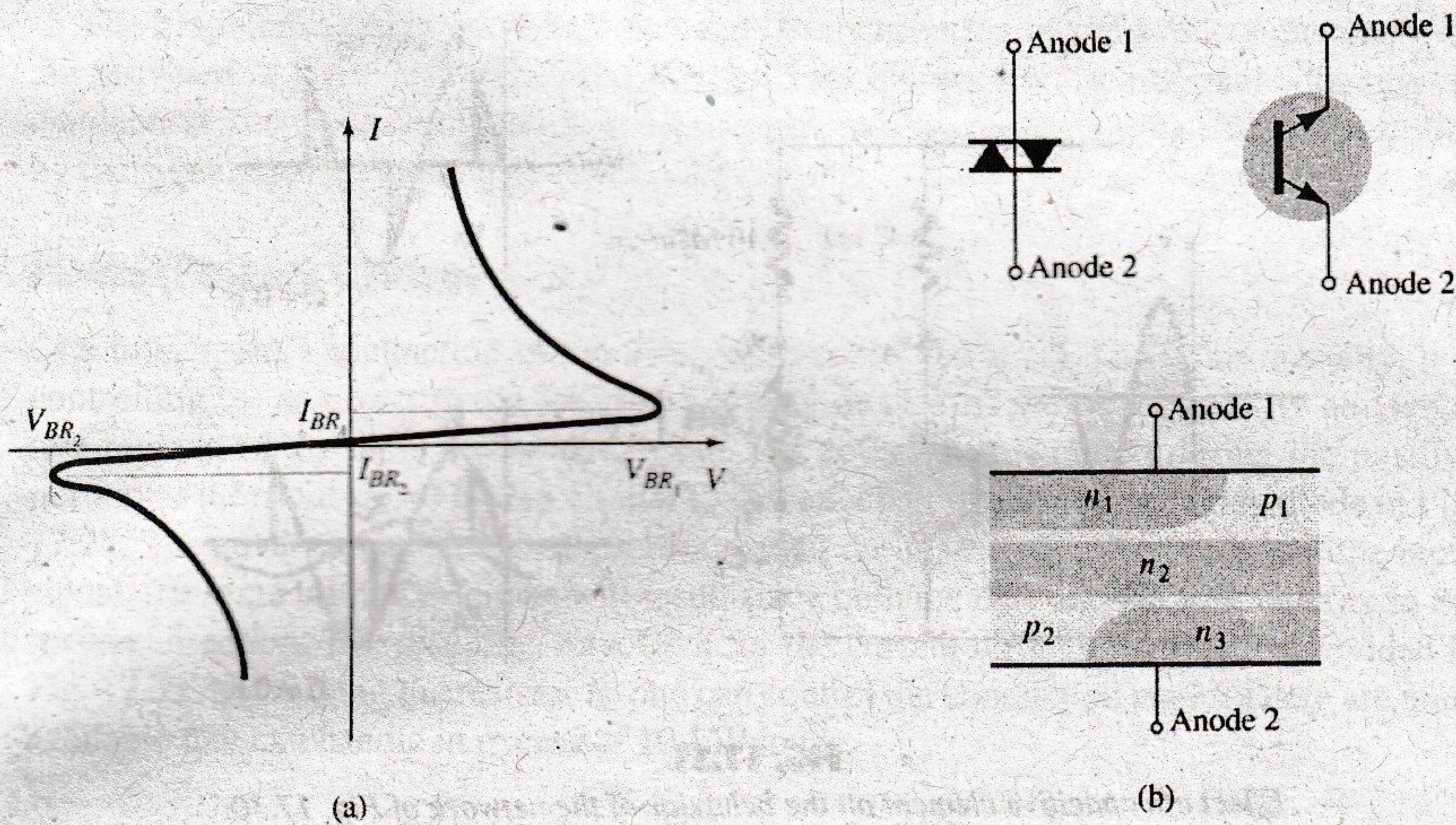


FIG. 17.29

The diac: (a) characteristics; (b) symbols and basic construction.

For the unit appearing in Fig. 17.29, the breakdown voltages are very close in magnitude but may vary from a minimum of 28 V to a maximum of 42 V. They are related by the following equation provided in the specification sheet:

$$V_{BR_1} = V_{BR_2} \pm 0.1V_{BR_2} \quad (17.1)$$

The current levels ( $I_{BR_1}$  and  $I_{BR_2}$ ) are also very close in magnitude for each device. For the unit of Fig. 17.29, both current levels are about  $200 \mu\text{A} = 0.2 \text{ mA}$ .

### Proximity Detector

The use of the diac in a proximity detector is shown in Fig. 17.30. Note the use of an SCR in series with the load and the programmable unijunction transistor (to be described in Section 17.12) connected directly to the sensing electrode.

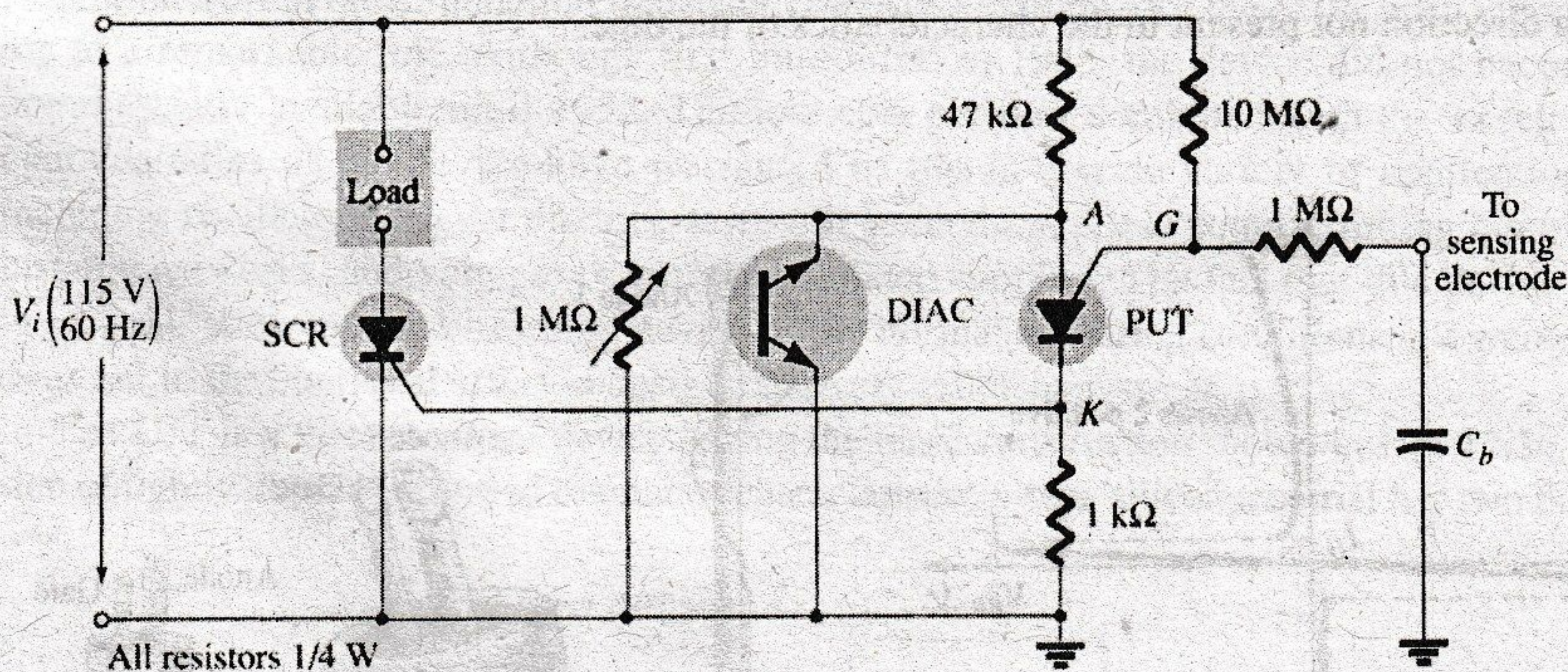
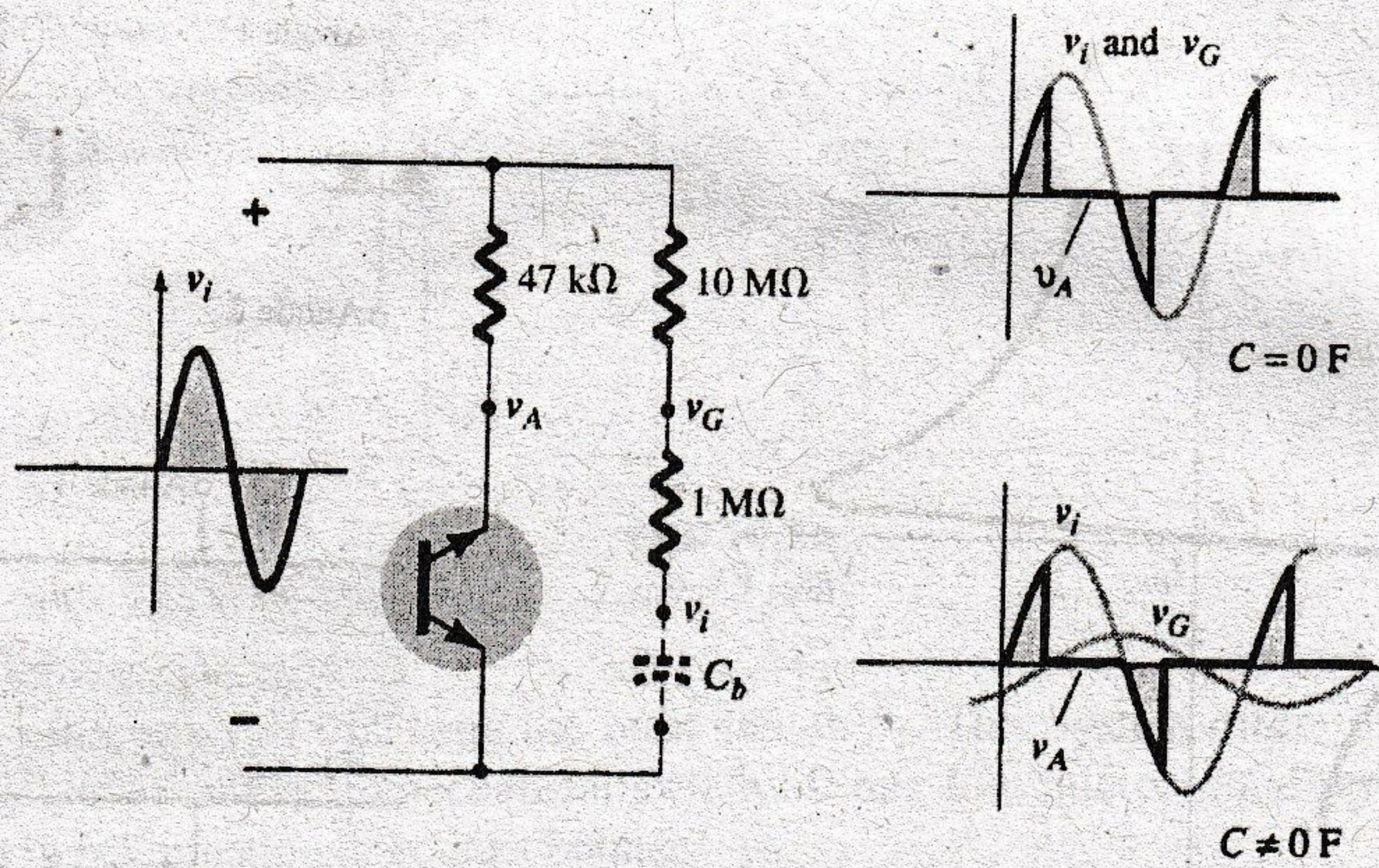


FIG. 17.30

Proximity detector or touch switch.

As a human body approaches the sensing electrode, the capacitance between the electrode and the ground ( $C_b$ ) increases. The programmable UJT (PUT) is a device that will fire (enter the short-circuit state) when the anode voltage ( $V_A$ ) is at least 0.7 V (for silicon) greater than the gate voltage ( $V_G$ ). Before the programmable device turns on, the system is essentially as shown in Fig. 17.31. As the input voltage rises, the diac voltage  $v_A$  will follow as shown in the figure until the firing potential is reached. It will then turn on and the diac voltage will drop substantially, as shown. Note that the diac is in essentially an open-circuit state until it fires. Before the capacitive element is introduced, the voltage  $v_G$  will be the



**FIG. 17.31**

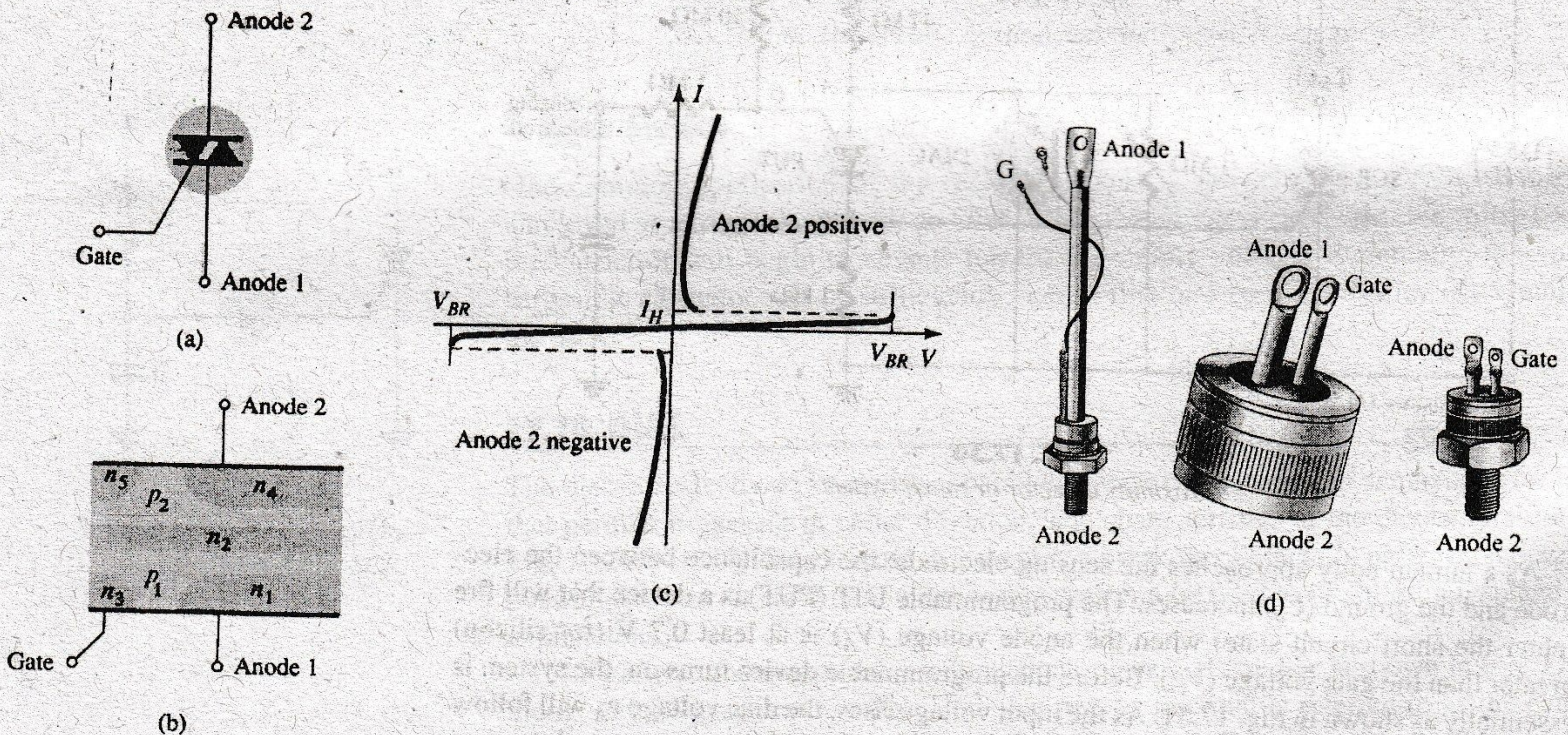
Effect of capacitive element on the behavior of the network of Fig. 17.30.

same as the input. As indicated in the figure, since both  $v_A$  and  $v_G$  follow the input,  $v_A$  can never be greater than  $v_G$  by 0.7 V and turn on the device. However, as the capacitive element is introduced, the voltage  $v_G$  will begin to lag the input voltage by an increasing angle, as indicated in the figure. There is therefore a point established where  $v_A$  can exceed  $v_G$  by 0.7 V and cause the programmable device to fire. A heavy current is established through the PUT at this point, raising the voltage  $v_G$  and turning on the SCR. A heavy SCR current will then exist through the load, reacting to the presence of the approaching person.

A second application of the diac appears in the next section (Fig. 17.33) as we consider an important power-control device: the triac.

### 17.11 TRIAC

The triac is fundamentally a diac with a gate terminal for controlling the turn-on conditions of the bilateral device in either direction. In other words, for either direction the gate current can control the action of the device in a manner very similar to that demonstrated for an SCR. The characteristics, however, of the triac in the first and third quadrants are somewhat different from those of the diac, as shown in Fig. 17.32c. Note the holding current in each direction not present in the characteristics of the diac.



**FIG. 17.32**

The triac: (a) symbol; (b) basic construction; (c) characteristics; (d) drawings.



The graphical symbol for the device and the distribution of the semiconductor layers are provided in Fig. 17.32 with photographs of the device. For each possible direction of conduction, there is a combination of semiconductor layers whose state will be controlled by the signal applied to the gate terminal.

### Phase (Power) Control

One fundamental application of the triac is presented in Fig. 17.33. In this capacity, it is controlling the ac power to the load by switching on and off during the positive and negative regions of the input sinusoidal signal. The action of this circuit during the positive portion of the input signal is very similar to that encountered for the Shockley diode in Fig. 17.28. The advantage of this configuration is that during the negative portion of the input signal, the same type of response will result since both the diac and the triac can fire in the reverse direction. The resulting waveform for the current through the load is provided in Fig. 17.33. By varying the resistor  $R$ , one can control the conduction angle. There are units available that can handle in excess of 10-kW loads.

