

Quadratic Forms

§ 9.01. Quadratic Form.

Definiton. A homogeneous polynomial of the type

$$q = \mathbf{X}' \mathbf{A} \mathbf{X} = \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j \quad \dots(i)$$

whose coefficients a_{ij} are elements of the field F is known as a quadratic form over F in the variables x_1, x_2, \dots, x_n .

For Example. $x_1^2 + 2x_2^2 + 5x_3^2 + 8x_1x_3 - 6x_2x_3$ is a quadratic form in the variables x_1, x_2, x_3 . Here the matrix of the form can be written in many ways according as the cross product terms $8x_1x_3$ and $-6x_2x_3$ are separated to form the terms $a_{13}x_1x_3, a_{31}x_3x_1$ and $a_{23}x_2x_3, a_{32}x_3x_2$.

Here we shall agree that the matrix \mathbf{A} of quadratic form be symmetric and shall always separate the cross-product terms so that $a_{ij} = a_{ji}$

$$\begin{aligned} \therefore q &= x_1^2 + 2x_2^2 + 5x_3^2 + 8x_1x_3 - 6x_2x_3 \\ &= [x_1 \ x_2 \ x_3] \begin{bmatrix} 1 & 0 & 4 \\ 0 & 2 & -3 \\ 4 & -3 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \dots \text{see Ex. 1 (b) Page 223 of this chapter} \\ &= \mathbf{X}' \begin{bmatrix} 1 & 0 & 4 \\ 0 & 2 & -3 \\ 4 & -3 & 5 \end{bmatrix} \mathbf{X} = \mathbf{X}' \mathbf{A} \mathbf{X} \end{aligned}$$

The symmetric matrix $\mathbf{A} = [a_{ij}]$ is known as the matrix of the quadratic form and the rank of \mathbf{A} is called the **rank of the quadratic form**.

If the rank of the form is $r < n$, then the quadratic form is called **singular** otherwise **non-singular**.

Transformations.

The linear transformation $\mathbf{X} = \mathbf{B}\mathbf{Y}$ over F carries the quadratic form (i) above with symmetric matrix \mathbf{A} over F into the quadratic form

$$(\mathbf{B}\mathbf{Y})' \mathbf{A} (\mathbf{B}\mathbf{Y}) = (\mathbf{Y}' \mathbf{B}') \mathbf{A} (\mathbf{B}\mathbf{Y}) = \mathbf{Y}' (\mathbf{B}' \mathbf{A} \mathbf{B}) \mathbf{Y} \quad \dots(ii)$$

with symmetric matrix $\mathbf{B}' \mathbf{A} \mathbf{B}$.

Equivalent Quadratic Forms.

Definition. Two quadratic forms in the same variables x_1, x_2, \dots, x_n are called **equivalent** if and only if there exists a non-singular linear transformation $\mathbf{X} = \mathbf{B}\mathbf{Y}$ which together with $\mathbf{Y} = \mathbf{I}\mathbf{X}$, where \mathbf{I} is the identity matrix, carries one of the forms into the other.

As $B'AB$ is congruent to A , we have

1. The rank of a quadratic form is invariant under a non-singular transformation of the variables.

2. Two quadratic forms over F are equivalent over F iff their matrices are congruent over F .

A quadratic form of rank r can be reduced to the form

$$b_1y_1^2 + b_2y_2^2 + b_3y_3^2 + \dots + b_ry_r^2, \quad b_i \neq 0 \quad \dots(iii)$$

in which only terms in the squares of the variables occur by a non-singular linear transformation $X = BY$.

§ 9.02. Lagrange's Reduction.

The reduction of a quadratic form to the form (iii) of § 9.01 above can be carried out by a method or procedure called Lagrange's Reduction, which consists of repeated completing of the square.

From example $q = x_1^2 + 2x_2^2 + 5x_3^2 + 8x_1x_3 - 6x_2x_3$ can be reduced to form (iii) of § 9.01 above as follows :—

$$\begin{aligned} q &= x_1^2 + 2x_2^2 + 5x_3^2 + 8x_1x_3 - 6x_2x_3 \\ &= (x_1^2 + 8x_1x_3 + 16x_3^2) + 2x_2^2 - 11x_3^2 - 6x_2x_3 \\ &= (x_1 + 4x_3)^2 + \frac{1}{2}(4x_2^2 - 12x_2x_3) - 11x_3^2 \\ &= (x_1 + 4x_3)^2 + \frac{1}{2}(4x_2^2 - 12x_2x_3 + 9x_3^2) - \frac{9}{2}x_3^2 - 11x_3^2 \\ &= (x_1 + 4x_3)^2 + \frac{1}{2}(2x_2 - 3x_3)^2 - \frac{31}{2}x_3^2 \\ &= y_1^2 + (1/2)y_2^2 - (31/2)y_3^2, \end{aligned}$$

where $y_1 = x_1 + 4x_3$, $y_2 = 2x_2 - 3x_3$, $y_3 = x_3$.

§ 9.03. Real Quadratic Forms.

Let a real quadratic form $q = X'AX$ be reduced by a real non-singular transformation to the form $b_1y_1^2 + b_2y_2^2 + \dots + b_ry_r^2$, $b_i \neq 0$. If one or more of the b_i are negative, then there exists a non-singular transformation $X = CZ$, where C is obtained from B (see § 9.01 Page 220 of this chapter) by a sequence of row and column transformations which carries q into

$$h_1z_1^2 + h_2z_2^2 + \dots + h_pz_p^2 - h_{p+1}z_{p+1}^2 - \dots - h_rz_r^2 \quad \dots(i)$$

in which the terms with positive coefficients precede those with negative coefficients.