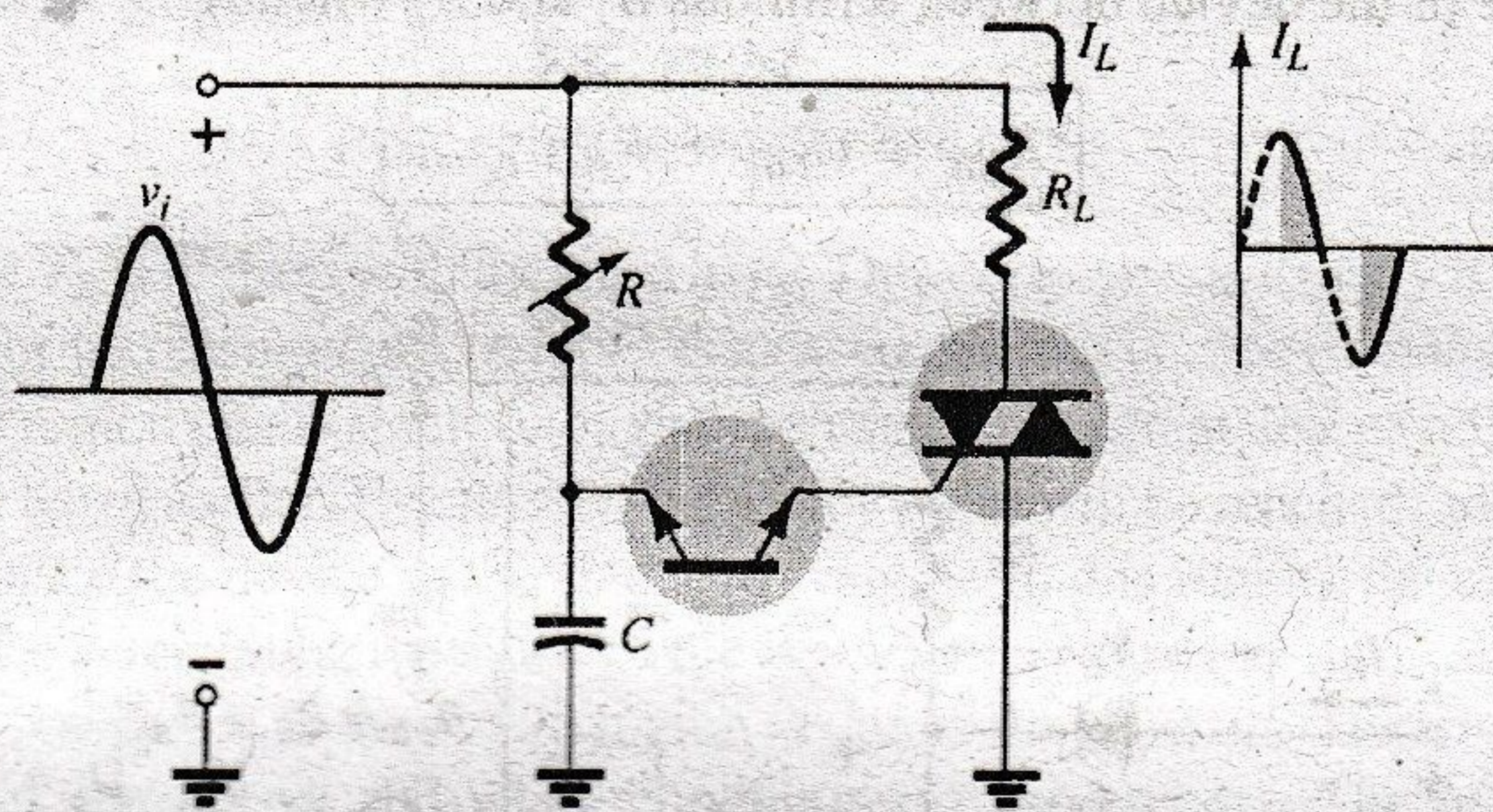


FIG. 17.33

Application of a triac: phase (power) control.

## OTHER DEVICES

### 17.12 UNIUNCTION TRANSISTOR

Recent interest in the unijunction transistor (UJT) has, like that for the SCR, been increasing at a remarkable rate. Although first introduced in 1948, the device did not become commercially available until 1952. The low cost per unit combined with the excellent characteristics of the device have warranted its use in a wide variety of applications, including oscillators, trigger circuits, sawtooth generators, phase control, timing circuits, bistable networks, and voltage- or current-regulated supplies. The fact that this device is, in general, a low-power-absorbing device under normal operating conditions is a tremendous aid in the continual effort to design relatively efficient systems.

The UJT is a three-terminal device having the basic construction shown in Fig. 17.34. A slab of lightly doped (increased resistance characteristic)  $n$ -type silicon material has two base

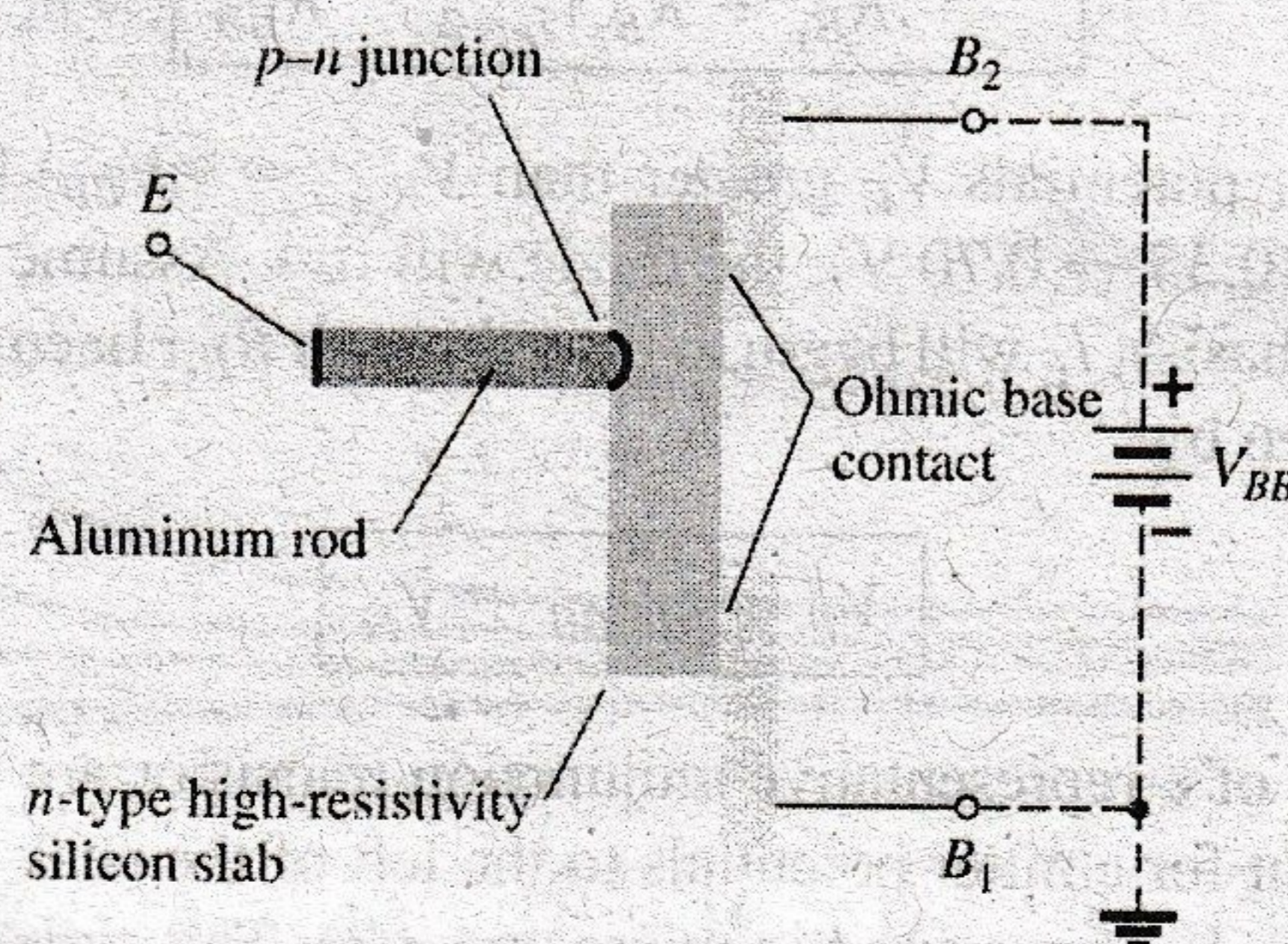


FIG. 17.34

Unijunction transistor (UJT): basic construction.

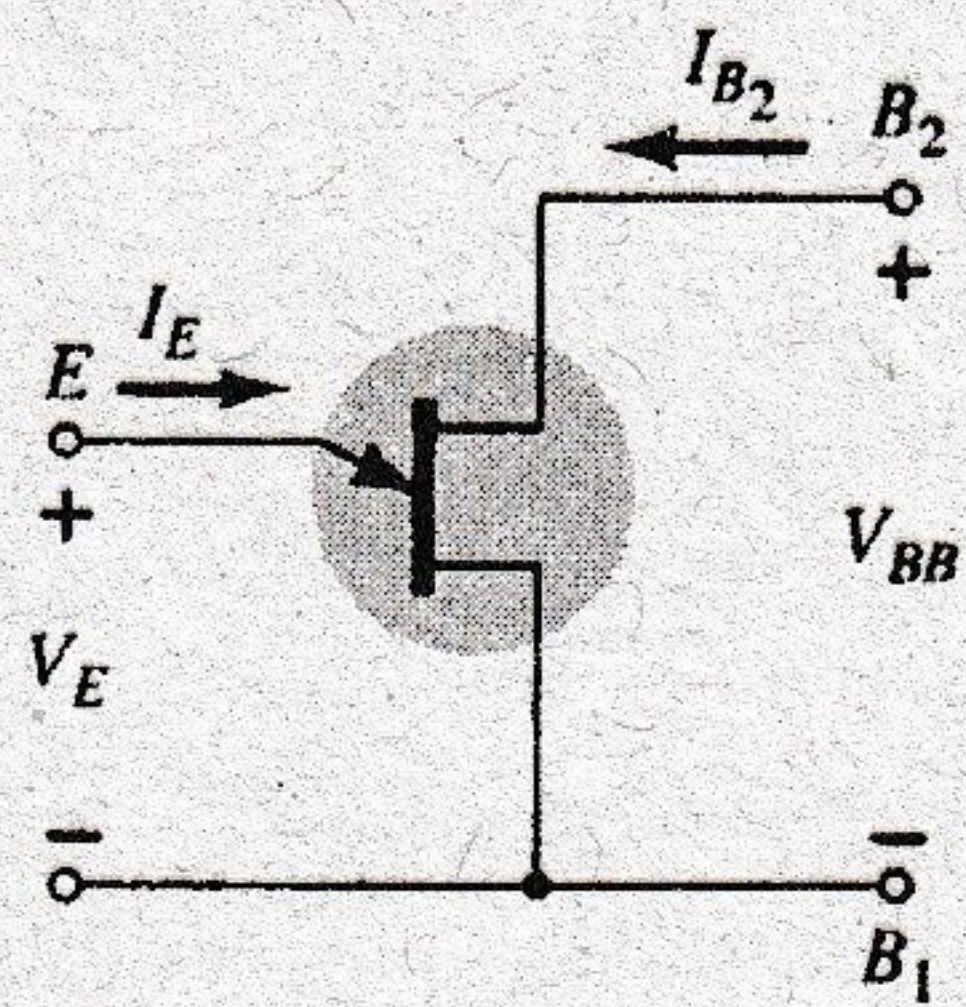


FIG. 17.35

Symbol and basic biasing arrangement for the unijunction transistor.

contacts attached to both ends of one surface and an aluminum rod alloyed to the opposite surface. The  $p-n$  junction of the device is formed at the boundary of the aluminum rod and the  $n$ -type silicon slab. The single  $p-n$  junction accounts for the terminology *unijunction*. It was originally called a duo (double) base diode due to the presence of two base contacts. Note in Fig. 17.34 that the aluminum rod is alloyed to the silicon slab at a point closer to the base 2 contact than the base 1 contact and that the base 2 terminal is made positive with respect to the base 1 terminal by  $V_{BB}$  volts. The effect of each will become evident in the paragraphs to follow.

The symbol for the unijunction transistor is provided in Fig. 17.35. Note that the emitter leg is drawn at an angle to the vertical line representing the slab of  $n$ -type material. The arrowhead is pointing in the direction of conventional current (hole) flow when the device is in the forward-biased, active, or conducting state.

The circuit equivalent of the UJT is shown in Fig. 17.36. Note the relative simplicity of this equivalent circuit: two resistors (one fixed, one variable) and a single diode. The resistance  $R_{B1}$  is shown as a variable resistor since its magnitude will vary with the current  $I_E$ . In fact, for a representative unijunction transistor,  $R_{B1}$  may vary from  $5 \text{ k}\Omega$  down to  $50 \Omega$  for a corresponding change of  $I_E$  from  $0 \mu\text{A}$  to  $50 \mu\text{A}$ . The interbase resistance  $R_{BB}$  is the resistance of the device between terminals  $B_1$  and  $B_2$  when  $I_E = 0$ . In equation form,

$$R_{BB} = (R_{B1} + R_{B2})|_{I_E=0} \quad (17.2)$$

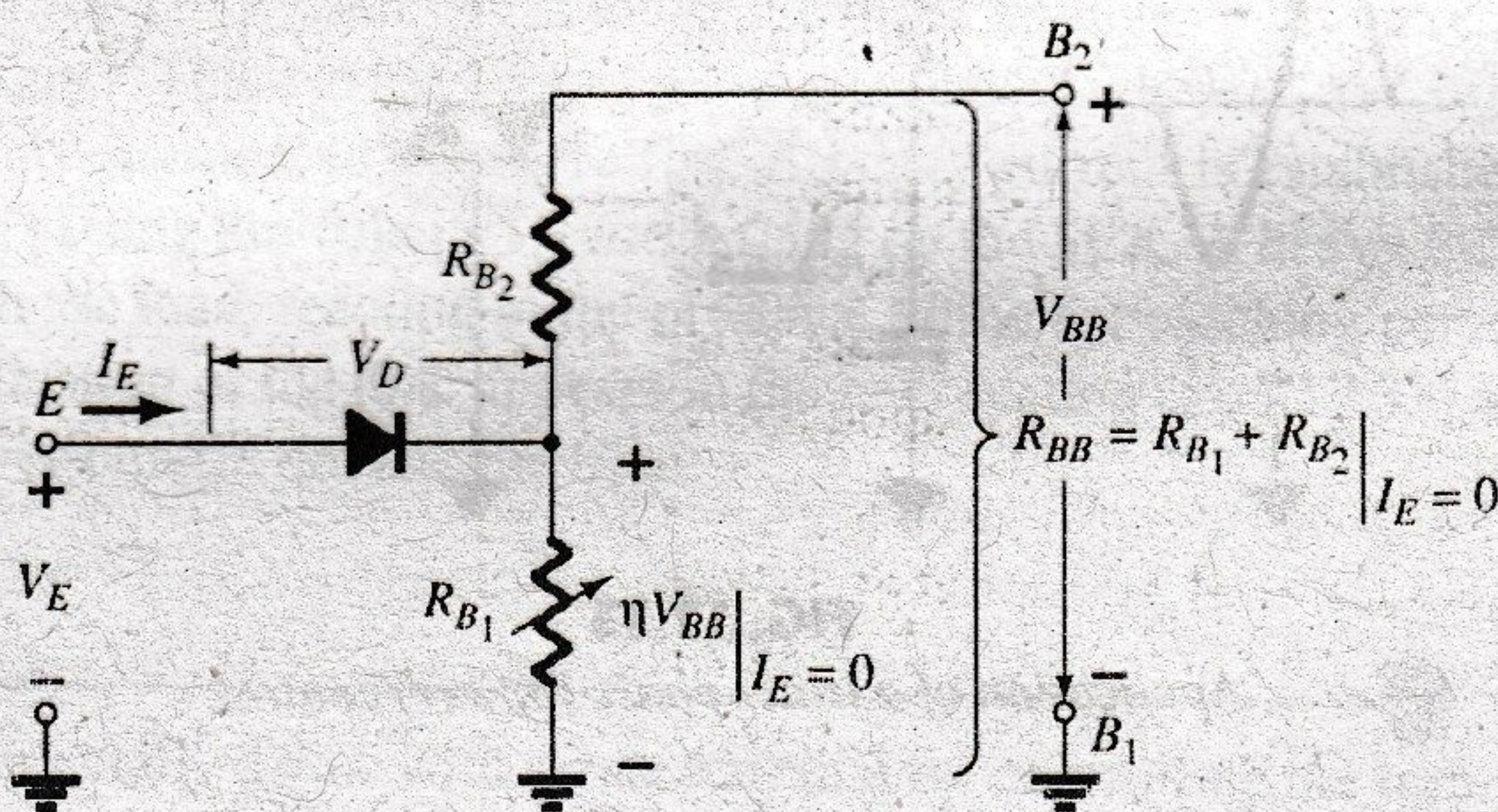


FIG. 17.36

UJT equivalent circuit.

( $R_{BB}$  is typically within the range of  $4 \text{ k}\Omega$  to  $10 \text{ k}\Omega$ .) The position of the aluminum rod of Fig. 17.34 will determine the relative values of  $R_{B1}$  and  $R_{B2}$  with  $I_E = 0$ . The magnitude of  $V_{R_{B1}}$  (with  $I_E = 0$ ) is determined by the voltage-divider rule in the following manner:

$$V_{R_{B1}} = \frac{R_{B1}}{R_{B1} + R_{B2}} \cdot V_{BB} = \eta V_{BB} |_{I_E=0} \quad (17.3)$$

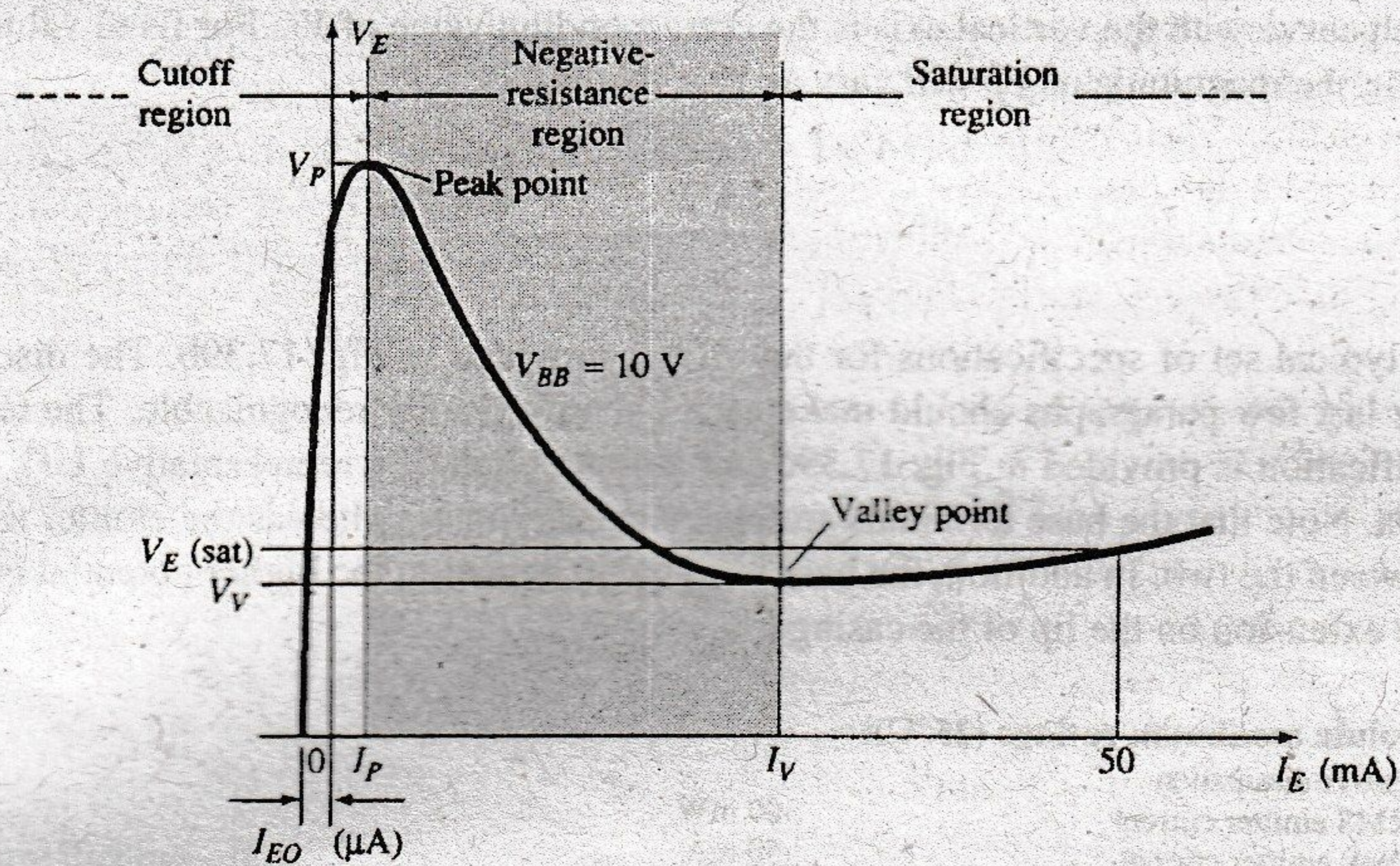
The Greek letter  $\eta$  (eta) denotes the *intrinsic stand-off* ratio of the device, which is defined by

$$\eta = \frac{R_{B1}}{R_{B1} + R_{B2}} |_{I_E=0} = \frac{R_{B1}}{R_{BB}} \quad (17.4)$$