Now the non-singular transformation

$$s_i = \sqrt{|h_i|} z_i, \quad i = 1, 2, \dots, r$$

$$s_j = z_j, \quad j = r + 1, r + 2, \dots, n$$

carries (i) into the canonical form

$$s_2^2 + s_2^2 + s_3^2 + \dots + s_p^2 - s_{p+1}^2 - \dots - s_r^2 \quad \dots(ii)$$

Thus, as the product of non-singular transformations is a non-singular transformation, we have every real quadratic form can be reduced by a non-singular transformation to the canonical form (ii) above, where p , the number of positive terms is called the index and r is the rank of the given quadratic form.

Example. In Ex. 3 (c) Page 225 the quadratic form $q = x_1^2 + 2x_2^2 - 7x_3^2 - 4x_1x_2 + 8x_1x_3$ was reduced to $q_1 = y_1^2 - 2y_2^2 + 9y_3^2$. The non-singular transformation $y_1 = z_1, y_2 = z_3, y_3 = z_2$ carries q_1 into $q_2 = z_1^2 + 9z_2^2 - 2z_3^2$ and the non-singular transformation $z_1 = s_1, z_2 = s_2/3, z_3 = s_3/\sqrt{2}$ reduces q_2 to $q_3 = s_1^2 + s_2^2 - s_3^2$.

Also in Ex. 3 (c) Page 225 we have

$$y_1 = x_1 - 2x_2 + 4x_3, y_2 = x_2 - 4x_3, y_3 = x_3$$

or $x_1 = y_1 + 2y_2 + 4y_3, x_2 = y_2 + 4y_3, x_3 = y_3$

or $x_1 = z_1 + 2z_3 + 4z_2, x_2 = z_3 + 4z_2, x_3 = z_2$

or $x_1 = s_1 + 2(s_3/\sqrt{2}) + 4(s_2/3), x_2 = (s_3/\sqrt{2}) + 4(s_2/3), x_3 = s_2/3$

or $x_1 = s_1 + (4/3)s_2 + \sqrt{2}s_3, x_2 = (4/3)s_2 + (1/2)\sqrt{2}s_3, x_3 = (1/3)s_2$

or
$$\mathbf{X} = \begin{bmatrix} 1 & 4/3 & \sqrt{2} \\ 0 & 4/3 & (1/2)\sqrt{2} \\ 0 & 1/3 & 0 \end{bmatrix} \mathbf{S}$$

is the non-singular linear transformation that reduces q to $q_3 = s_1^2 + s_2^2 - s_3^2$.

\therefore The quadratic form is of rank 3 and index 2.

§ 9.04. Complex Quadratic Forms

Let the complex quadratic form $\mathbf{X}'\mathbf{A}\mathbf{X}$ be reduced by a non-singular transformation to the form $b_1y_1^2 + b_2y_2^2 + \dots + b_ry_r^2, b_i \neq 0$.

Evidently the non-singular transformation

$$z_i = \sqrt{|b_i|} y_i, i = 1, 2, \dots, r$$

$$z_j = y_j, j = r+1, r+2, \dots, n$$

carries $b_1y_1^2 + b_2y_2^2 + \dots + b_ry_r^2$ into $z_1^2 + z_2^2 + \dots + z_r^2$ (i)

Solved Examples on § 9.01 to § 9.04

*Ex. 1. Write the following quadratic forms in matrix notation :

(a) $x_1^2 + 4x_1x_2 + 3x_2^2$

(b) $x_1^2 - 2x_2^2 - 3x_3^2 + 4x_1x_2 + 6x_1x_3 - 8x_2x_3$.

(Garhwal 95)

Sol. Let $x_1^2 + 4x_1x_2 + 3x_2^2 = \mathbf{X}'\mathbf{A}\mathbf{X} = [x_1 \ x_2] \begin{bmatrix} a_1 & a_2 \\ a_2 & b_1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$... (i)

since A is a symmetric matrix

$$\begin{aligned} \text{i.e. } x_1^2 + 4x_1x_2 + 3x_2^2 &= [a_1x_1 + a_2x_2 \quad a_2x_1 + b_1x_2] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \\ &= [(a_1x_1 + a_2x_2)x_1 + (a_2x_1 + b_1x_2)x_2] \\ \Rightarrow x_1^2 + 4x_1x_2 + 3x_2^2 &= a_1x_1^2 + 2a_2x_1x_2 + b_1x_2^2 \end{aligned}$$

Comparing coefficients of x_1^2 , x_1x_2 and x_2^2 on both sides, we get

$$a_1 = 1, a_2 = 2, b_1 = 3.$$

$$\therefore \text{From (i), } x_1^2 + 4x_1x_2 + 3x_2^2 = \mathbf{X}' \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} \mathbf{X} \quad \text{Ans}$$

$$\text{(b) Let } x_1^2 - 2x_2^2 - 3x_3^2 + 4x_1x_2 + 6x_1x_3 - 8x_2x_3$$

$$= \mathbf{X}'\mathbf{A}\mathbf{X} = [x_1 \ x_2 \ x_3] \begin{bmatrix} a_1 & b_1 & c_1 \\ b_1 & b_2 & c_2 \\ c_1 & c_2 & c_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$\therefore A$ is a symmetric matrix

$$= [a_1x_1 + b_1x_2 + c_1x_3 \quad b_1x_1 + b_2x_2 + c_2x_3 \quad c_1x_1 + c_2x_2 + c_3x_3] \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$\begin{aligned} &= [(a_1x_1 + b_1x_2 + c_1x_3)x_1 + (b_1x_1 + b_2x_2 + c_2x_3)x_2 + (c_1x_1 + c_2x_2 + c_3x_3)x_3] \\ \Rightarrow x_1^2 - 2x_2^2 - 3x_3^2 + 4x_1x_2 + 6x_1x_3 - 8x_2x_3 \\ &= a_1x_1^2 + b_2x_2^2 + c_3x_3^2 + 2b_1x_1x_2 + 2c_1x_1x_3 + 2c_2x_2x_3 \\ \Rightarrow a_1 &= 1, b_2 = -2, c_3 = -3, b_1 = 2, c_1 = 3, c_2 = -4. \end{aligned}$$

$$\therefore \text{From (ii), we have } x_1^2 - 2x_2^2 - 3x_3^2 + 4x_1x_2 + 6x_1x_3 - 8x_2x_3$$

$$= \mathbf{X}' \begin{bmatrix} 1 & 2 & 3 \\ 2 & -2 & -4 \\ 3 & -4 & -3 \end{bmatrix} \mathbf{X} \quad \text{Ans.}$$