For applied emitter potentials  $V_E$  greater than  $V_{R_{B1}}$  ( $= \eta V_{BB}$ ) by the forward voltage drop of the diode  $V_D$  ( $0.35 \rightarrow 0.70 \text{ V}$ ), the diode will fire. Assume the short-circuit representation (on an ideal basis);  $I_E$  will begin to flow through  $R_{B1}$ . In equation form, the emitter firing potential is given by

$$V_P = \eta V_{BB} + V_D \quad (17.5)$$

The characteristics of a representative unijunction transistor are shown for  $V_{BB} = 10 \text{ V}$  in Fig. 17.37. Note that for emitter potentials to the left of the peak point, the magnitude of  $I_E$  is never greater than  $I_{EO}$  (measured in microamperes). The current  $I_{EO}$  corresponds very closely to the reverse leakage current  $I_{CO}$  of the conventional bipolar transistor. This region, as indicated in the figure, is called the cutoff region. Once conduction is established at  $V_E = V_P$ ,

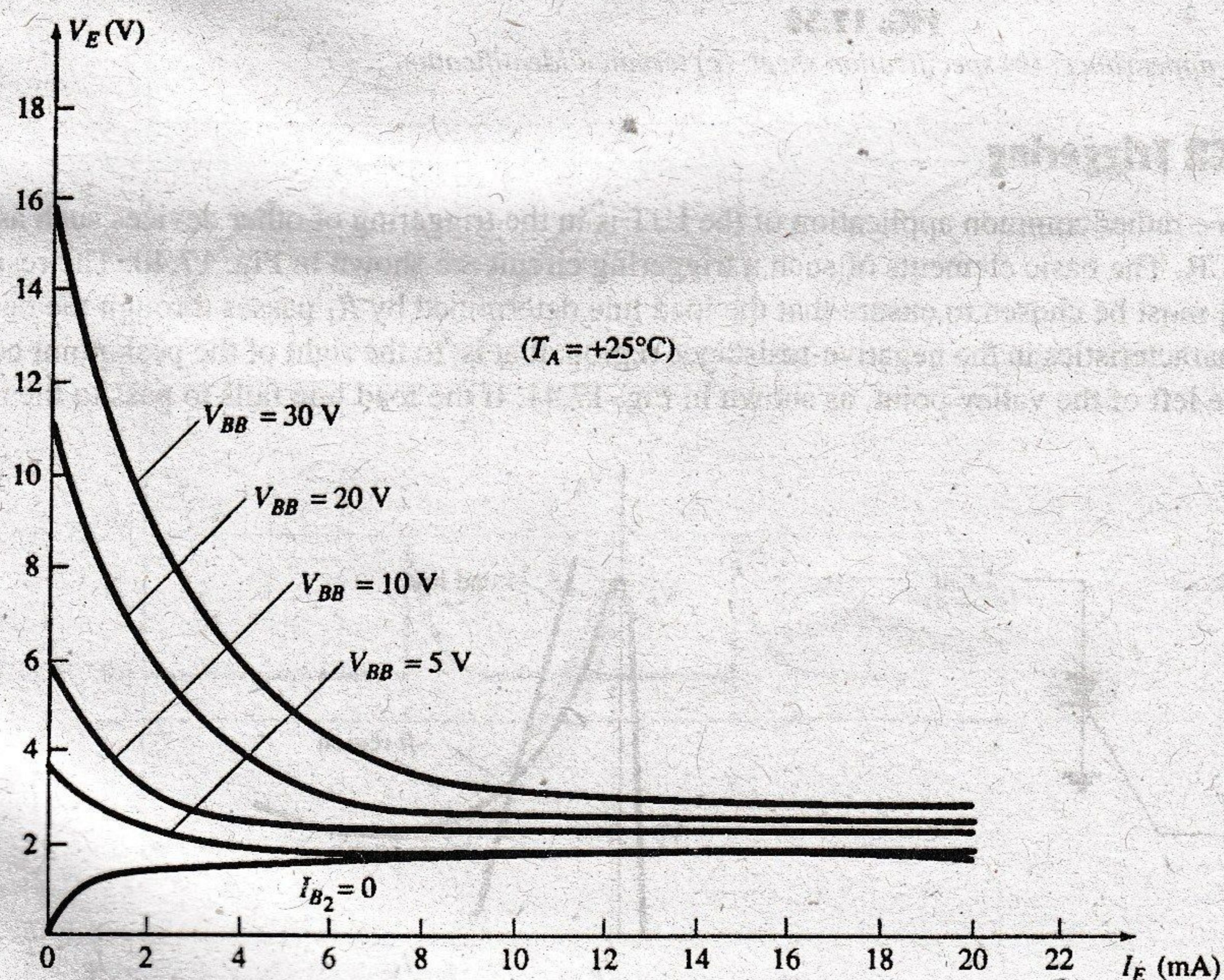

**FIG. 17.37**

*UJT static emitter characteristic curve.*

the emitter potential  $V_E$  will drop with increase in  $I_E$ . This corresponds exactly to the decreasing resistance  $R_B$  for increasing current  $I_E$ , as discussed earlier. This device, therefore, has a *negative-resistance* region that is stable enough to be used with a great deal of reliability in the areas of application listed earlier. Eventually, the valley point will be reached, and any further increase in  $I_E$  will place the device in the saturation region. In this region, the characteristics approach those of the semiconductor diode in the equivalent circuit of Fig. 17.36.

The decrease in resistance in the active region is due to the holes injected into the  $n$ -type slab from the aluminum  $p$ -type rod when conduction is established. The increased hole content in the  $n$ -type material will result in an increase in the number of free electrons in the slab, producing an increase in conductivity  $G$  and a corresponding drop in resistance ( $R \downarrow = 1/G \uparrow$ ). Three other important parameters for the unijunction transistor are  $I_P$ ,  $V_V$ , and  $I_V$ . Each is indicated on Fig. 17.37. They are all self-explanatory.

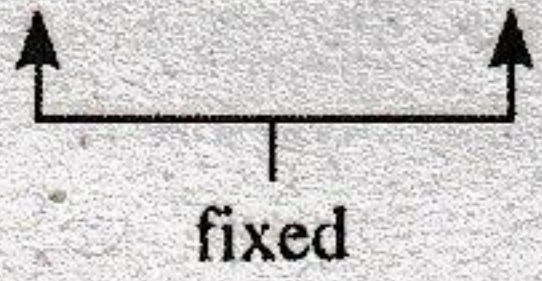
The emitter characteristics as they normally appear are provided in Fig. 17.38. Note that  $I_{E0}$  ( $\mu\text{A}$ ) is not in evidence since the horizontal scale is in milliamperes. The intersection


**FIG. 17.38**

*Typical static emitter characteristic curves for a UJT.*

of each curve with the vertical axis is the corresponding value of  $V_P$ . For fixed values of  $\eta$  and  $V_D$ , the magnitude of  $V_P$  will vary as  $V_{BB}$ , that is,

$$V_P \uparrow = \eta V_{BB} \uparrow + V_D$$



A typical set of specifications for the UJT is provided in Fig. 17.39b. The discussion of the last few paragraphs should make each quantity readily recognizable. The terminal identification is provided in Fig. 17.39c and a photograph of a representative UJT in Fig. 17.39a. Note that the base terminals are opposite each other, whereas the emitter terminal is between the two. In addition, the base terminal to be tied to the higher potential is closer to the extension on the lip of the casing.

**Absolute maximum ratings (25°C):**

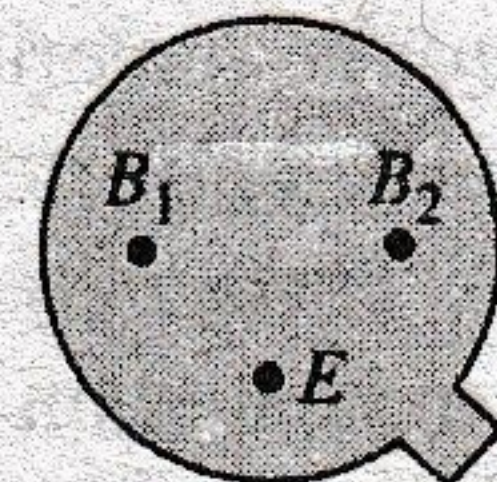
Power dissipation	
RMS emitter current	300 mA
Peak emitter current	50 mA
Emitter reverse voltage	2 A
Interbase voltage	30 V
Operating temperature range	35 V
Storage temperature range	-65°C to +125°C

**Electrical characteristics (25°C):**

	Minimum	Typical	Maximum
Intrinsic standoff ratio ( $V_{BB} = 10\text{ V}$ )	0.56	0.65	
$\eta$	0.56	0.65	0.75
Interbase resistance ( $k\Omega$ ) ( $V_{BB} = 3\text{ V}, I_E = 0$ )	$R_{BB}$ 4.7	7	9.1
Emitter saturation voltage ( $V_{BB} = 10\text{ V}, I_E = 50\text{ mA}$ )	$V_{E(sat)}$	2	
Emitter reverse current ( $V_{BB} = 3\text{ V}, I_{B1} = 0$ )	$I_{EO}$	0.05	12
Peak point emitter current ( $V_{BB} = 25\text{ V}$ )	$I_P$ ( $\mu\text{A}$ )	0.04	5
Valley point current ( $V_{BB} = 20\text{ V}$ )	$I_V$ (mA)	4	6



(a)



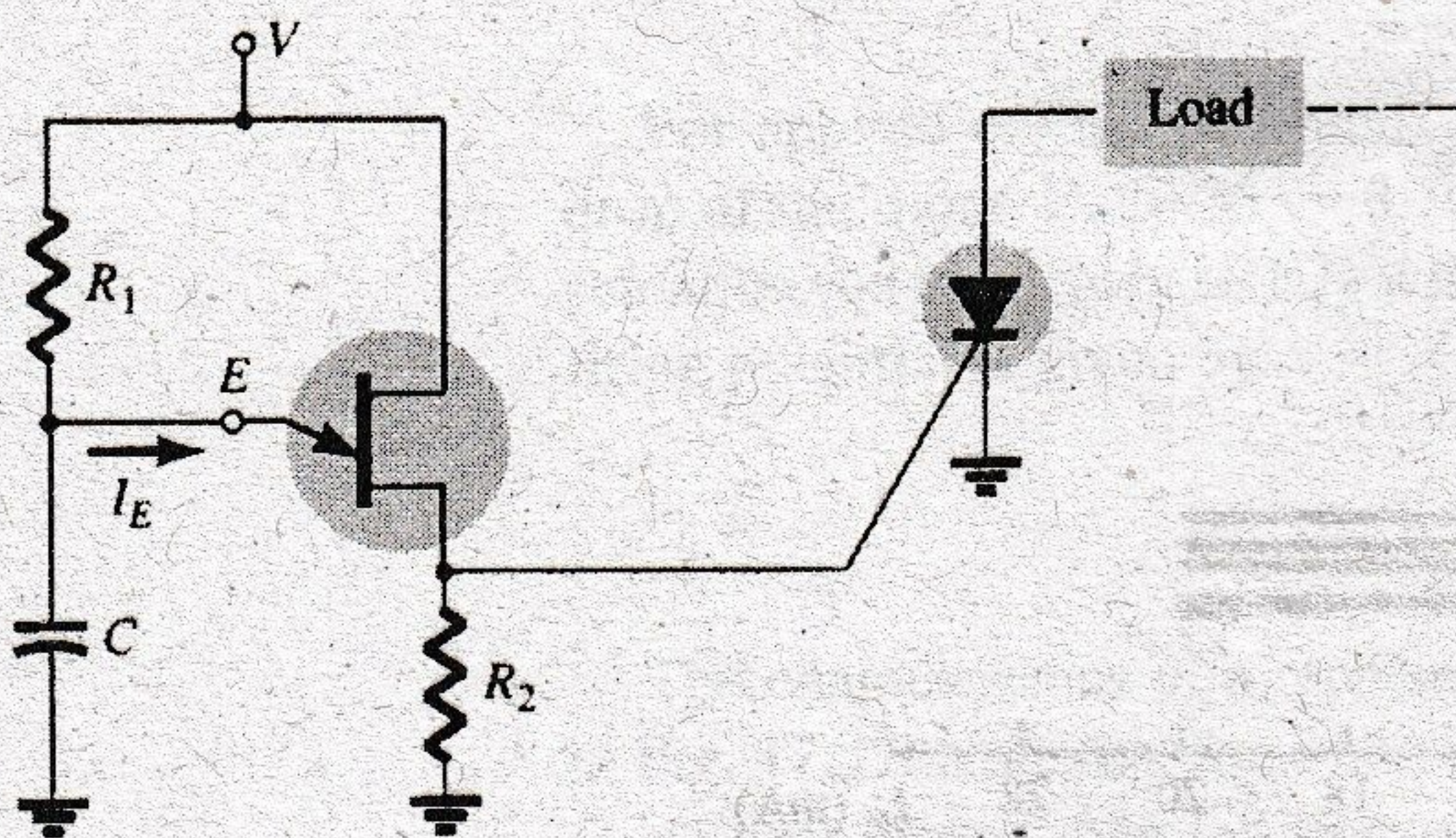
(c)

**FIG. 17.39**

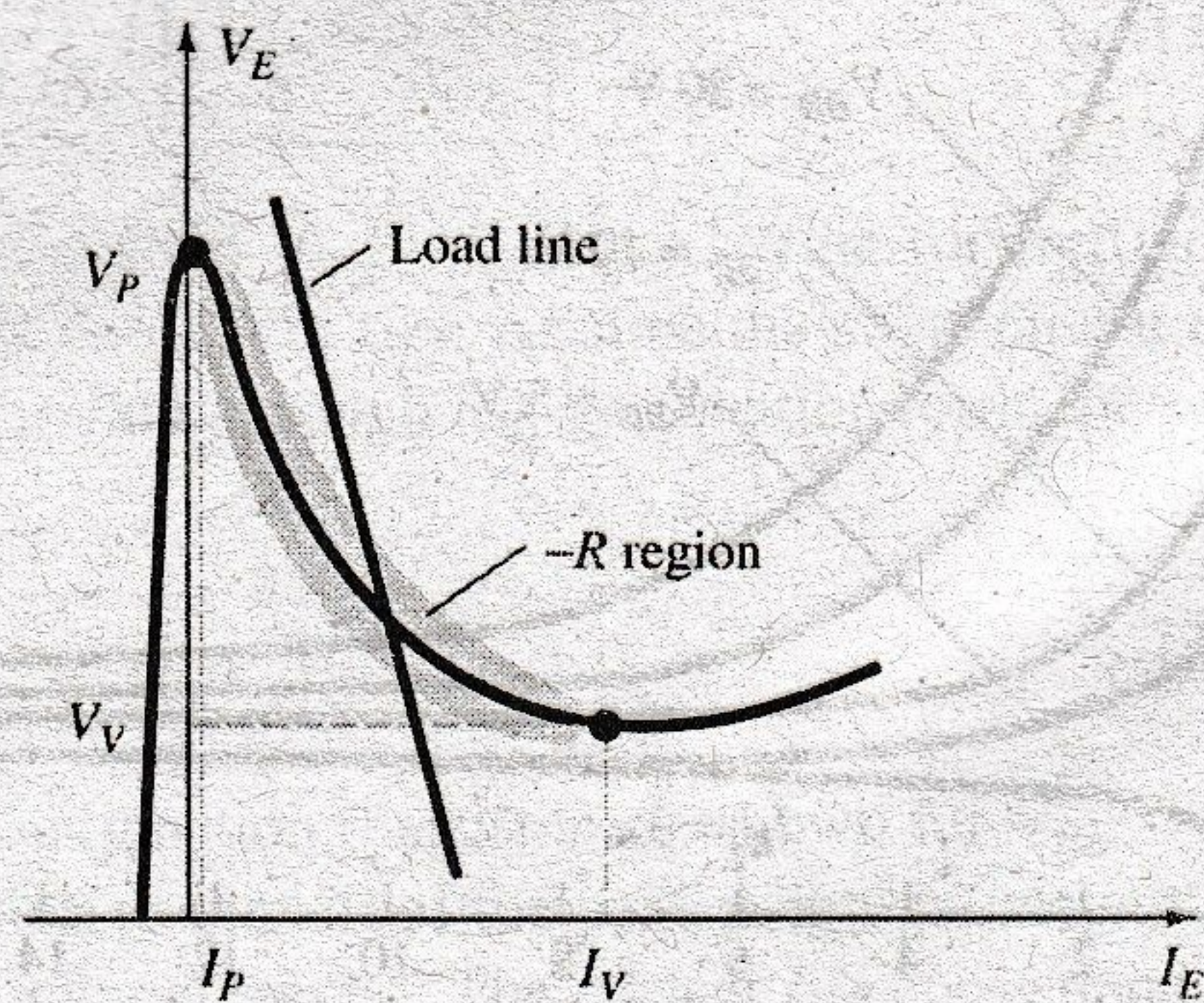
UJT: (a) appearance; (b) specification sheet; (c) terminal identification.

**SCR Triggering**

One rather common application of the UJT is in the triggering of other devices such as the SCR. The basic elements of such a triggering circuit are shown in Fig. 17.40. The resistor  $R_1$  must be chosen to ensure that the load line determined by  $R_1$  passes through the device characteristics in the negative-resistance region, that is, to the right of the peak point but to the left of the valley point, as shown in Fig. 17.41. If the load line fails to pass to the right



**FIG. 17.40**  
UJT triggering of an SCR.



**FIG. 17.41**  
Load line for a triggering application.

A representative set of characteristics for a phototransistor is provided in Fig. 17.49 along with the symbolic representation of the device. Note the similarities between these curves and those of a typical bipolar transistor. As expected, an increase in light intensity corresponds to an increase in collector current. To provide a greater degree of familiarity with the light-intensity unit of measurement, milliwatts per square centimeter, we give a curve of base current versus flux density in Fig. 17.50a. Note the exponential increase in base current with increasing flux density. In the same figure, a sketch of the phototransistor is provided with the terminal identification and the angular alignment.

Some of the areas of application for the phototransistor include computer logic circuitry, lighting control (highways, etc.), level indication, relays, and counting systems.

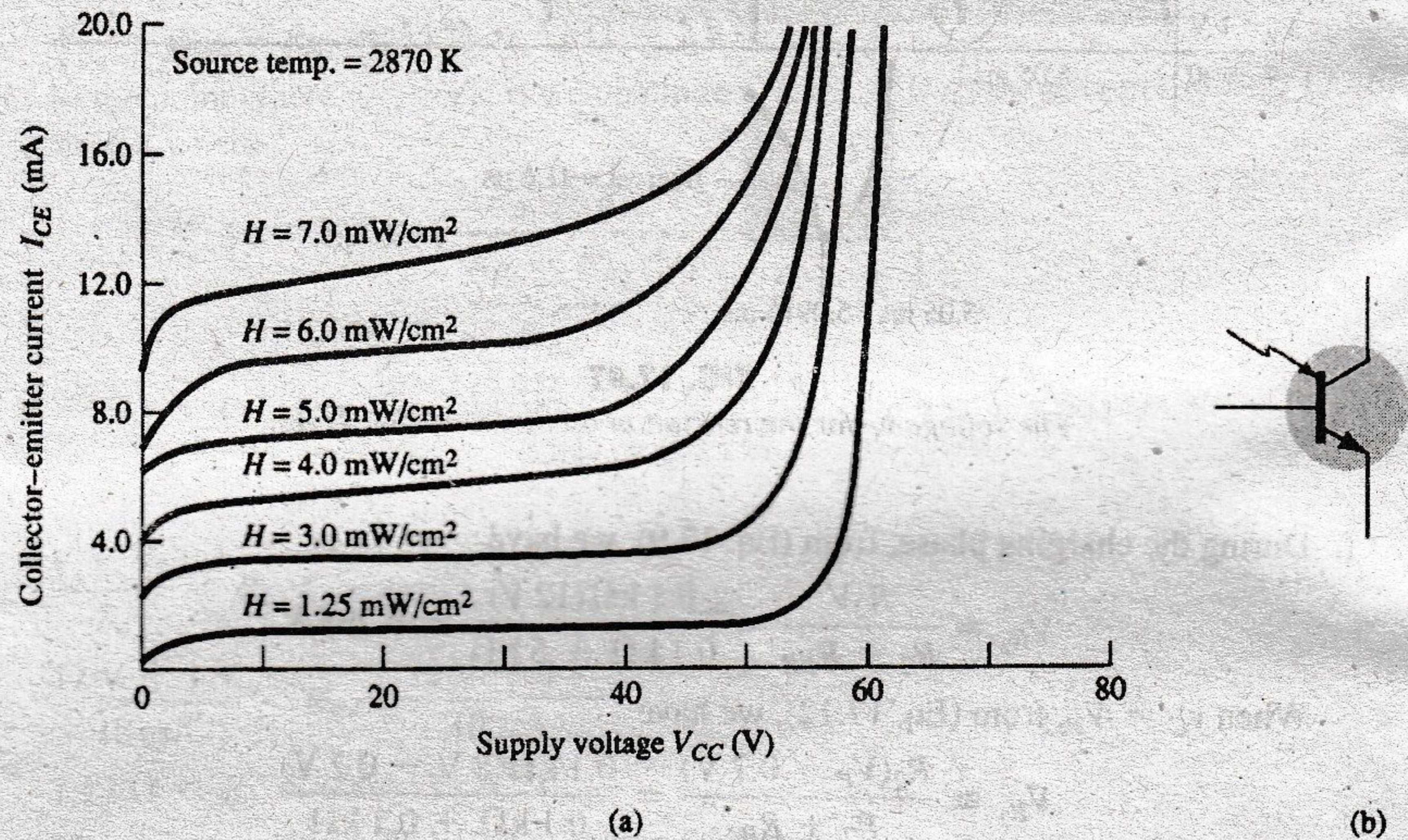


FIG. 17.49

Phototransistor: (a) collector characteristics; (b) symbol.

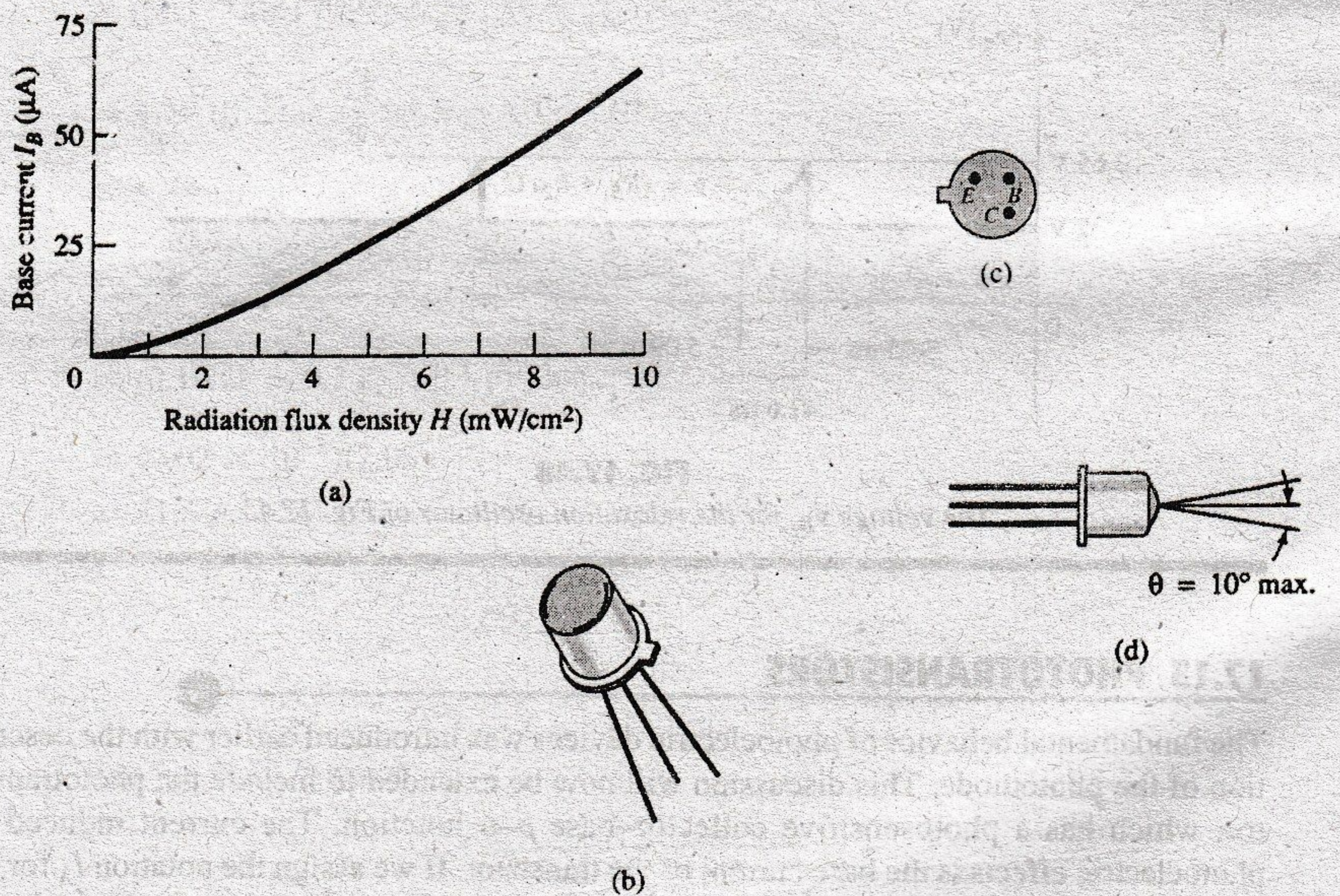
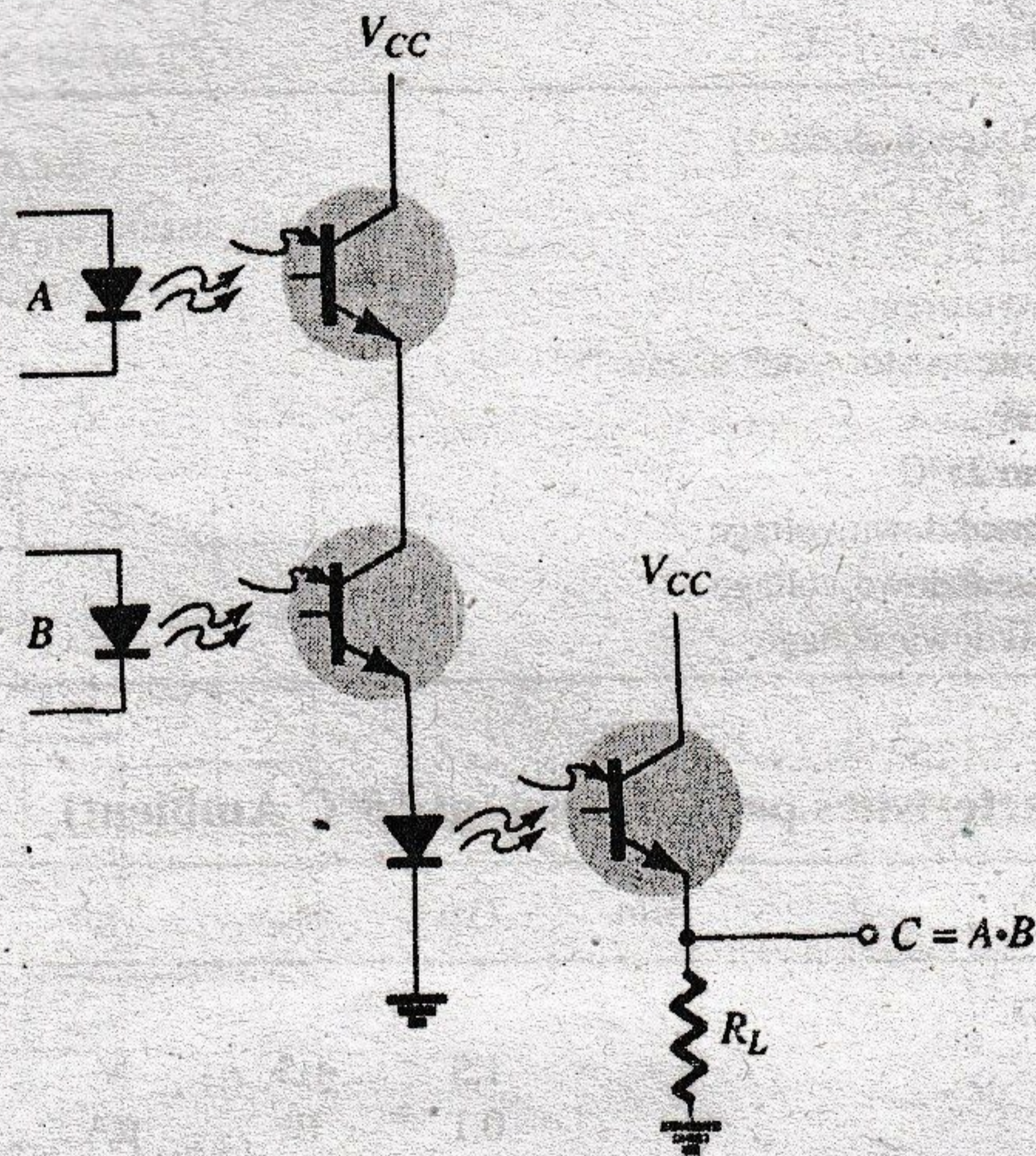


FIG. 17.50

Phototransistor: (a) base current versus flux density; (b) device; (c) terminal identification; (d) angular alignment.

## High-Isolation AND Gate

A high-isolation AND gate is shown in Fig. 17.51 using three phototransistors and three LEDs (light-emitting diodes). The LEDs are semiconductor devices that emit light at an intensity determined by the forward current through the device. With the aid of discussions in Chapter 1, the circuit behavior should be relatively easy to understand. The terminology *high isolation* simply refers to the lack of an electrical connection between the input and output circuits.

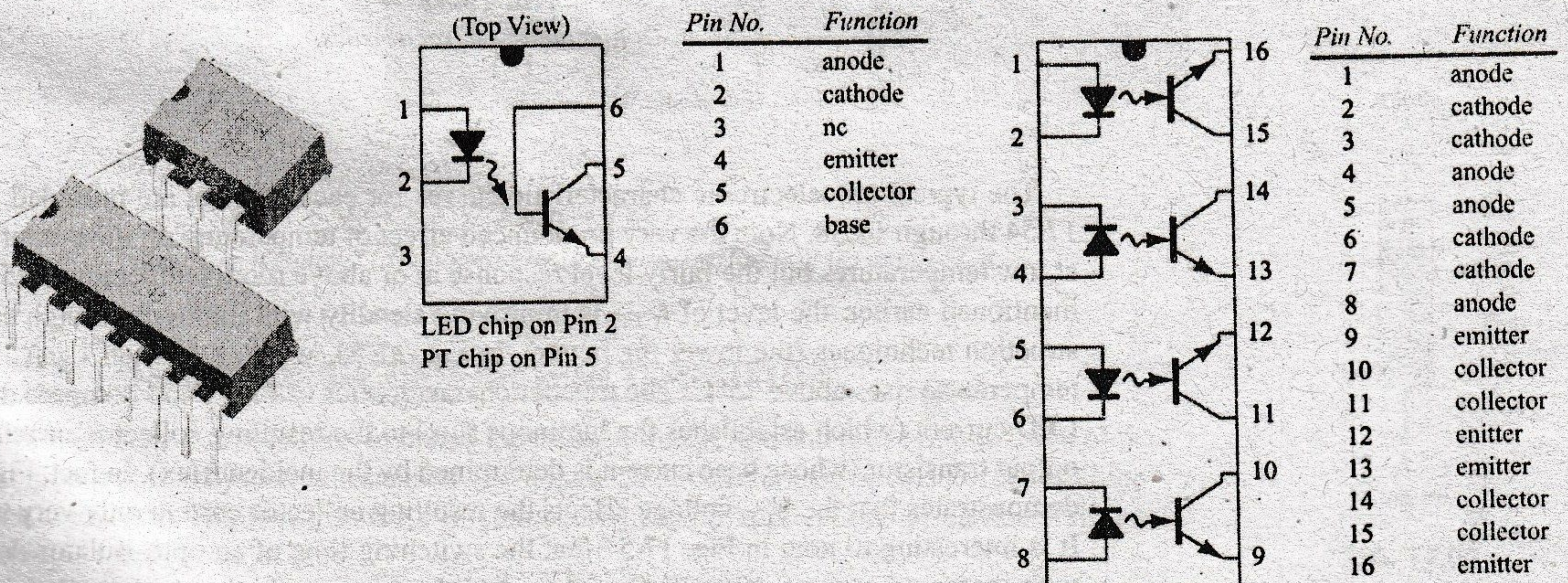


**FIG. 17.51**

High-isolation AND gate employing phototransistors and light-emitting diodes (LEDs).

## 17.14 OPTO-ISOLATORS

The *opto-isolator* is a device that incorporates many of the characteristics described in the preceding section. It is simply a package that contains both an infrared LED and a photo-detector such as a silicon diode, transistor Darlington pair, or SCR. The wavelength response of each device is tailored to be as identical as possible to permit the highest measure of coupling possible. In Fig. 17.52, two possible chip configurations are provided,



**FIG. 17.52**

Two Litronix opto-isolators.

with a drawing of each. There is a transparent insulating cap between each set of elements embedded in the structure (not visible) to permit the passage of light. They are designed with response times so small that they can be used to transmit data in the megahertz range.

The maximum ratings and electrical characteristics for the 6-pin model are provided in Fig. 17.53. Note that  $I_{CEO}$  is measured in nanoamperes and that the power dissipation of the LED and transistor are about the same.

### Maximum Ratings

Gallium arsenide LED (each channel)	
Power dissipation @ 25°C	200 mW
Derate linearly from 25°C	2.6 mW/°C
Continuous forward current	150 mA
Detector silicon phototransistor (each channel)	
Power dissipation @ 25°C	200 mW
Derate linearly from 25°C	2.6 mW/°C
Collector-emitter breakdown voltage	30 V
Emitter-collector breakdown voltage	7 V
Collector-base breakdown voltage	70 V

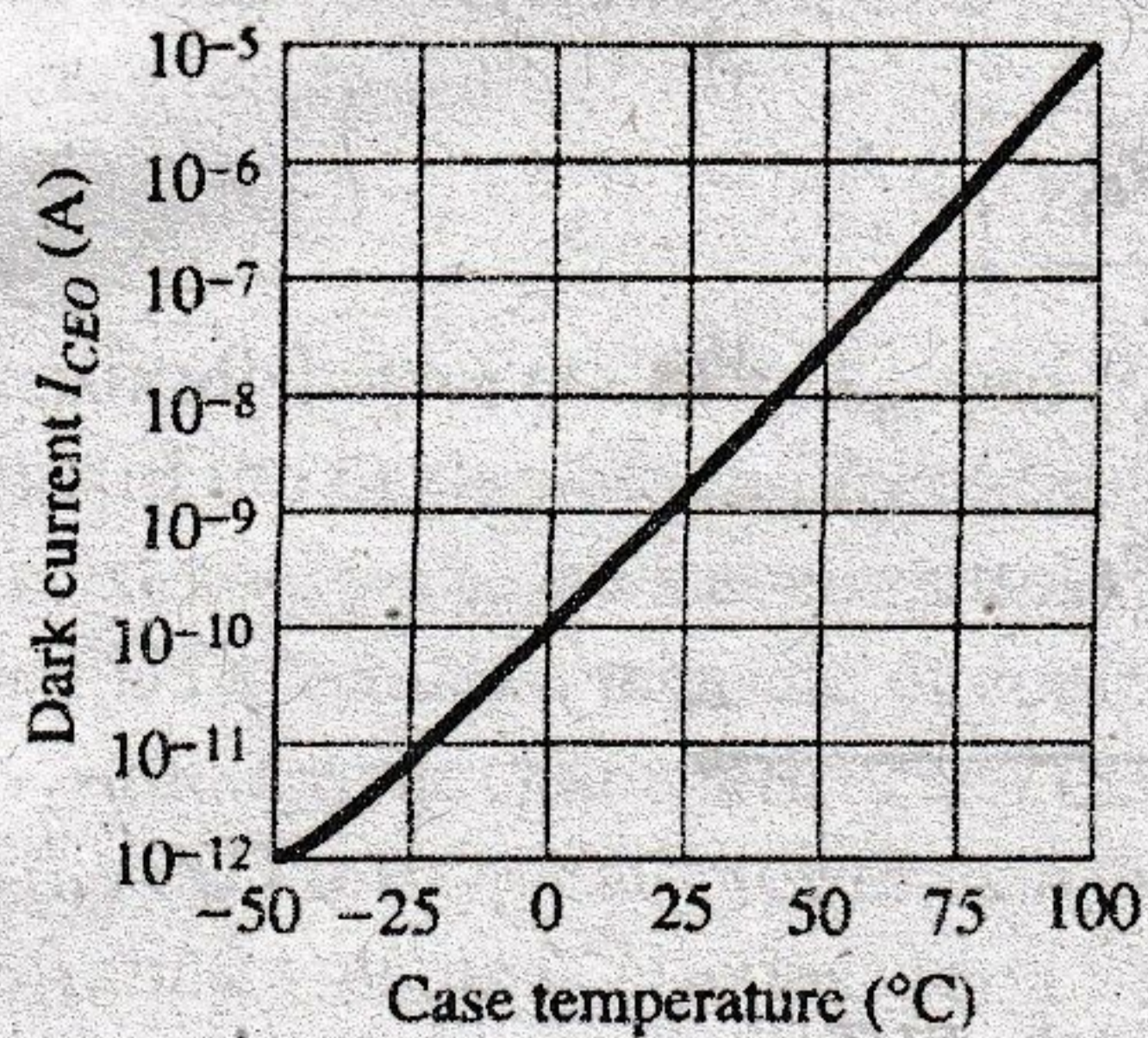
### Electrical Characteristics per Channel (at 25°C Ambient)