Ex. 2 (a). Find the matrix of the quadratic form $x_1^2 + 2x_2^2 - 5x_3^2 - x_1x_2 + 4x_2x_3 - 3x_3x_1$ and verify that it can be written as a matrix product $\mathbf{X}'\mathbf{A}\mathbf{X}$.
(Garhwal 94, 93)

$$\text{Sol. Let } x_1^2 + 2x_2^2 - 5x_3^2 - x_1x_2 + 4x_2x_3 - 3x_3x_1$$

$$= \mathbf{X}'\mathbf{A}\mathbf{X} = [x_1 \ x_2 \ x_3] \begin{bmatrix} a_1 & b_1 & c_1 \\ b_1 & b_2 & c_2 \\ c_1 & c_2 & c_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \quad \dots(i)$$

since A is a symmetric matrix,

$$\begin{aligned}
 &= [a_1x_1 + b_1x_2 + c_1x_3 \quad b_1x_1 + b_2x_2 + c_2x_3 \quad c_1x_1 + c_2x_2 + c_3x_3] \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \\
 &= [(a_1x_1 + b_1x_2 + c_1x_3)x_1 + (b_1x_1 + b_2x_2 + c_2x_3)x_2 + (c_1x_1 + c_2x_2 + c_3x_3)x_3] \\
 \Rightarrow \quad &x_1^2 + 2x_2^2 - 5x_3^2 - x_1x_2 + 4x_2x_3 - 3x_3x_1 \\
 &= a_1x_1^2 + b_2x_2^2 + c_3x_3^2 + 2b_1x_1x_2 + 2c_2x_2x_3 + 2c_1x_3x_1
 \end{aligned}$$

Equating coefficients of like terms on both sides, we get

$$a_1 = 1, b_2 = 2, c_3 = -5, 2b_1 = -1, 2c_2 = 4, 2c_1 = -3$$

\(\therefore\) From (i), we have the given quadratic form

$$= [x_1 \ x_2 \ x_3] \begin{bmatrix} 1 & -1/2 & -3/2 \\ -1/2 & 2 & 2 \\ -3/2 & 2 & -5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

\(\therefore\) The required matrix of the given quadratic form

$$= \begin{bmatrix} 1 & -1/2 & -3/2 \\ -1/2 & 2 & 2 \\ -3/2 & 2 & -5 \end{bmatrix}$$

Ans.

$$\text{Also } [x_1 \ x_2 \ x_3] \begin{bmatrix} 1 & -1/2 & -3/2 \\ -1/2 & 2 & 2 \\ -3/2 & 2 & -5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$= [x_1 - \frac{1}{2}x_2 - \frac{3}{2}x_3 \quad -\frac{1}{2}x_1 + 2x_2 + 2x_3 \quad -\frac{3}{2}x_1 + 2x_2 - 5x_3] \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$= (x_1 - \frac{1}{2}x_2 - \frac{3}{2}x_3)x_1 + (-\frac{1}{2}x_1 + 2x_2 + 2x_3)x_2 + (-\frac{3}{2}x_1 + 2x_2 - 5x_3)x_3$$

$$= x_1^2 + 2x_2^2 - 5x_3^2 - x_1x_2 + 4x_2x_3 - 3x_3x_1 = \text{Given quadratic form.}$$

Hence proved.

Ex. 2 (b). Find the matrix of the quadratic form $G = x^2 + y^2 + 3z^2 + 4xy + 5yz + 6zx$ and express it in the form $G = X'AX$, where $X' = (x, y, z)$

(Garhwal 96)

$$\text{Sol. Let } G = x^2 + y^2 + 3z^2 + 4xy + 5yz + 6zx$$

$$= X'AX = [x \ y \ z] \begin{bmatrix} a_1 & b_1 & c_1 \\ b_1 & b_2 & c_2 \\ c_1 & c_2 & c_3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad \dots(i)$$

$$= [a_1x + b_1y + c_1z \quad b_1x + b_2y + c_2z \quad c_1x + c_2y + c_3z] \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$\begin{aligned}
 &= [(a_1x + b_1y + c_1z)x + (b_1x + b_2y + c_2z)y + (c_1x + c_2y + c_3z)z] \\
 \Rightarrow &x^2 + y^2 + 3z^2 + 4xy + 5yz + 6zx \\
 &= a_1x^2 + b_2y^2 + c_3z^2 + 2b_1xy + 2c_2yz + 2c_1zx \\
 \Rightarrow &a_1 = 1, b_2 = 1, c_3 = 3, 2b_1 = 4, 2c_2 = 5, 2c_1 = 6 \\
 \Rightarrow &a_1 = 1, b_2 = 1, c_3 = 3, b_1 = 2, c_2 = 5/2, c_1 = 3.
 \end{aligned}$$

$$\therefore \text{From (i), we get } G = \mathbf{X}'\mathbf{A}\mathbf{X} = [x \ y \ z] \begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & 5/2 \\ 3 & 5/2 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad \dots(\text{ii})$$

which gives the required matrix $\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & 5/2 \\ 3 & 5/2 & 3 \end{bmatrix}$

Ans.

and G can be expressed in the form $\mathbf{X}'\mathbf{A}\mathbf{X}$ by (ii).