Parameter	Min.	Typ.	Max.	Unit	Test Conditions
Gallium arsenide LED					
Forward voltage		1.3	1.5	V	$I_F = 60 \text{ mA}$
Reverse current		0.1	10	$\mu\text{A}$	$V_R = 3.0 \text{ V}$
Capacitance		100		pF	$V_R = 0 \text{ V}$
Phototransistor detector					
$BV_{CEO}$	30			V	$I_C = 1 \text{ mA}$
$I_{CEO}$		5.0	50	nA	$V_{CE} = 10 \text{ V}, I_F = 0 \text{ A}$
Collector-emitter capacitance		2.0		pF	$V_{CE} = 0 \text{ V}$
$BV_{ECO}$	7			V	$I_E = 100 \mu\text{A}$
Coupled characteristics					
dc current transfer ratio	0.2	0.35			$I_F = 10 \text{ mA}, V_{CE} = 10 \text{ V}$
Capacitance, input to output		0.5		pF	
Breakdown voltage	2500			V	DC
Resistance, input to output		100		G $\Omega$	
$V_{sat}$			0.5	V	$I_C = 1.6 \text{ mA}, I_F = 16 \text{ mA}$
Propagation delay					
$t_{on}$		6.0		$\mu\text{s}$	$R_L = 2.4 \text{ k}\Omega, V_{CE} = 5 \text{ V}$
$t_{D off}$		25		$\mu\text{s}$	$I_F = 16 \text{ mA}$

**FIG. 17.53**

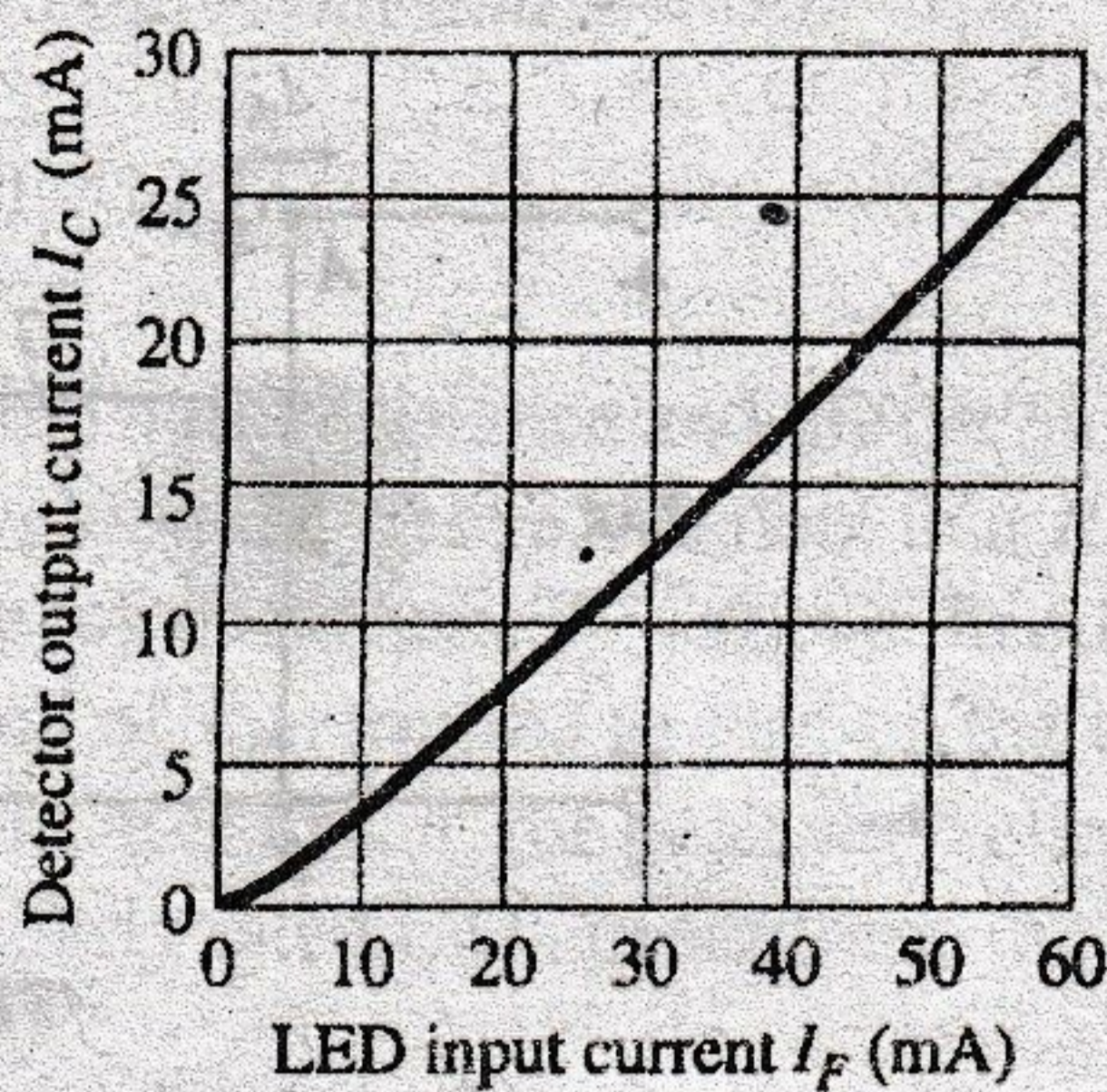
Opto-isolator characteristics.

The typical optoelectronic characteristic curves for each channel are provided in Figs. 17.54 through 17.58. Note the very pronounced effect of temperature on the output current at low temperatures but the fairly level response at or above room temperature (25°C). As mentioned earlier, the level of  $I_{CEO}$  is improving steadily with improved design and construction techniques (the lower the better). In Fig. 17.54, we do not reach 1  $\mu\text{A}$  until the temperature rises above 75°C. The transfer characteristics of Fig. 17.55 compare the input LED current (which establishes the luminous flux) to the resulting collector current of the output transistor (whose base current is determined by the incident flux). In fact, Fig. 17.56 demonstrates that the  $V_{CE}$  voltage affects the resulting collector current only very slightly. It is interesting to note in Fig. 17.57 that the switching time of an opto-isolator decreases with increased current, whereas for many devices it is exactly the reverse. Consider that it is only 2  $\mu\text{s}$  for a collector current of 6 mA and a load  $R_L$  of 100  $\Omega$ . The relative output versus temperature appears in Fig. 17.58.



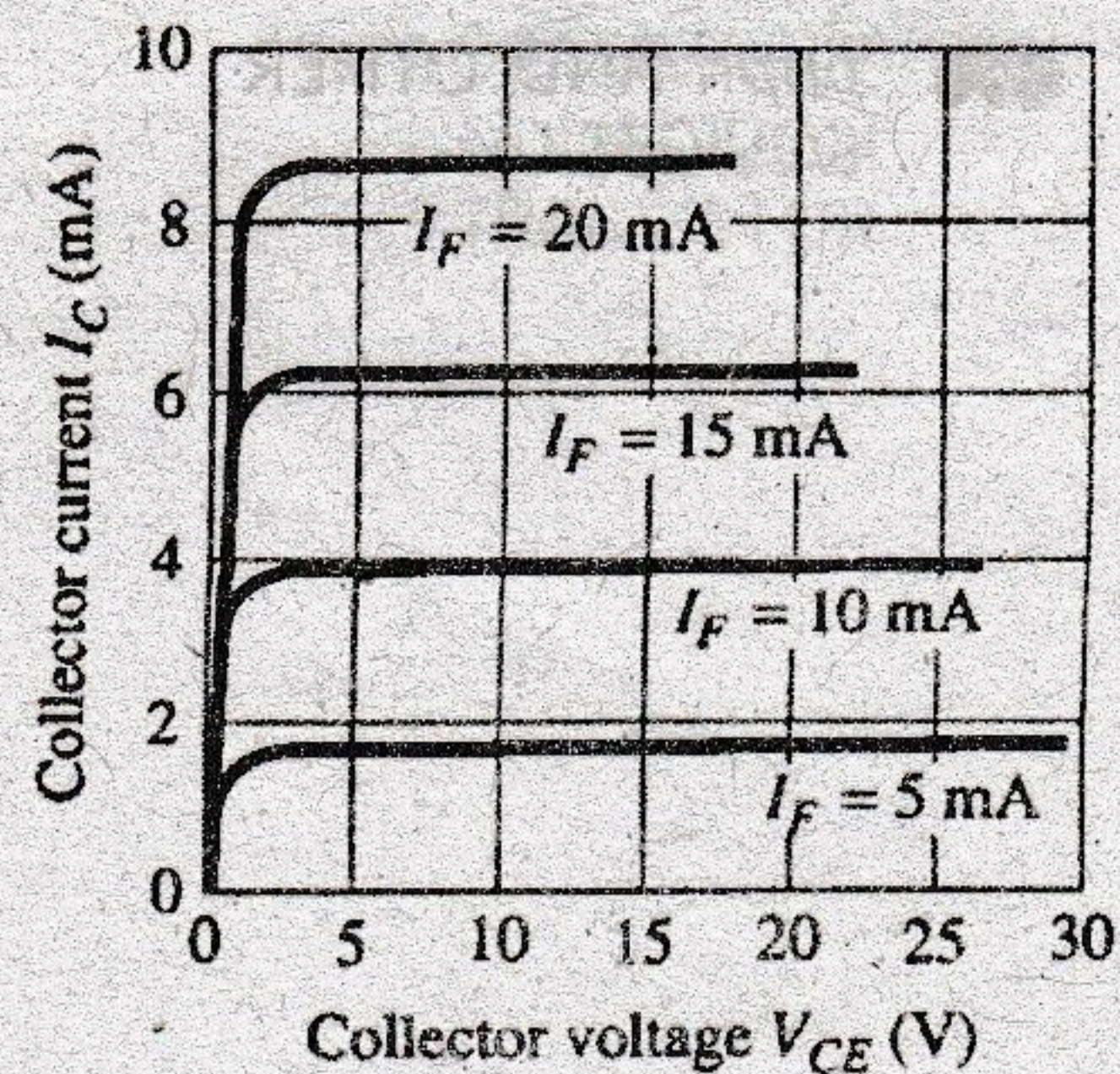
**FIG. 17.54**

Dark current  $I_{CEO}$  versus temperature.



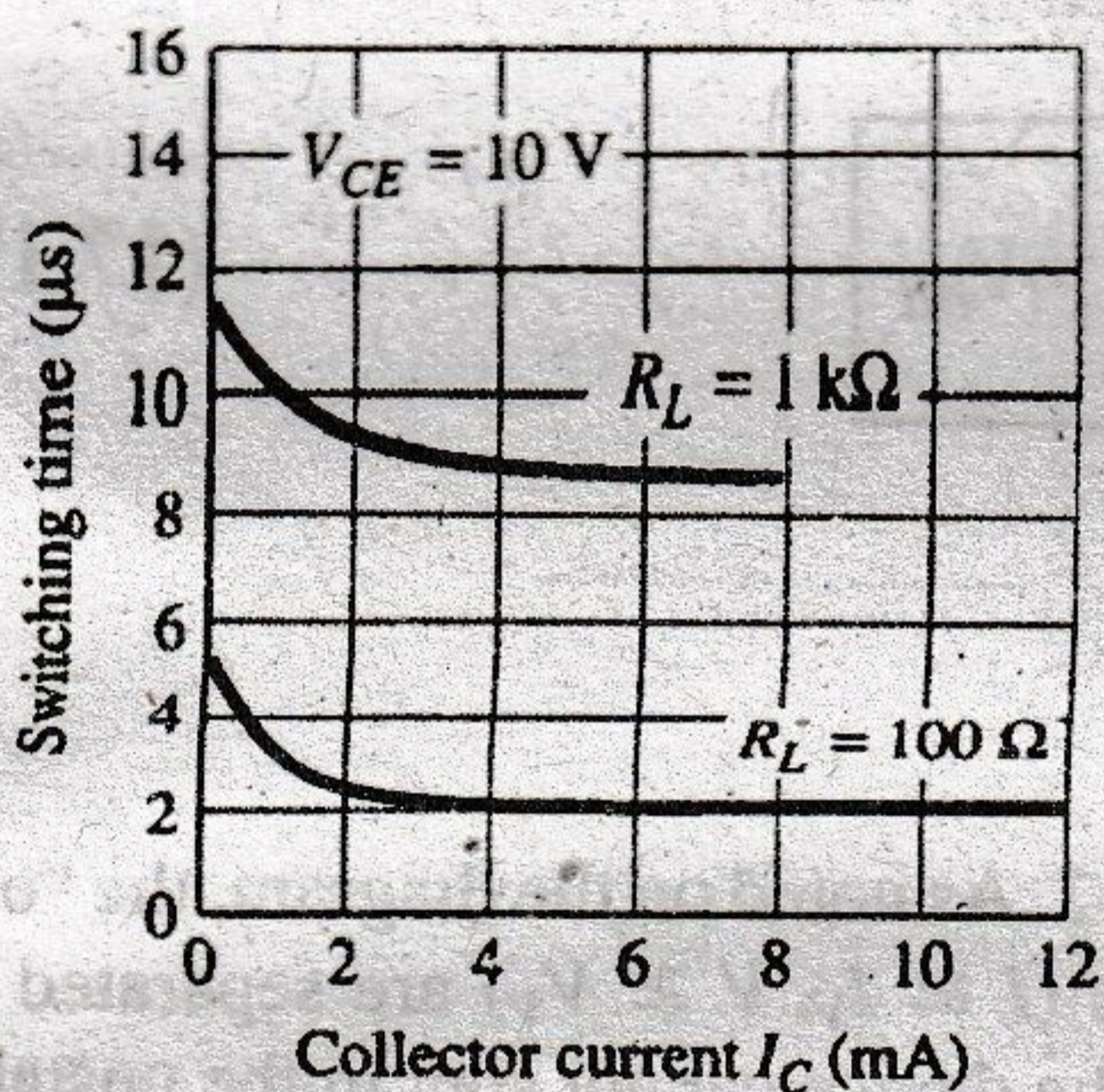
**FIG. 17.55**

Transfer characteristics.



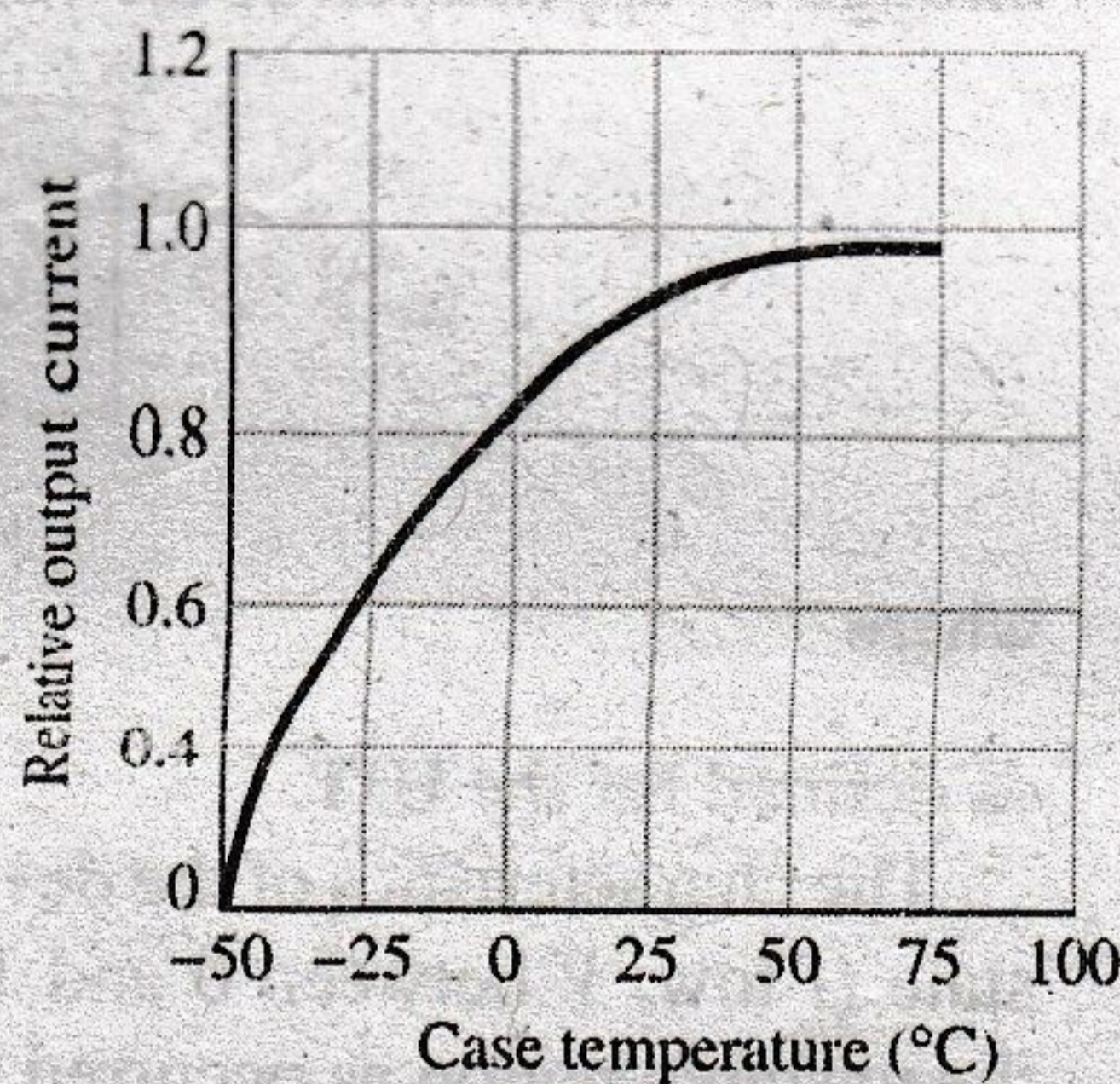
**FIG. 17.56**

Detector output characteristics.



**FIG. 17.57**

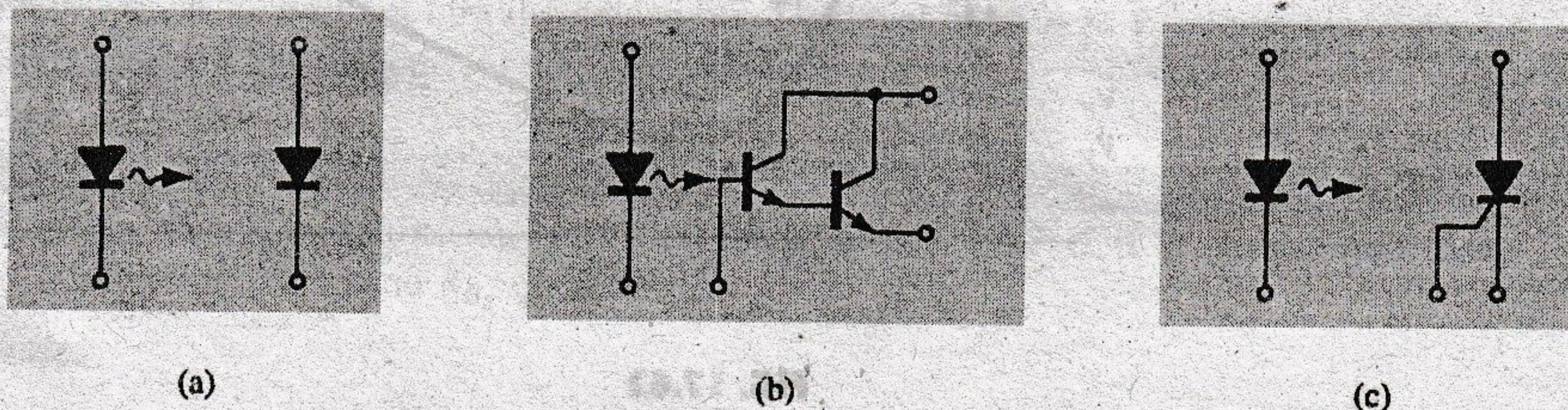
Switching time versus collector current.