Ex. 2 (c). Write out in full the quadratic form in x_1, x_2, x_3 whose matrix is $\begin{bmatrix} 2 & -2 & 5 \\ -2 & 3 & 0 \\ 5 & 0 & 4 \end{bmatrix}$

$$\begin{aligned}
 \text{Sol. Here } \mathbf{X}'\mathbf{A}\mathbf{X} &= [x_1 \ x_2 \ x_3] \begin{bmatrix} 2 & -2 & 5 \\ -2 & 3 & 0 \\ 5 & 0 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \\
 &= [2x_1 - 2x_2 + 5x_3 \quad -2x_1 + 3x_2 + 0x_3 \quad 5x_1 + 0x_2 + 4x_3] \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \\
 &= [(2x_1 - 2x_2 + 5x_3)x_1 + (-2x_1 + 3x_2)x_2 + (5x_1 + 4x_3)x_3] \\
 &= [2x_1^2 - 2x_2x_1 + 5x_3x_1 - 2x_1x_2 + 3x_2^2 + 5x_1x_3 + 4x_3^2] \\
 &= [2x_1^2 + 3x_2^2 + 4x_3^2 - 4x_1x_2 + 10x_1x_3]
 \end{aligned}$$

\therefore Required quadratic form is

$$2x_1^2 + 3x_2^2 + 4x_3^2 - 4x_1x_2 + 10x_1x_3.$$

Ans.

Ex. 3. Reduce the following by Lagrange's Reduction :

$$(a) \mathbf{X}' \begin{bmatrix} 1 & 2 & 4 \\ 2 & 6 & -2 \\ 4 & -2 & 18 \end{bmatrix} \mathbf{X}; \quad (b) \mathbf{X}' \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & -2 \\ 1 & -2 & 3 \end{bmatrix} \mathbf{X}$$

$$(c) q = x_1^2 + 2x_2^2 - 7x_3^2 - 4x_1x_2 + 8x_1x_3$$

$$\text{Sol. (a) } \mathbf{X}' \begin{bmatrix} 1 & 2 & 4 \\ 2 & 6 & -2 \\ 4 & -2 & 18 \end{bmatrix} \mathbf{X} = [x_1 \ x_2 \ x_3] \begin{bmatrix} 1 & 2 & 4 \\ 2 & 6 & -2 \\ 4 & -2 & 18 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$= [x_1 + 2x_2 + 4x_3 \quad 2x_1 + 6x_2 - 2x_3 \quad 4x_1 - 2x_2 + 18x_3] \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$= [(x_1 + 2x_2 + 4x_3)x_1 + (2x_1 + 6x_2 - 2x_3)x_2 + (4x_1 - 2x_2 + 18x_3)x_3]$$

$$= [x_1^2 + 6x_2^2 + 18x_3^2 + 4x_1x_2 - 4x_2x_3 + 8x_1x_3]$$

$$\therefore q = x_1^2 + 6x_2^2 + 18x_3^2 + 4x_1x_2 - 4x_2x_3 + 8x_1x_3$$

$$= [x_1^2 + 4x_1(x_2 + 2x_3)] + 6x_2^2 + 18x_3^2 - 4x_2x_3$$

$$= [x_1^2 + 4x_1(x_2 + 2x_3) + 4(x_2 + 2x_3)^2] + 6x_2^2 + 18x_3^2 - 4x_2x_3 - 4(x_2 + 2x_3)^2$$

$$= [x_1 + 2(x_2 + 2x_3)]^2 + 6x_2^2 + 18x_3^2 - 4x_2x_3 - 4x_2^2 - 16x_3^2 - 16x_3x_2$$

$$= (x_1 + 2x_2 + 4x_3)^2 + 2x_2^2 + 2x_3^2 - 20x_2x_3$$

$$= (x_1 + 2x_2 + 4x_3)^2 + 2(x_2^2 - 10x_2x_3) + 2x_3^2$$

$$= (x_1 + 2x_2 + 4x_3)^2 + 2(x_2^2 - 10x_2x_3 + 25x_3^2) - 48x_3^2$$

$$= (x_1 + 2x_2 + 4x_3)^2 + 2(x_2 - 5x_3)^2 - 48x_3^2$$

$$= y_1^2 + 2y_2^2 - 48y_3^2.$$

Ans.

where $y_1 = x_1 + 2x_2 + 4x_3$, $y_2 = x_2 - 5x_3$, $y_3 = x_3$.

$$(b) X' \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & -2 \\ 1 & -2 & 3 \end{bmatrix} X = [x_1 \ x_2 \ x_3] \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & -2 \\ 1 & -2 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$= [x_1 \ 0 + x_2 \ 0 + x_3 \ 1 \ x_1 \ 0 + x_2 \ 1 - 2x_3 \ x_1 - 2x_2 + 3x_3] \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$= [(x_3)x_1 + (x_2 - 2x_3)x_2 + (x_1 - 2x_2 + 3x_3)x_3]$$

$$= [x_2^2 + 3x_3^2 + 2x_1x_3 - 4x_2x_3]$$

$$= [z_1^2 + 3z_2^2 + 2z_3z_1 - 4z_1z_2], \text{ using } x_1 = z_3, x_2 = z_1, x_3 = z_2$$

$$= [(z_1^2 - 4z_1z_2 + 4z_2^2) - (z_2^2 - 2z_2z_3)]$$

$$= [(z_1 - 2z_2)^2 - (z_2^2 - 2z_2z_3 + z_3^2) + z_3^2]$$

$$= [(z_1 - 2z_2)^2 - (z_2 - z_3)^2 + z_3^2]$$

$$\therefore q = (z_1 - 2z_2)^2 - (z_2 - z_3)^2 + z_3^2$$

$$= y_1^2 - y_2^2 + y_3^2.$$

where $y_1 = z_1 - 2z_2 = x_2 - 2x_3$, $y_2 = z_2 - z_3 = x_3 - x_1$, $y_3 = z_3 = x_1$