**FIG. 17.58**

Relative output versus temperature.

The schematic representation for a transistor coupler appears in Fig. 17.52. The schematic representations for a photodiode, a photo-Darlington, and a photo-SCR opto-isolator appear in Fig. 17.59.



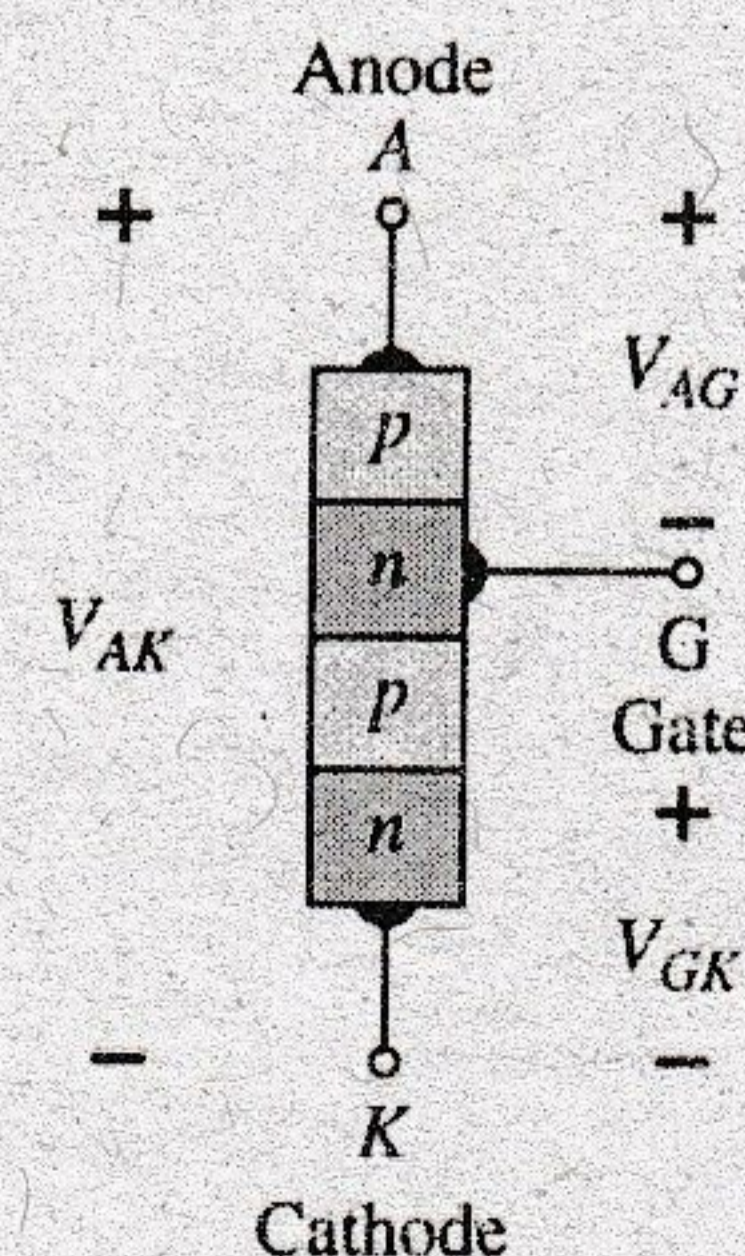
**FIG. 17.59**

Opto-isolators: (a) photodiode; (b) photo-Darlington; (c) photo-SCR.

### 17.15 PROGRAMMABLE UNIJUNCTION TRANSISTOR

Although there is a similarity in name, the actual construction and mode of operation of the programmable unijunction transistor (PUT) are quite different from those of the unijunction transistor. The fact that the  $I$ - $V$  characteristics and applications of each are similar prompted the choice of labels.

As indicated in Fig. 17.60, the PUT is a four-layer  $pnpn$  device with a gate connected directly to the sandwiched  $n$ -type layer. The symbol for the device and the basic biasing arrangement appear in Fig. 17.61. As the symbol suggests, it is essentially an SCR with



**FIG. 17.60**

Programmable UJT (PUT).



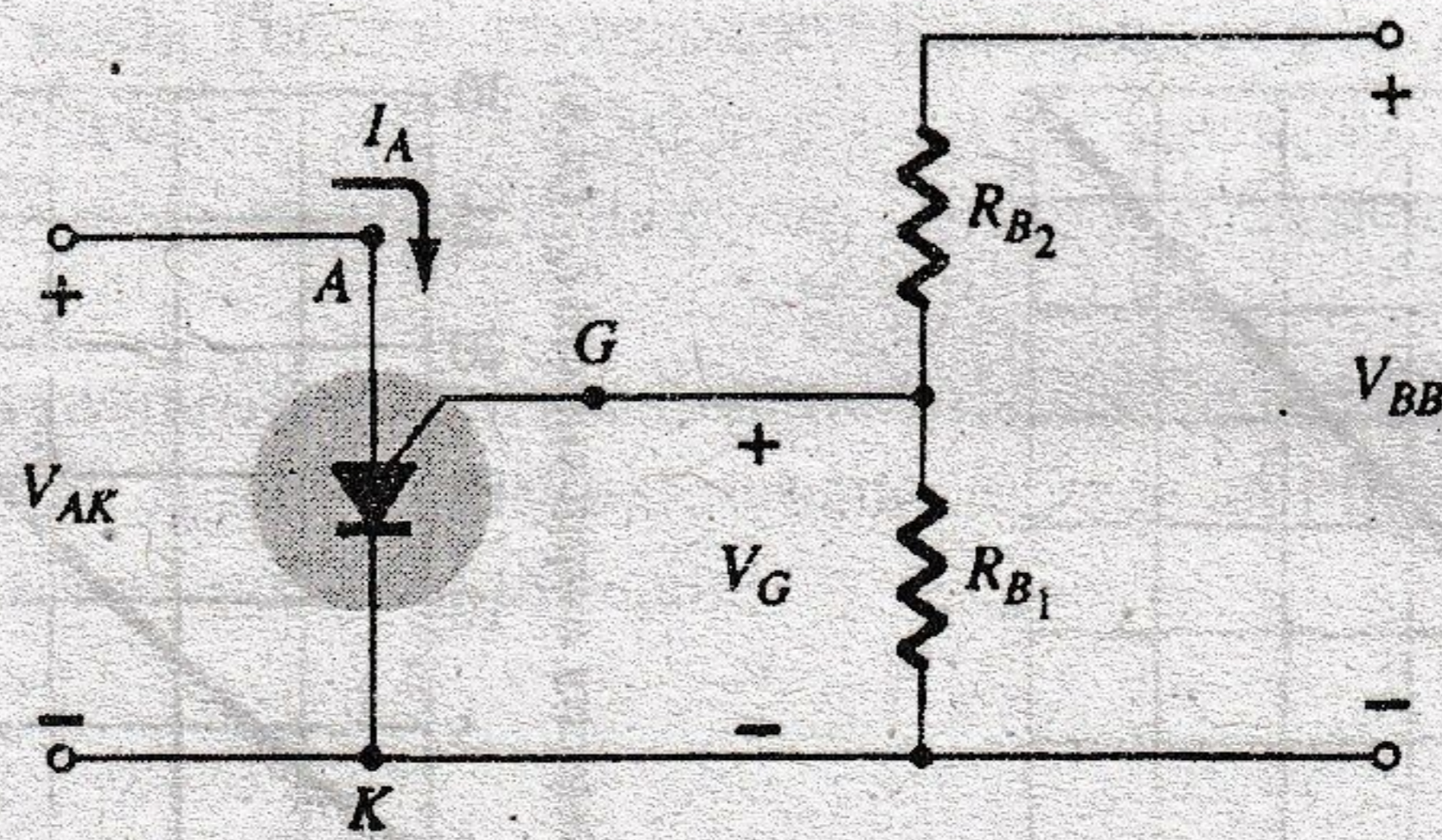


FIG. 17.61

Basic biasing arrangement for the PUT.

a control mechanism that permits a duplication of the characteristics of the typical SCR. The term *programmable* is applied because  $R_{BB}$ ,  $\eta$ , and  $V_P$  as defined for the UJT can be controlled through the resistors  $R_{B1}$ ,  $R_{B2}$ , and the supply voltage  $V_{BB}$ . Note in Fig. 17.61 that through an application of the voltage-divider rule, when  $I_G = 0$ ,

$$V_G = \frac{R_{B1}}{R_{B1} + R_{B2}} V_{BB} = \eta V_{BB} \quad (17.19)$$

where

$$\eta = \frac{R_{B1}}{R_{B1} + R_{B2}}$$

as defined for the UJT.

The characteristics of the device appear in Fig. 17.62. As noted on the diagram, the “off” state ( $I$  low,  $V$  between 0 and  $V_P$ ) and the “on” state ( $I \geq I_V$ ,  $V \geq V_V$ ) are separated by the unstable region as occurred for the UJT. That is, the device cannot stay in the unstable state—it will simply shift to either the “off” or the “on” stable state.

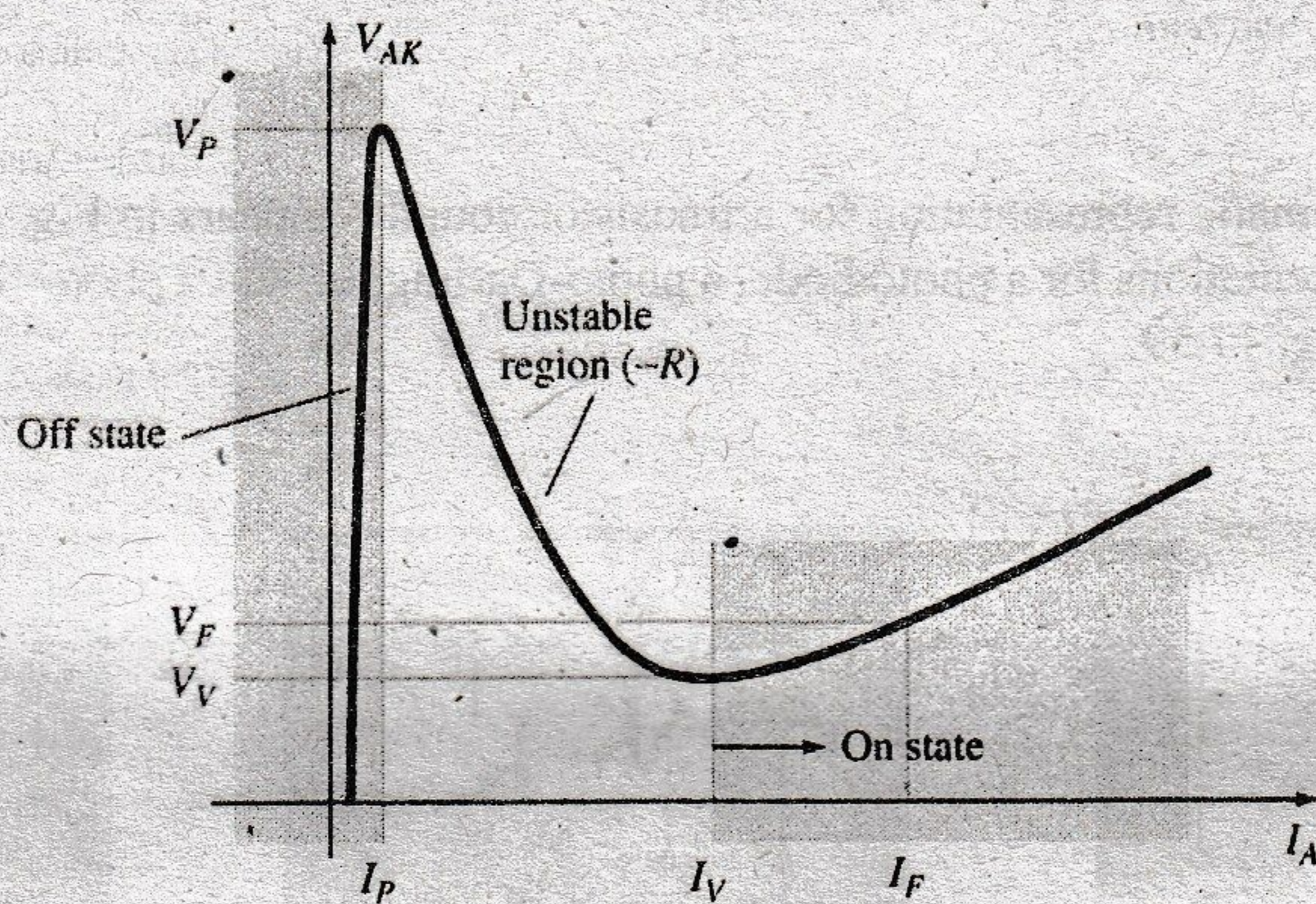


FIG. 17.62

PUT characteristics.

The firing potential  $V_P$ , or voltage necessary to “fire” the device, is given by

$$V_P = \eta V_{BB} + V_D \quad (17.20)$$

as defined for the UJT. However,  $V_P$  represents the voltage drop  $V_{AK}$  in Fig. 17.60 (the forward voltage drop across the conducting diode). For silicon,  $V_D$  is typically 0.7 V. Therefore,

$$\begin{aligned} V_{AK} &= V_{AG} + V_{GK} \\ V_P &= V_D + V_G \end{aligned}$$

and

$$V_P = \eta V_{BB} + 0.7 \text{ V} \quad \text{silicon} \quad (17.21)$$

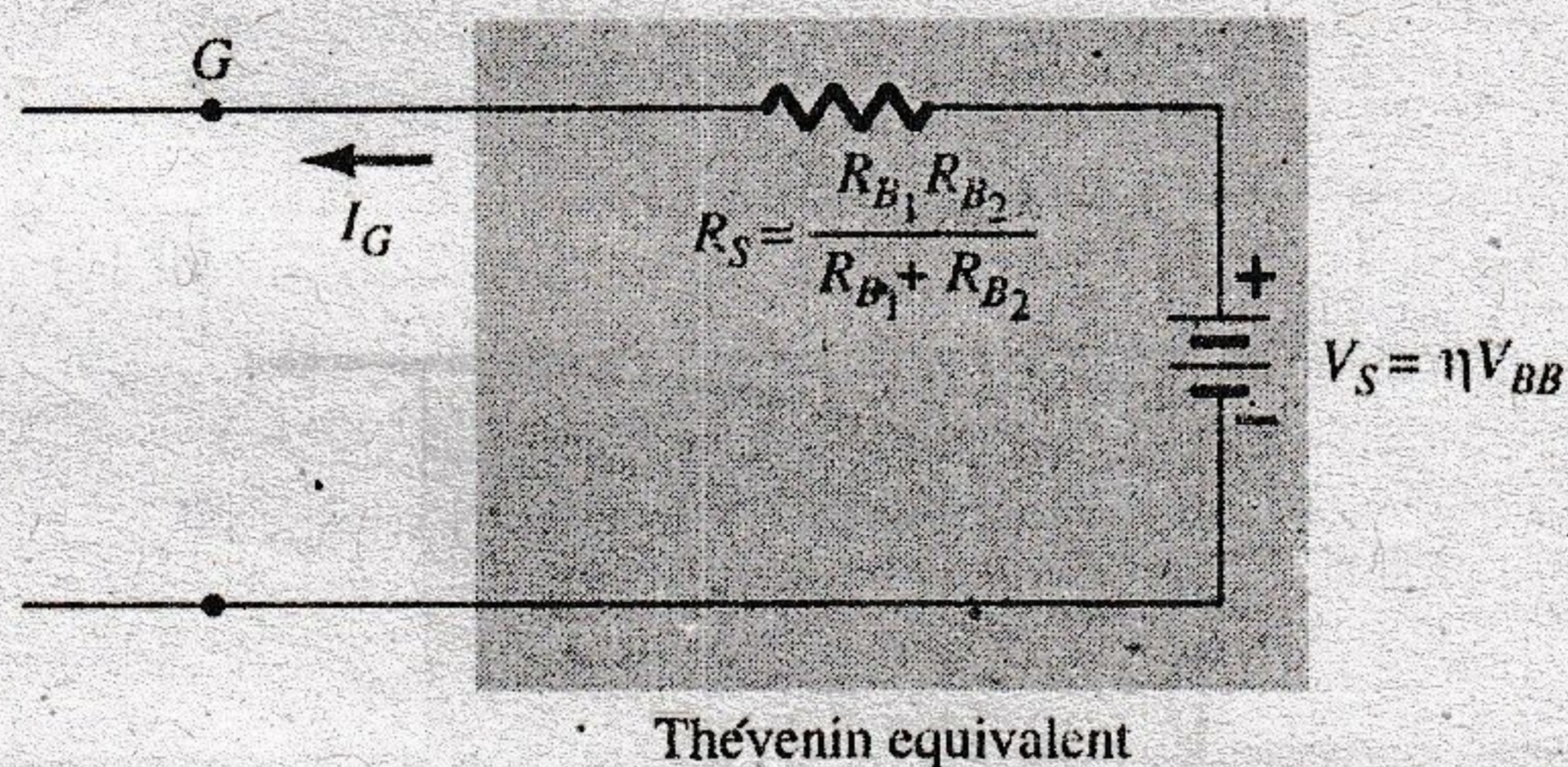
We noted above, however, that  $V_G = \eta V_{BB}$ , with the result that

$$\boxed{V_P = V_G + 0.7} \quad \text{silicon} \quad (17.22)$$

Recall that for the UJT,  $R_{B_1}$  and  $R_{B_2}$  represent the bulk resistance and the ohmic base contacts of the device—both inaccessible. In the development above, we note that  $R_{B_1}$  and  $R_{B_2}$  are external to the device, permitting an adjustment of  $\eta$  and hence  $V_G$  above. In other words, the PUT provides a measure of control on the level of  $V_P$  required to turn on the device.

Although the characteristics of the PUT and UJT are similar, the peak and valley currents of the PUT are typically lower than those of a similarly rated UJT. In addition, the minimum operating voltage is also less for a PUT.

If we take a Thévenin equivalent of the network to the right of the gate terminal in Fig. 17.61, the network of Fig. 17.63 results. The resulting resistance  $R_S$  is important because it is often included in specification sheets since it affects the level of  $I_V$ .



**FIG. 17.63**

*Thévenin equivalent for the network to the right of the gate terminal in Fig. 17.61.*

The basic operation of the device can be reviewed through reference to Fig. 17.62. A device in the “off” state will not change state until the voltage  $V_P$  as defined by  $V_G$  and  $V_D$  is reached. The level of current until  $I_P$  is reached is very low, resulting in an open-circuit equivalent since  $R = V(\text{high})/I(\text{low})$  will result in a high resistance level. When  $V_P$  is reached, the device will switch through the unstable region to the “on” state, where the voltage is lower but the current higher, resulting in a terminal resistance  $R = V(\text{low})/I(\text{high})$ , which is quite small, representing a short-circuit equivalent on an approximate basis. The device has therefore switched from essentially an open-circuit to a short-circuit state at a point determined by the choice of  $R_{B_1}$ ,  $R_{B_2}$ , and  $V_{BB}$ . Once the device is in the “on” state, the removal of  $V_G$  will not turn the device off. The level of voltage  $V_{AK}$  must be dropped sufficiently to reduce the current below a holding level.

**EXAMPLE 17.2** Determine  $R_{B_1}$  and  $V_{BB}$  for a silicon PUT if it is determined that  $\eta = 0.8$ ,  $V_P = 10.3$  V, and  $R_{B_2} = 5$  k $\Omega$ .