$$(c) q = x_1^2 + 2x_2^2 - 7x_3^2 - 4x_1x_2 + 8x_1x_3$$

$$\begin{aligned}
 &= \{x_1^2 - 4x_1(x_2 - 2x_3)\} + 2x_2^2 - 7x_3^2 \\
 &= \{x_1^2 - 4x_1(x_2 - 2x_3) + 4(x_2 - 2x_3)^2\} + 2x_2^2 - 7x_3^2 - 4(x_2 - 2x_3)^2 \\
 &= \{x_1 - 2(x_2 - 2x_3)\}^2 + 2x_2^2 - 7x_3^2 - 4(x_2^2 - 4x_2x_3 + 4x_3^2) \\
 &= (x_1 - 2x_2 + 4x_3)^2 - 2x_2^2 + 16x_2x_3 - 23x_3^2 \\
 &= (x_1 - 2x_2 + 4x_3)^2 - 2(x_2^2 - 8x_2x_3 + 16x_3^2) + 9x_3^2 \quad \text{(Note)} \\
 &= (x_1 - 2x_2 + 4x_3)^2 - 2(x_2 - 4x_3)^2 + 9x_3^2 \\
 &= y_1^2 - 2y_2^2 + 9y_3^2. \quad \text{Ans.}
 \end{aligned}$$

where $y_1 = x_1 - 2x_2 + 4x_3$, $y_2 = x_2 - 4x_3$, $y_3 = x_3$.

Exercise on § 9.01 - § 9.02

Ex. 1. Write $2x_1^2 - 6x_1x_2 + x_3^2$ in matrix notation

$$\text{Ans. } \mathbf{X}' \begin{bmatrix} 2 & -3 & 0 \\ -3 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \mathbf{X}$$

Ex. 2. Write out in full the quadratic form in x_1, x_2, x_3 whose matrix is

$$\begin{bmatrix} 2 & -3 & 1 \\ -3 & 2 & 4 \\ 1 & 4 & -5 \end{bmatrix}$$

$$\text{Ans. } 2x_1^2 - 6x_1x_2 + 2x_1x_3 + 2x_2^2 + 8x_2x_3 - 5x_3^2$$

Ex. 3. Reduce the following by Lagrange's reduction :

$$\mathbf{X}' \begin{bmatrix} 0 & 1 & 2 \\ 1 & 1 & -1 \\ 2 & -1 & 0 \end{bmatrix} \mathbf{X}$$

$$\text{Ans. } y_1^2 - y_2^2 + 8y_3^2$$

[Hint : Use $x_1 = z_3, x_2 = z_1, x_3 = z_2$]

§ 9.05. Definite and Semi-definite Forms.

Definition (i) A real non-singular quadratic form $q = \mathbf{X}'\mathbf{A}\mathbf{X}$, $|\mathbf{A}| \neq 0$, in n variables is known as **positive definite** if its rank and index are equal. Thus, in the real field a positive definite quadratic form can be reduced to the form $y_1^2 + y_2^2 + \dots + y_n^2$ and for any non-trivial set of values of the x 's, $q > 0$.

(ii) A real singular quadratic form $q = \mathbf{X}'\mathbf{A}\mathbf{X}$, $|\mathbf{A}| = 0$ is as **positive semi-definite** if its rank and index are equal i.e. $r = p < n$.

Thus in the real field a positive semi-definite quadratic form can be reduced to the form $y_1^2 + y_2^2 + \dots + y_r^2$, $r < n$ and for any non-trivial set of values of the x 's, $q \geq 0$.

(iii) A real non-singular quadratic form $q = \mathbf{X}'\mathbf{A}\mathbf{X}$ is known as **negative definite** if its index $p = 0$ i.e. $r = n, p = 0$.

Thus in the real field a negative definite form can be reduced to the form $-y_1^2 - y_2^2 - \dots - y_n^2$ and for any non-trivial set of values of the x 's, $q < 0$.

(iv) A real singular quadratic form $q = X'AX$ is known as **negative semi-definite** if its index $p = 0$ i.e. $r < n, p = 0$.

* Thus in the real field a negative semi-definite form can be reduced to the form $-y_1^2 - y_2^2 - \dots - y_n^2$ and for any non-trivial set of values of the x 's, $q \leq 0$.

Note 1. If q is negative definite (semi-definite), then $-q$ is positive definite (semi-definite).

Note 2. For positive definite quadratic form, if $q = X'AX$ is positive definite then $|A| > 0$.

§ 9.06. Definite and Semi-definite Matrices.

Definition. The matrix A of a real quadratic form $q = X'AX$ is known as definite or semi-definite according as the quadratic form is definite or semi-definite. Thus

(i) A real symmetric matrix A is positive definite iff there exists a non-singular matrix C , such that $A = C'C$.

(ii) A real symmetric matrix of rank r is positive semi-definite iff there exists a matrix C of rank r , such that $A = C'C$.

§ 9.07. Principal Minors.

Definition. A minor of matrix A is known as **principal** if it is obtained by deleting certain rows and the same numbered columns of the matrix A .

Note 1. The diagonal elements of a principal minor of the matrix A are diagonal elements of the matrix A .

Note 2. Every symmetric matrix of rank r has at least one principal minor of order r different from zero.

Note 3. If the matrix A is positive definite, then every principal minor of the matrix A is positive.

Note 4. If the matrix A is positive semi-definite, then every principal minor of the matrix A is non-negative.

Exercises on Chapter IX

Ex. 1. Reduce the square matrix A into diagonal form and interpret the result in terms of quadratic form:

$$A = \begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix}$$

(Garhwal 94).

Ex. 2. Reduce the quadratic form $2x_1^2 + x_2^2 - 3x_3^2 - 8x_2x_3 - 4x_3x_1 + 12x_1x_2$ to normal form.

(Garhwal 93)

(A) VERY SHORT AND SHORT ANSWER TYPE QUESTIONS**Ch. V Rank and Adjoint of a Matrix**

1. Define rank of a matrix. (Purvanchal 2000) [See § 5-02 Pages 1-2]
 2. Find the rank of the matrix A, where

$$A = \begin{bmatrix} 1 & -1 & 2 & -3 \\ 4 & 1 & 0 & 2 \\ 0 & 3 & 0 & 4 \\ 0 & 1 & 0 & 2 \end{bmatrix}$$

(Meerut 2001)

[Hint : Do as Ex. 11 (b) P. 28]

Ans. 4

3. Reduce the matrix $\begin{bmatrix} 1 & 3 & 4 \\ -2 & 1 & -1 \\ 3 & -1 & 2 \end{bmatrix}$ to normal form.

(Kanpur 2001)

$$\text{Ans. } \begin{bmatrix} I_2 & O \\ O & O \end{bmatrix}$$

4. When is a matrix said to be in Echelon form ?

(Purvanchal 98)

[See § 5-04 Page 36]

5. Write down the four normal forms of a matrix.

[See § 5-03 Page 15]

6. Define adjoint of a matrix.

[See § 5-08 Page 43]

7. Show that adjoint of the matrix $\begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}$ is $\begin{bmatrix} bc & 0 & 0 \\ 0 & ca & 0 \\ 0 & 0 & ab \end{bmatrix}$.

8. How will you use the notion of determinant to complete the inverse of a non-singular square matrix ?

[See Th. I result (iv) Page 50]

9. Find the inverse of the matrix $\begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix}$

[See Ex. 15 Page 67]

$$\text{Ans. } \begin{bmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{bmatrix}$$

10. If $a^2 + b^2 + c^2 + d^2 = 1$, then show that the inverse of the matrix

$$\begin{bmatrix} a+ib & c+id \\ -c+id & a-ib \end{bmatrix} \text{ is } \begin{bmatrix} a-ib & -c-id \\ c-id & a+ib \end{bmatrix}$$

[See Ex. 18 Page 70]

11. Find the rank of an $m \times n$ matrix, every element of which is unity.

Ans. 1.

[Hint : See Ex. 9 Page 96]

12. A, B, P and Q are matrices such that $\text{adj. } B = A$, $|P| = |Q| = 1$, then $\text{adj}(Q^{-1} B P^{-1}) = PAQ$.

(Kanpur 2001)

Ch. VI Solution of Linear Equations

13. Express in matrix form the system of equations :

$$9x + 7y + 3z = 6, 5x + y + 4z = 1; 6x + 8y + 2z = 4 \quad \text{[See Ex. 1 Page 106]}$$

14. Define a homogeneous linear equation. [See § 6-10 Page 144]

15. Solve the simultaneous equations given below :

$$x + y + 2z = 3; 2x + 2y + 3z = 7; 3x - y + 2z = 1, 2x - y - z = 2$$

(Kanpur 2001) Ans. $x = 2, y = 3, z = 1$

Ch. VII Characteristics Equations of a Matrix

16. What do you understand by the characteristic equation of the matrix A?

[See § 7-02 (iii) Page 160]

17. What is eigen value problem ?

[See § 7-02 (v) Page 160]

18. Obtain the characteristic equation of the matrix $\begin{bmatrix} 1 & 0 & 2 \\ 0 & 2 & 1 \\ 2 & 0 & 3 \end{bmatrix}$

(Meerut 2001) Ans. $\lambda^3 - 6\lambda^2 + 7\lambda + 2 = 0$

19. State Cayley-Hamilton's Theorem.

20. Find latent vectors of the matrix $\begin{bmatrix} a & h & g \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}$

[See Ex: 25(a) Page 200]

Ch. VIII Linear Dependence of Vectors

21. Define linearly dependent and linearly independent set of vectors.

(Kanpur 2001) [See § 8-03 Page 211]

22. Show that the set of vectors $V_1 = \{1, 2, 3\}$, $V_2 = \{1, 0, 1\}$ and $V_3 = \{0, 1, 0\}$ are linearly independent.

[See Ex. 1 Page 212]

23. Find a linear relation, if any, between the linear forms of the following system $f_1 = x + y + z, f_2 = y - 2z, f_3 = 2x + 3y$.

Ans. $2f_1 + f_2 = f_3$ [See Ex. 3 Page 217]

Ch. IX Quadratic Forms

24. Define a quadratic form.

[See § 9-01 Page 220]

25. What do you understand by the rank of a quadratic form.

[See § 9-01 Page 220]

26. Write the quadratic form corresponding to the matrix $\begin{bmatrix} 0 & -3 & -4 \\ 3 & 0 & 2 \\ -4 & -2 & 0 \end{bmatrix}$.

(Kanpur 2001) Ans. $-4x_1x_3$

(B) OBJECTIVE TYPE QUESTIONS

(I) MULTIPLE CHOICE TYPE :

Select (i), (ii), (iii) or (iv) whichever is correct :

Ch. V. Rank and Adjoint of a Matrix

1. The rank of the matrix $\begin{bmatrix} 3 & 4 & 5 \\ 4 & 5 & 6 \\ 2 & 3 & 4 \end{bmatrix}$ is

- (i) 0 (ii) 1 (iii) 2 (iv) none of these
(Kanpur 2001)

2. The rank of the matrix $\begin{bmatrix} 0 & 2 & 3 \\ 0 & 4 & 6 \\ 0 & 6 & 9 \end{bmatrix}$ is

- (i) 0 (ii) 1 (iii) 2 (iv) 3

3. If A be a matrix, which one of the following is a number :

- (i) A^{-1} (ii) $\text{adj } A$ (iii) $\text{rank } A$ (iv) none of these

4. If A' be the transpose of the matrix A , then

- (i) $\text{rank } A' > \text{rank } A$ (ii) $\text{rank } A' = \text{rank } A$
(iii) $\text{rank } A' < \text{rank } A$ (iv) none of these