**Solution:**

$$\text{Eq. (17.4): } \eta = \frac{R_{B_2}}{R_{B_1} + R_{B_2}} = 0.8$$

$$R_{B_1} = 0.8(R_{B_1} + R_{B_2})$$

$$0.2R_{B_1} = 0.8R_{B_2}$$

$$R_{B_1} = 4R_{B_2}$$

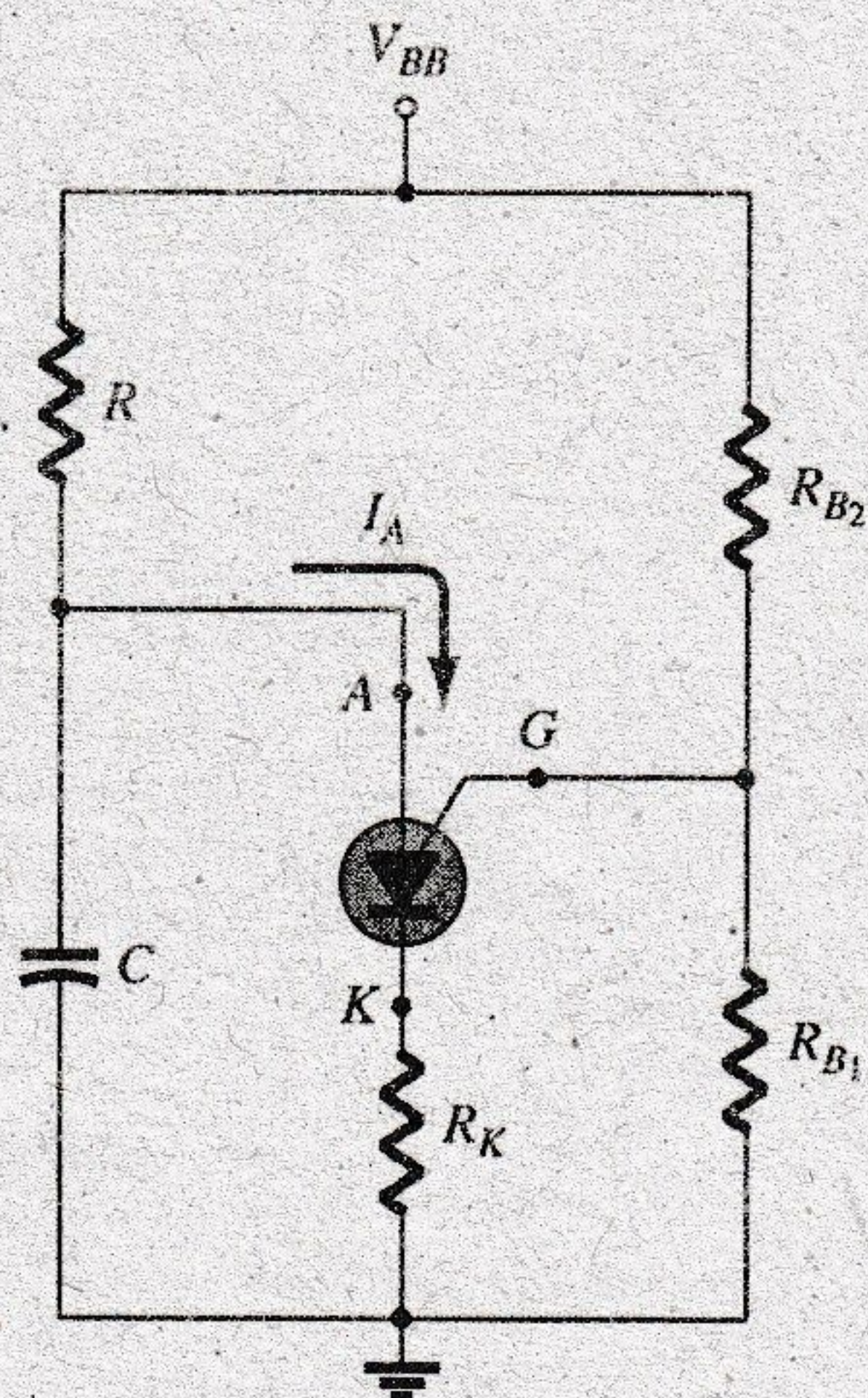
$$R_{B_1} = 4(5 \text{ k}\Omega) = 20 \text{ k}\Omega$$

$$\text{Eq. (17.20): } V_P = \eta V_{BB} + V_D$$

$$10.3 \text{ V} = (0.8)(V_{BB}) + 0.7 \text{ V}$$

$$9.6 \text{ V} = 0.8V_{BB}$$

$$V_{BB} = 12 \text{ V}$$



**FIG. 17.64**  
PUT relaxation oscillator.

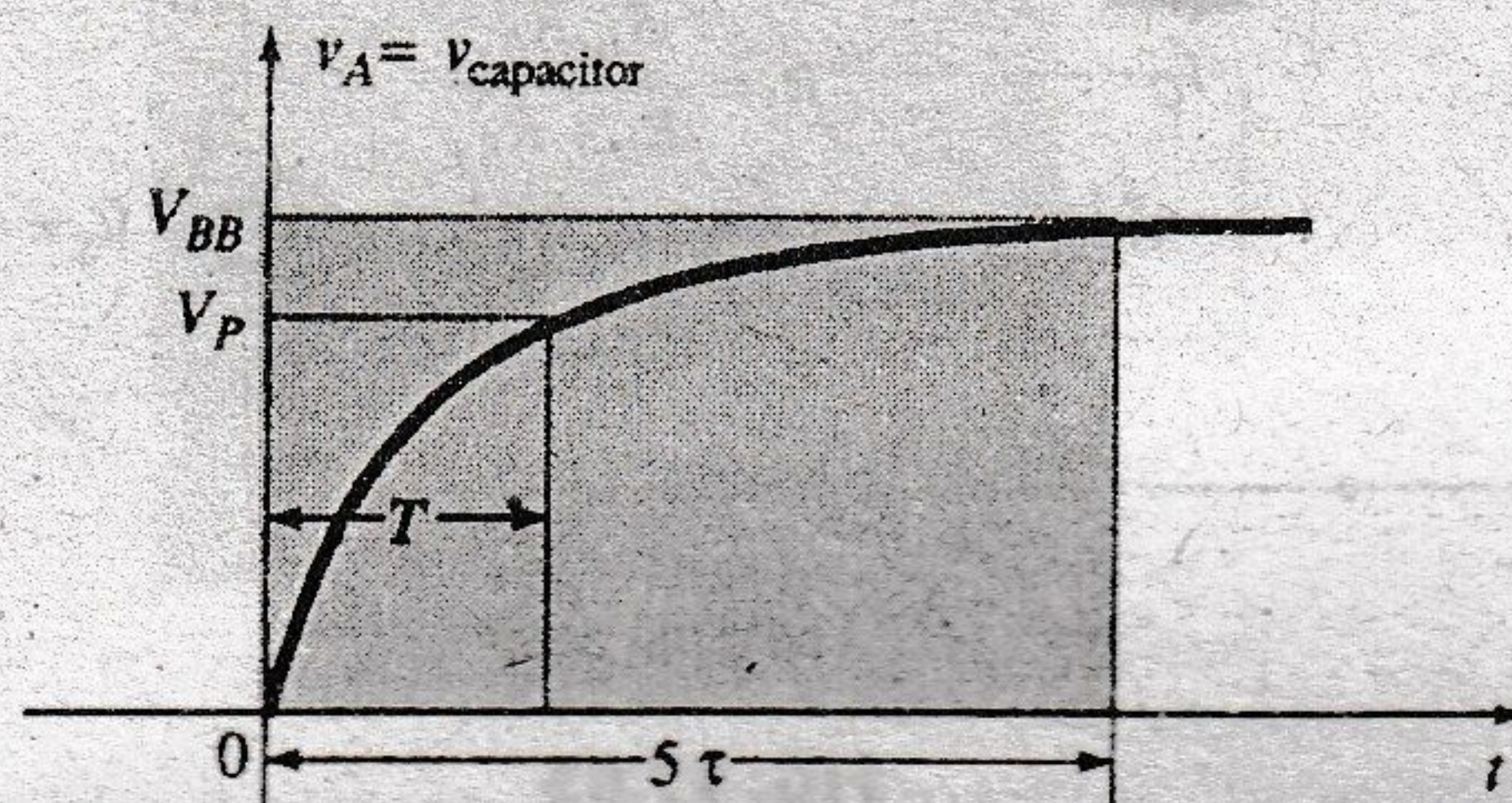
## Relaxation Oscillator

One popular application of the PUT is in the relaxation oscillator of Fig. 17.64. The instant the supply is connected, the capacitor will begin to charge toward  $V_{BB}$  volts since there is no anode current at this point. The charging curve appears in Fig. 17.65. The period  $T$  required to reach the firing potential  $V_P$  is given approximately by

$$T \cong RC \log_e \frac{V_{BB}}{V_{BB} - V_P} \quad (17.23)$$

or, when  $V_P \cong \eta V_{BB}$ ,

$$T \cong RC \log_e \left( 1 + \frac{R_{B1}}{R_{B2}} \right) \quad (17.24)$$



**FIG. 17.65**

Charging wave for the capacitor  $C$  of Fig. 17.64.

The instant the voltage across the capacitor equals  $V_P$ , the device will fire and a current  $I_A = I_P$  will be established through the PUT. If  $R$  is too large, the current  $I_P$  cannot be established and the device will not fire. At the point of transition,

$$I_P R = V_{BB} - V_P$$

and

$$R_{\max} = \frac{V_{BB} - V_P}{I_P} \quad (17.25)$$

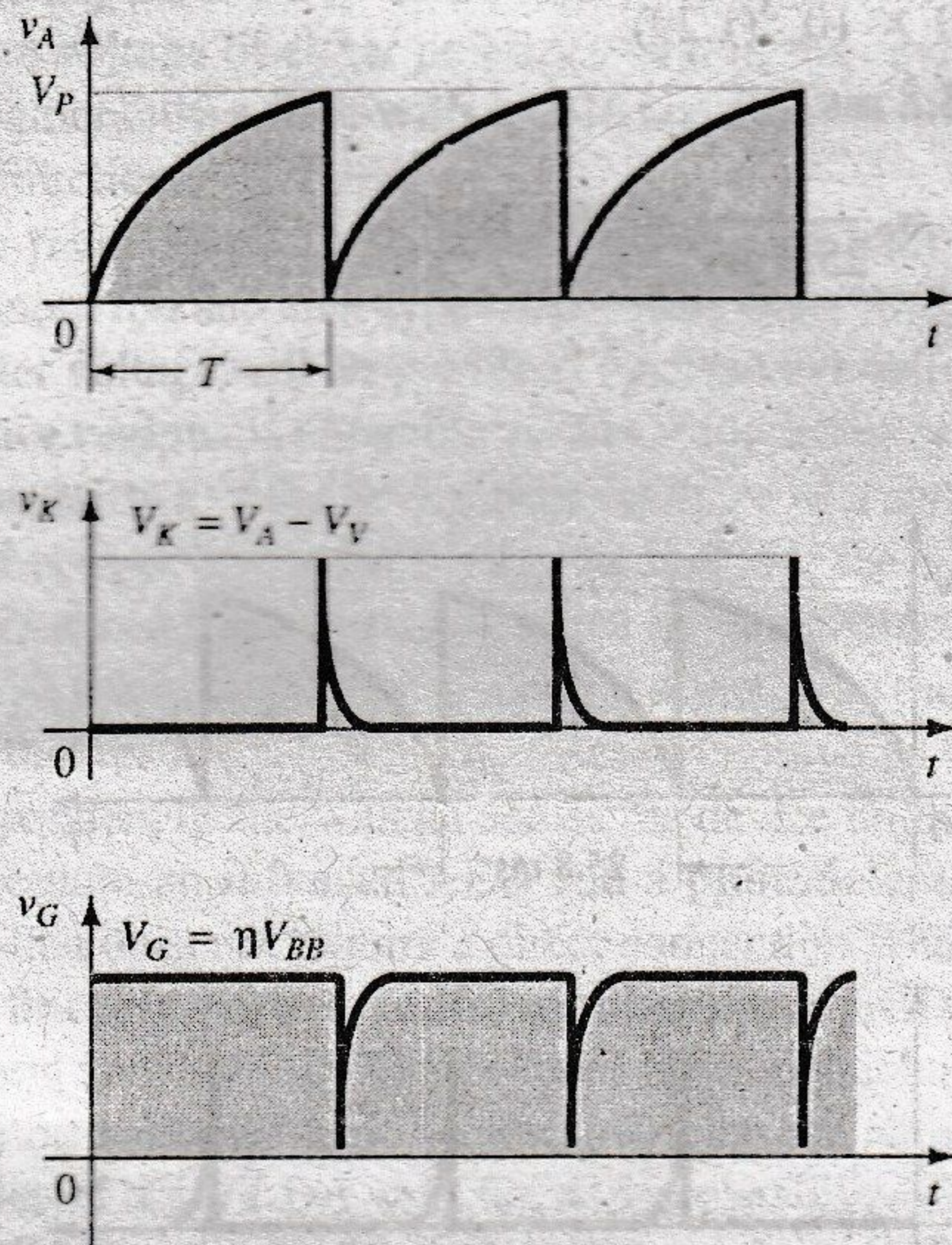
The subscript is included to indicate that any  $R$  greater than  $R_{\max}$  will result in a current less than  $I_P$ . The level of  $R$  must also be such as to ensure it is less than  $I_V$  if oscillations are to occur. In other words, we want the device to enter the unstable region and then return to the "off" state. From reasoning similar to that above, we obtain

$$R_{\min} = \frac{V_{BB} - V_V}{I_V} \quad (17.26)$$

The discussion above requires that  $R$  be limited to the following for an oscillatory system:

$$R_{\min} < R < R_{\max}$$

The waveforms of  $v_A$ ,  $v_G$ , and  $v_K$  appear in Fig. 17.66. Note that  $T$  determines the maximum voltage that  $v_A$  can charge to. Once the device fires, the capacitor will rapidly discharge through the PUT and  $R_K$ , producing the drop shown. Of course,  $v_K$  will peak at the same time due to the brief but heavy current. The voltage  $v_G$  will rapidly drop from  $V_G$  to a level just greater than 0 V. When the capacitor voltage drops to a low level, the PUT will once again turn off and the charging cycle will be repeated. The effect on  $V_G$  and  $V_K$  is shown in Fig. 17.66.


**FIG. 17.66**

Waveforms for PUT oscillator of Fig. 17.64.

**EXAMPLE 17.3** For the network of Fig. 17.64, if  $V_{BB} = 12\text{ V}$ ,  $R = 20\text{ k}\Omega$ ,  $C = 1\text{ }\mu\text{F}$ ,  $R_K = 100\text{ }\Omega$ ,  $R_{B1} = 10\text{ k}\Omega$ ,  $R_{B2} = 5\text{ k}\Omega$ ,  $I_P = 100\text{ }\mu\text{A}$ ,  $V_V = 1\text{ V}$ , and  $I_V = 5.5\text{ mA}$ , determine:

- $V_P$ .
- $R_{\text{max}}$  and  $R_{\text{min}}$ .
- $T$  and frequency of oscillation.
- The waveforms of  $v_A$ ,  $v_G$ , and  $v_K$ .

**Solution:**

a. Eq. (17.20):  $V_P = \eta V_{BB} + V_D$

$$\begin{aligned} &= \frac{R_{B1}}{R_{B1} + R_{B2}} V_{BB} + 0.7\text{ V} \\ &= \frac{10\text{ k}\Omega}{10\text{ k}\Omega + 5\text{ k}\Omega} (12\text{ V}) + 0.7\text{ V} \\ &= (0.67)(12\text{ V}) + 0.7\text{ V} = \mathbf{8.7\text{ V}} \end{aligned}$$

b. From Eq. (17.25):  $R_{\text{max}} = \frac{V_{BB} - V_P}{I_P}$

$$\begin{aligned} &= \frac{12\text{ V} - 8.7\text{ V}}{100\text{ }\mu\text{A}} = \mathbf{33\text{ k}\Omega} \end{aligned}$$

From Eq. (17.26):  $R_{\text{min}} = \frac{V_{BB} - V_V}{I_V}$

$$\begin{aligned} &= \frac{12\text{ V} - 1\text{ V}}{5.5\text{ mA}} = \mathbf{2\text{ k}\Omega} \end{aligned}$$

$$R: 2\text{ k}\Omega < 20\text{ k}\Omega < 33\text{ k}\Omega$$

c. Eq. (17.23):  $T = RC \log_e \frac{V_{BB}}{V_{BB} - V_P}$

$$\begin{aligned} &= (20\text{ k}\Omega)(1\text{ }\mu\text{F}) \log_e \frac{12\text{ V}}{12\text{ V} - 8.7\text{ V}} \\ &= 20 \times 10^{-3} \log_e (3.64) \end{aligned}$$

$$= 20 \times 10^{-3}(1.29)$$

$$= 25.8 \text{ ms}$$

$$f = \frac{1}{T} = \frac{1}{25.8 \text{ ms}} = 38.8 \text{ Hz}$$

d. Indicated in Fig. 17.67.

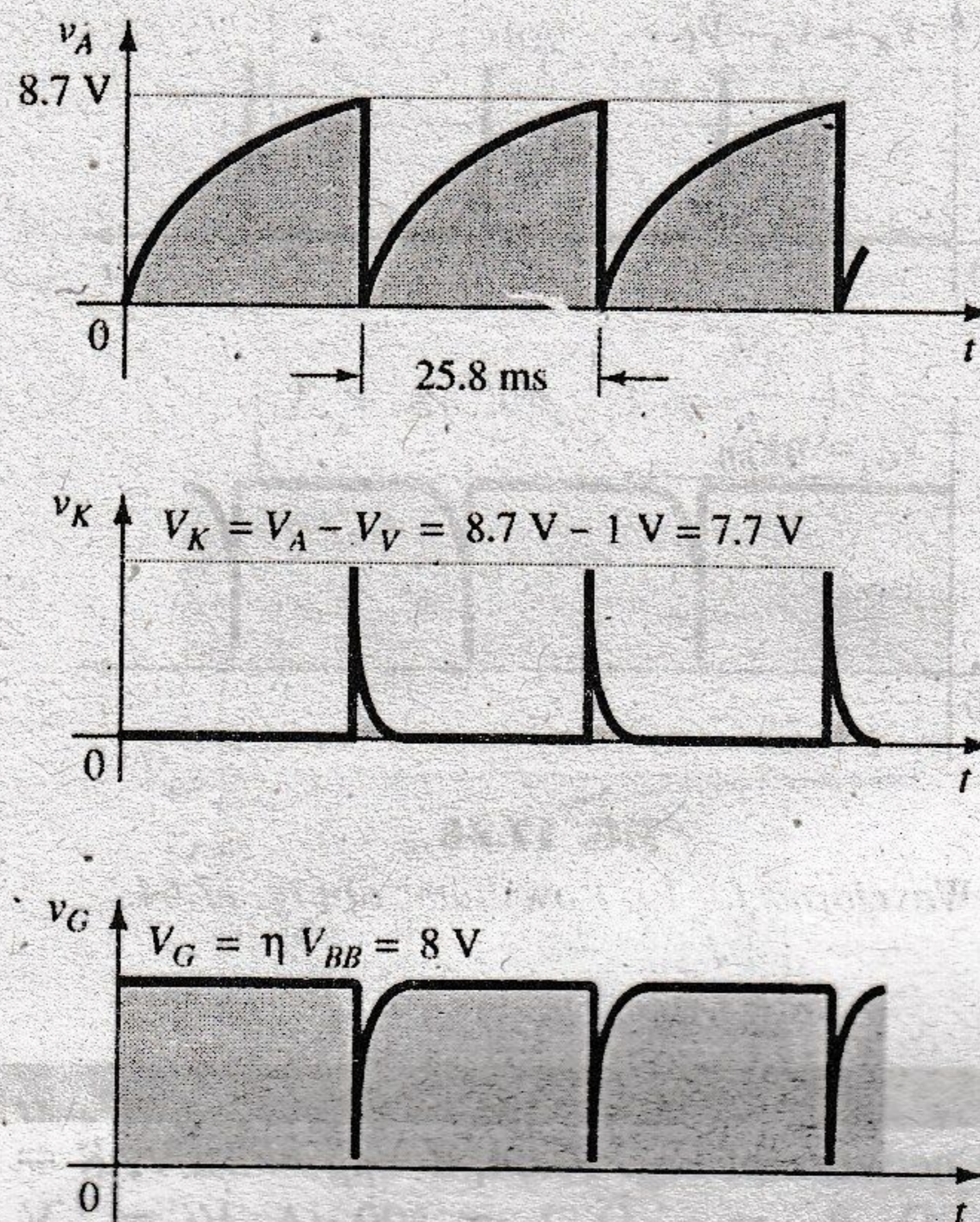


FIG. 17.67

Waveforms for the oscillator of Example 17.3.