5. If by a series of elementary transformations an n -rowed square matrix A

is reduced to the form $\begin{bmatrix} I_r & O \\ O & O \end{bmatrix}$, the rank of A is

- (i) $n + r$ (ii) r (iii) $n - r$ (iv) n

6. The rank of the matrix $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 3 & 4 \\ 4 & 9 & 16 \end{bmatrix}$ is

- (i) 0 (ii) 1 (iii) 2 (iv) 3

7. The rank of the matrix $\begin{bmatrix} 2 & -1 & 3 & 15 \\ 3 & 2 & 0 & 21 \end{bmatrix}$ is

- (i) 1 (ii) 2 (iii) 3 (iv) none of these

8. The rank of the matrix $\begin{bmatrix} 1 & 6 & 5 & 5 \\ 3 & 18 & 15 & 3 \\ 1 & 6 & 5 & 1 \end{bmatrix}$ is

- (i) 4 (ii) 3 (iii) 2 (iv) 1

9. The value of a for which the matrix $\begin{bmatrix} 2 & 3 & 1 \\ 3 & 2 & -1 \\ a & 1 & 3 \end{bmatrix}$ is singular, is

- (i) -2 (ii) -1 (iii) 1 (iv) 2

10. The necessary and sufficient condition that a square matrix may possess an inverse is that it be

- (i) singular (ii) triangular
(iii) non-singular (iv) none of these

11. If A is non-singular matrix, then $(A^{-1})^{-1}$ is

- (i) I (ii) A^{-1} (iii) A (iv) AA^{-1}
(Kanpur 2001)

12. If a non-singular matrix A is symmetric, then A^{-1} is

- (i) skew-symmetric (ii) Hermitian
(iii) diagonal (iv) symmetric

[Hint : See § 5-11 Th. V Page 77]

Ch. VI Solution of Linear Equations**13.** The system of equations

$$x + 2y + z = 2, 3x + 5y + 5z = 4, 2x + 4y + 3z = 3 \text{ has a}$$

- (i) unique solution (ii) infinite solution
 (iii) trivial solution (iv) none of these

, [See Ex. 5(a) P.110]

14. The system of equations

$$3x - y + z = 0, -15x + 6y - 5z = 0, 5x - 2y + 2z = 0 \text{ has a}$$

- (i) unique solution (ii) trivial solution
 (iii) infinite solution (iv) none of these

15. The theorem 'every square matrix satisfies its characteristic equation' is named after

- (i) Cramer (ii) Hamilton (iii) Newton (iv) none of them

Ch. VII Characteristic Equations of a Matrix**16.** If A be any matrix and I the identity matrix, then $A - \lambda I$ is known as

- (i) characteristic polynomial of A (ii) spectrum of A
 (iii) characteristic matrix of A (iv) none of these

(II) TRUE OR FALSE TYPE :

Write "T" or "F" according as the following statements are true or false :

Ch. V Rank and Adjoint of a Matrix

1. The rank of $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ is 2.

(Agra 90)

2. All equivalent matrices have the same rank.

3. If every minor of order p of a matrix A is zero, then every minor of order higher than p is not necessarily zero.4. If at least one minor of order r of the matrix A is not equal to zero, then rank of $A \geq r$.

5. The rank of $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 8 \\ 4 & 10 & 18 \end{bmatrix}$ is 2.

[See Ex. 1(a) P. 2]

6. The matrices $\begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 4 \\ 3 & 7 & 9 \end{bmatrix}$ and $\begin{bmatrix} 1 & 0 & -5 & 6 \\ 3 & -2 & 1 & 2 \\ 5 & -2 & -9 & 14 \\ 4 & -2 & -4 & 8 \end{bmatrix}$ are equivalent.

7. If the elements of a row of a matrix are multiplied by a non-zero number, then the rank of the matrix remains unaffected.

8. The rank of a matrix is equal to the rank of the transposed matrix.

9. The rank of the product matrix \mathbf{AB} of two matrices \mathbf{A} and \mathbf{B} is less than the rank of either of the matrices \mathbf{A} and \mathbf{B} .

10. If \mathbf{A} and \mathbf{B} are two $n \times n$ matrices, then

$$\text{Adj}(\mathbf{AB}) \neq (\text{Adj } \mathbf{B}) \cdot (\text{Adj } \mathbf{A})$$

11. If $\mathbf{A} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$, then $\mathbf{A}^{-1} = \mathbf{A}$

12. The necessary and sufficient condition that a square matrix may possess an inverse is that it be singular.

13. The inverse of transpose of a matrix is not the transpose of the inverse.

14. The inverse of the inverse of a matrix is the matrix itself.

15. If \mathbf{A} is any square matrix, then $(\text{adj. } \mathbf{A})^{-1} = \text{adj}(\mathbf{A}^{-1})$.

16. Inverse of a matrix \mathbf{A} exists if \mathbf{A} is singular.

17. If \mathbf{A} is a matrix of order $n \times n$, then \mathbf{A}^{-1} is also of the same order.

Ch. VI Solution of Linear Equations

18. A consistent system of equations has no solution.

19. A consistent system of equations has either one solution or infinitely many solutions.

20. A system of m linear equations in n unknowns given by $\mathbf{AX} = \mathbf{K}$ is consistent if the matrix \mathbf{A} and the augmented matrix \mathbf{A}^* of the system have the same rank.

Ch. VII Characteristic Equation of a Matrix

21. The matrix $\mathbf{A} - \lambda\mathbf{I}$ is known as the characteristics matrix of \mathbf{A} , when \mathbf{I} is the identity matrix.