## 17.16 SUMMARY

### Important Conclusions and Concepts

1. The **silicon-controlled rectifier (SCR)** is a rectifier whose state is **controlled by the magnitude of the gate current**. The forward-bias voltage across the device will determine the level of gate current required to “fire” (turn on) the device. The **higher** the level of biasing voltage, the **less** is the required gate current.
2. In addition to gate triggering, an SCR can be **turned on with zero gate current** simply by applying **sufficient voltage** across the device. The higher the gate current, however, the less is the required biasing voltage to turn the SCR on.
3. The **silicon-controlled switch** has both an **anode gate** and a **cathode gate** for controlling the state of the device, although the anode gate is now connected to an *n*-type layer and the cathode gate to a *p*-type layer. The result is that a **negative pulse at the anode gate will turn the device on**, whereas a **positive pulse will turn it off**. The reverse is true for the cathode gate.
4. A **gate turn-off switch (GTO)** looks similar in construction to the SCR with only **one gate connection**, but the GTO has the added advantage of being able to turn the device **off and on** at the gate terminal. However, this added option of being able to turn the device off at the gate results in a much **higher gate current** to turn the device on.
5. The **LASCR** is a light-activated SCR whose state can be controlled by **light falling on a semiconductor layer** of the device or by **triggering the gate terminal** in a manner described for SCRs. The higher the junction temperature of the device, the less is the required incident light to turn the device on.
6. The **Shockley diode** has essentially the **same characteristics as an SCR with zero gate current**. It is turned on by simply increasing the forward-bias voltage across the device beyond the breakover level.

7. The **diac** is essentially a **Shockley diode that can fire in either direction**. The application of sufficient voltage of either polarity will turn the device on.
8. The **triac** is fundamentally a **diac with a gate terminal to control the action of the device** in either direction.
9. The **unijunction transistor** is a three-terminal device with a  $p-n$  junction formed between an aluminum rod and an  $n$ -type silicon slab. Once the emitter firing potential is reached, the emitter voltage will drop with an increase in emitter current, establishing a **negative-resistance region** excellent for oscillator applications. Once the valley point is reached, the characteristics of the device **take on those of a semiconductor diode**. The higher the applied voltage across the device, the higher is the emitter firing potential.
10. The **phototransistor** is a three-terminal device having characteristics **very similar to those of a BJT** with a base and collector current sensitive to the incident light intensity. The base current that results is essentially **linearly related to the applied light** with a level almost independent of the voltage across the device until breakdown results.
11. **Opto-isolators** contain an **infrared LED** and a **photodetector** to provide a linkage between systems that does not require a direct connection. The output detector current is **less than but linearly related to the applied input LED current**. Furthermore, the collector current is essentially independent of the collector-to-emitter voltage.
12. The **PUT** (programmable unijunction transistor) is, as the name implies, a device with the **characteristics of a UJT** but with the added capability of **being able to control the firing potential**. In general, the peak, valley, and minimum operating voltages of PUTs are less than those of UJTs.

### Equations

Diac:

$$V_{BR1} = V_{BR2} \pm 0.1V_{BR2}$$

UJT:

$$R_{BB} = (R_{B1} + R_{B2})|_{I_E=0}$$

$$V_{RB1} = \frac{R_{B1}}{R_{B1} + R_{B2}} \cdot V_{BB} = \eta V_{BB} \Big|_{I_E=0}$$

$$\eta = \frac{R_{B1}}{R_{BB}}$$

$$V_P = \eta V_{BB} + V_D$$

Phototransistor:

$$I_C \cong h_{fe} I_\lambda$$

PUT:

$$V_G = \frac{R_{B1}}{R_{B1} + R_{B2}} \cdot V_{BB} = \eta V_{BB}$$

$$V_P = \eta V_{BB} + V_D$$

### PROBLEMS

\*Note: Asterisks indicate more difficult problems.

#### 17.3 Basic Silicon-Controlled Rectifier Operation

1. Describe in your own words the basic behavior of the SCR using the two-transistor equivalent circuit.
2. Describe two techniques for turning an SCR off.
3. Consult a manufacturer's manual or specification sheet and obtain a turn-off network. If possible, describe the turn-off action of the design.

#### 17.4 SCR Characteristics and Ratings

- \*4. a. At high levels of gate current, the characteristics of an SCR approach those of what two-terminal device?

- b. At a fixed anode-to-cathode voltage less than  $V_{(BR)F}$ , what is the effect on the firing of the SCR as the gate current is reduced from its maximum value to the zero level?
  - c. At a fixed gate current greater than  $I_G = 0$ , what is the effect on the firing of the SCR as the gate voltage is reduced from  $V_{(BR)F}$ ?
  - d. For increasing levels of  $I_G$ , what is the effect on the holding current?
5.
    - a. Based on Fig. 17.8, will a gate current of 50 mA fire the device at room temperature (25°C)?
    - b. Repeat part (a) for a gate current of 10 mA.
    - c. Will a gate voltage of 2.6 V trigger the device at room temperature?
    - d. Is  $V_G = 6$  V,  $I_G = 800$  mA a good choice for firing conditions? Would  $V_G = 4$  V,  $I_G = 1.6$  A be preferred? Explain.

### 17.5 SCR Applications

6. In Fig. 17.10b, why is there very little loss in potential across the SCR during conduction?
7. Fully explain why reduced values of  $R_1$  in Fig. 17.11 will result in an increased angle of conduction.
- \*8. Refer to the charging network of Fig. 17.12.
  - a. Determine the dc level of the full-wave rectified signal if a 1:1 transformer is employed.
  - b. If the battery in its uncharged state is sitting at 11 V, what is the anode-to-cathode voltage drop across SCR<sub>1</sub>?
  - c. What is the maximum possible value of  $V_R$  ( $V_{GK} \cong 0.7$  V)?
  - d. At the maximum value of part (c), what is the gate potential of SCR<sub>2</sub>?
  - e. Once SCR<sub>2</sub> has entered the short-circuit state, what is the level of  $V_2$ ?
9. Refer to the temperature controller of Fig. 17.13.
  - a. Sketch the waveform of the full-wave rectified waveform across the SCR.
  - b. What is the peak current through the heater when the SCR is "on" and has a short-circuit equivalent between anode and cathode? Assume each diode has a drop of 0.7 V when conducting.
  - c. When the SCR is on, what is the maximum current through the thermostat?
  - d. What is the total time for the rise time of the positive pulse of the applied ac voltage from 0 V to the maximum voltage of the rectified signal?
  - e. What is the time constant of the capacitor that is charging during the same period of part (d)? How do they compare? Why is this a concern?
  - f. What is the state of the SCR during this charging period? Why?
  - g. If the gate-firing potential is 40 V, what is the time period between successive triggering of the SCR?
  - h. Once the thermostat reaches its set temperature and assumes the short-circuit state, how will the SCR react?
  - i. What method was used to turn the SCR off: anode current interruption or forced commutation?
10. Refer to the emergency-lighting system of Fig. 17.14.
  - a. Sketch the waveform of the full-wave rectified signal across the bulb using a drop of 0.7 V during conduction of each diode.
  - b. Determine the peak voltage across the capacitor  $C_1$  when the SCR<sub>1</sub> is off.
  - c. What is the peak voltage across  $R_1$  during the charging phase if the battery voltage drops to 5 V?
  - d. What is the voltage across the lamp when the SCR turns on and the battery is fully charged at 6 V?
  - e. What is the current drawn from the battery if the lamp is dissipating 2 W of power?

### 17.6 Silicon-Controlled Switch

11. Fully describe in your own words the behavior of the networks of Fig. 17.16.
12. What is the suggested turn-off procedure for the network of Fig. 17.18?
13. For the network of Fig. 17.19
  - a. Write an equation for the voltage from gate to ground for the SCR.
  - b. What is the voltage  $V_{GK}$  when  $R_S = R'$ ?
  - c. Find  $R_S$  to establish a turn-on voltage of 2 V if  $R' = 10$  k $\Omega$ .
  - d. When the alarm turns on, what is the current through the relay?
  - e. At  $V_A = 0$  V, the maximum dc current through the rate-effect resistor will be established. What is its value?
  - f. When the reset button is activated, is there any reason for concern about spikes in voltage anywhere in the network? How could they be suppressed?

### 17.7 Gate Turn-Off Switch

14. a. In Fig. 17.22, if  $V_Z = 50$  V, determine the maximum possible value the capacitor  $C_1$  can charge to ( $V_{GK} \cong 0.7$  V).

- b. Determine the approximate discharge time ( $5\tau$ ) for  $R_3 = 20 \text{ k}\Omega$ .  
 c. Determine the internal resistance of the GTO if the rise time is one-half the decay period determined in part (b).

### 17.8 Light-Activated SCR

15. a. Using Fig. 17.24b, determine the minimum irradiance required to fire the device at room temperature ( $25^\circ\text{C}$ ).  
 b. What percentage reduction in irradiance is allowable if the junction temperature is increased from  $0^\circ\text{C}$  ( $32^\circ\text{F}$ ) to  $100^\circ\text{C}$  ( $212^\circ\text{F}$ )?

### 17.9 Shockley Diode

16. For the network of Fig. 17.28, if  $V_{BR} = 6 \text{ V}$ ,  $V = 40 \text{ V}$ ,  $R = 10 \text{ k}\Omega$ ,  $C = 0.2 \mu\text{F}$ , and  $V_{GK}$  (firing potential) =  $3 \text{ V}$ , determine the time period between energizing the network and the turning on of the SCR.

### 17.10 Diac

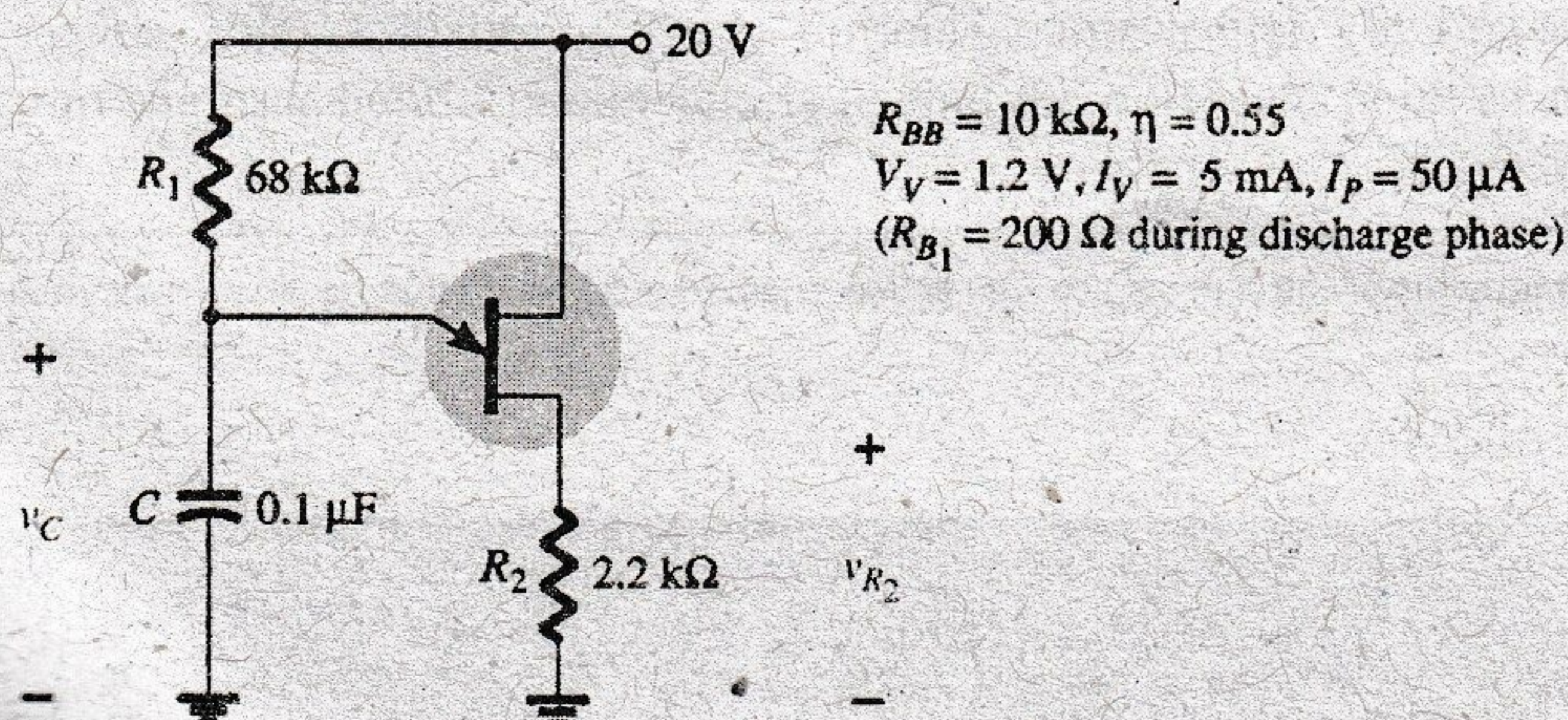
17. Using whatever reference you require, find an application of a diac and explain the network behavior.  
 18. If  $V_{BR_2}$  is  $6.4 \text{ V}$ , determine the range for  $V_{BR_1}$  using Eq. (17.1).  
 19. Find the level of human body capacitance  $C_b$  that would result in a  $45^\circ$ -degree phase shift between  $v_i$  and  $v_o$  for the network of Fig. 17.30.

### 17.11 Triac

20. For the network of Fig. 17.33, if  $C = 1 \mu\text{F}$ , find the level of  $R$  that will result in a 50% conduction period for the load in either direction if the turn-on voltage for the diac in either direction is  $12 \text{ V}$  and the applied sinusoidal signal has a peak value of  $170 \text{ V}$  ( $= 1.414 \times 120 \text{ V}$ ) at  $60 \text{ Hz}$ .

### 17.12 Unijunction Transistor

21. For the network of Fig. 17.40, in which  $V = 40 \text{ V}$ ,  $\eta = 0.6$ ,  $V_V = 1 \text{ V}$ ,  $I_V = 8 \text{ mA}$ , and  $I_P = 10 \mu\text{A}$ , determine the range of  $R_1$  for the triggering network.  
 22. For a unijunction transistor with  $V_{BB} = 20 \text{ V}$ ,  $\eta = 0.65$ ,  $R_{B_1} = 2 \text{ k}\Omega$  ( $I_E = 0$ ), and  $V_D = 0.7 \text{ V}$ , determine:  
 a.  $R_{B_2}$ .  
 b.  $R_{BB}$ .  
 c.  $V_{R_{B_1}}$ .  
 d.  $V_P$ .  
 \*23. Given the relaxation oscillator of Fig. 17.68:  
 a. Find  $R_{B_1}$  and  $R_{B_2}$  at  $I_E = 0 \text{ A}$ .  
 b. Determine  $V_P$ , the voltage necessary to turn on the UJT.  
 c. Determine whether  $R_1$  is within the permissible range of values defined by Eq. (17.8).  
 d. Determine the frequency of oscillation if  $R_{B_1} = 200 \Omega$  during the discharge phase.  
 e. Sketch the waveform of  $v_C$  for two full cycles.  
 f. Sketch the waveform of  $v_{R_2}$  for two full cycles.  
 g. Determine the frequency using Eq. (17.17) and compare to the value determined in part (d). Account for any major differences.



**FIG. 17.68**  
 Problem 23.



**17.13 Phototransistors**

- 24. For a phototransistor having the characteristics of Fig. 17.50, determine the photoinduced base current for a radiant flux density of  $5 \text{ mW/cm}^2$ . If  $h_{fe} = 40$ , find  $I_C$ .
- \*25. Design a high-isolation OR-gate employing phototransistors and LEDs.

**17.14 Opto-Isolators**

- 26. a. Determine an average derating factor from the curve of Fig. 17.58 for the region defined by temperatures between  $-25^\circ\text{C}$  and  $+50^\circ\text{C}$ .  
b. Is it fair to say that for temperatures greater than room temperature (up to  $100^\circ\text{C}$ ), the output current is somewhat unaffected by temperature?
- 27. a. Determine from Fig. 17.54 the average change in  $I_{CEO}$  per degree change in temperature for the range  $25^\circ\text{C}$  to  $50^\circ\text{C}$ .  
b. Can the results of part (a) be used to determine the level of  $I_{CEO}$  at  $35^\circ\text{C}$ ? Test your theory.
- 28. Determine from Fig. 17.55 the ratio of LED output current to detector input current for an output current of 20 mA. Would you consider the device to be relatively efficient in its purpose?
- \*29. a. Sketch the maximum-power curve of  $P_D = 200 \text{ mW}$  on the graph of Fig. 17.56. List any noteworthy conclusions.  
b. Determine  $\beta_{dc}$  (defined by  $I_C/I_F$ ) for the system at  $V_{CE} = 15 \text{ V}$ ,  $I_F = 10 \text{ mA}$ .  
c. Compare the results of part (b) with those obtained from Fig. 17.55 at  $I_F = 10 \text{ mA}$ . Do they compare? Should they? Why?
- \*30. a. Referring to Fig. 17.57, determine the collector current above which the switching time does not change appreciably for  $R_L = 1 \text{ k}\Omega$  and  $R_L = 100 \Omega$ .  
b. At  $I_C = 6 \text{ mA}$ , how does the ratio of switching times for  $R_L = 1 \text{ k}\Omega$  and  $R_L = 100 \Omega$  compare to the ratio of resistance levels?

**17.15 Programmable Unijunction Transistor**

- 31. Determine  $\eta$  and  $V_G$  for a PUT with  $V_{BB} = 20 \text{ V}$  and  $R_{B_1} = 3R_{B_2}$ .
- 32. Using the data provided in Example 17.3, determine the impedance of the PUT at the firing and valley points. Are the approximate open- and short-circuit states verified?
- 33. Can Eq. (17.24) be derived exactly as shown from Eq. (17.23)? If not, what element is missing in Eq. (17.24)?
- \*34. a. Will the network of Example 17.3 oscillate if  $V_{BB}$  is changed to 10 V? What minimum value of  $V_{BB}$  is required ( $V_V$  a constant)?  
b. Referring to the same example, what value of  $R$  would place the network in the stable "on" state and remove the oscillatory response of the system?  
c. What value of  $R$  would make the network a 2-ms time-delay network? That is, would provide a pulse  $v_K$  at 2 ms after the supply is turned on and then stay in the "on" state.