22. Every square matrix satisfies its characteristic equation.

23. The characteristic roots of a Hermitian matrix are either purely imaginary or zero.

24. The characteristic roots of real skew-symmetric matrix are purely imaginary or zero.

25. The characteristic roots of a unitary matrix are of unit modulus.

Ch. VIII Linear Dependence of Vectors

26. The set of vectors $\mathbf{V}_1 = \{1, 2, 3\}$, $\mathbf{V}_2 = \{1, 0, 1\}$ and $\mathbf{V}_3 = \{0, 1, 0\}$ are linearly dependent.

27. If there be n linearly dependent vectors, then none of these can be expressed as a linear combination of the remaining ones.

[See Th. I § 8.04 Page 214]

Ch. IX Quadratic Forms

28. $x_1^2 + 2x_2^2 + 5x_3^2 - 8x_1x_2 + 6x_1x_3$ is a quadratic form in the variables x_1, x_2, x_3 .

(III) FILL IN THE BLANKS TYPE :

Fill in the blanks in the following : —

Ch. V Rank and Adjoint of Matrix

1. Rank of the null matrix is

(Kanpur 2001)

2. Rank of the matrix $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ is

(Kanpur 2001)

3. If a matrix A of order $m \times n$ can be expressed as $\begin{bmatrix} I_r & O \\ O & O \end{bmatrix}$, then rank of A is

(Meerut 2001)

4. All matrices have the same rank.

5. If every minor of order p of a matrix A is zero, then every minor of order p is definitely zero.6. If a matrix A does not possess any minor of order $(r + 1)$ then rank of A is r .7. The rank of the matrix $\begin{bmatrix} 1 & 3 & 4 \\ 2 & 6 & 8 \end{bmatrix}$ is8. The rank of the matrix $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{bmatrix}$ is

9. The rank of a matrix is to the rank of the transposed matrix.

10. The adjoint of the matrix $\begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$ is11. If A be a square matrix of order n , then

$$A (\text{adj } A) = (\text{adj } A) A = \dots\dots\dots$$

(Meerut 2001)

12. If A and B are two $n \times n$ matrices, then

$$(\text{Adj } B) \bullet (\text{Adj } A) = \dots\dots\dots$$

[See § 5-09 Th. III P. 50]

13. If A be an $n \times n$ matrix and $|A| \neq 0$, then

$$|\text{Adj } A| = \dots\dots\dots$$

[See § 5-09 Th. II P. 50]

14. A and B are two matrices such that $AB = I$, then

$$\text{adj } B = \dots\dots\dots$$

(Kanpur 2001)

[Hint : We know $B^{-1} = \frac{\text{adj } B}{|B|}$ and here $B^{-1} = A$, $\therefore AB = I$

$$\therefore \text{adj } B = A \cdot |B|]$$

15. If A is a non-singular matrix, then $(A^{-1})^{-1} = \dots\dots\dots$, where A^{-1} is the inverse of A .

16. The inverse of a matrix is

17. A singular matrix has no

18. A matrix when multiplied by its inverse given the matrix.

Ch. VI Solution of Linear Equations

19. Inconsistent equations have solution.
20. A constant system of equations has either one solution or solutions.
21. A homogeneous system of n linear equations in n unknowns, whose determinants of coefficients does not vanish, has only the solution.
22. A set of simultaneous homogeneous equations expressed in matrix form as $AX = O$ has non-trivial solution if (Kanpur 2001)
23. A system of m non-homogeneous linear equation $AX = B$ in n unknowns is called iff ranks of A and $[A, B]$ are equal. (Meerut 2001)
[See § 6-07 P. 119, § 6-06 P. 118]

Ch. VII Characteristic Equation of a Matrix

24. The set of all eigen values of the matrix A is called the of A .
[See § 7-02 (iv) Page 160]
25. The determinant $|A - \lambda I|$ is called the characteristic of the matrix A , when I is the identity matrix.
26. Every square matrix its characteristic equation.
(Meerut 2001)
27. Characteristic roots of skew-Hermitian matrix are either zero or
(Kanpur 2001)
28. All the characteristic roots of a real symmetric matrix are
29. The characteristic roots of a Hermitian matrix are all
30. The characteristic roots of an orthogonal matrix are of modulus.
31. Two matrices have the same characteristic roots.
(Kanpur 2001)
[See § 7-05 Th. I Page 167]

Ch. VIII Linear Dependence of Vectors

32. The set of vectors $V_1 = \{1, 2, 3\}$, $V_2 = \{1, 0, 1\}$ and $V_3 = \{0, 1, 0\}$ are linearly
[See Ex. 1 P. 212]
33. The set of vectors $X_1 = [2, 3, 1, -1]$, $X_2 = [2, 3, 1, -2]$ and $X_3 = [4, 6, 2, -3]$ is linearly
[See Ex. 1 Page 213]

Ch. IX Quadratic Forms

34. The quadratic form in x_1, x_2, x_3 of the matrix $\begin{bmatrix} 2 & -2 & 5 \\ -2 & 3 & 0 \\ 5 & 0 & 4 \end{bmatrix}$ is

ANSWERS TO OBJECTIVE TYPE QUESTIONS**(I) Multiple Choice Type :**

1. (iii); 2. (ii); 3. (iii); 4. (ii); 5. (ii); 6. (iv)

7. (ii) ... (iii) ... (iv) ...
 13. (i) ... (ii) ... (iii) ...

(II) True & False Type :

1. F; 2. T; 3. F; 4. T; 5. F; 6. F; 7. T;
 8. T; 9. T; 10. F; 11. T; 12. F; 13. F; 14. T;
 15. T; 16. F; 17. T; 18. F; 19. T; 20. T; 21. T;
 22. T; 23. F; 24. T; 25. T; 26. F; 27. F; 28. T.

(III) Fill in the blanks Type :

1. 0; 2. 2; 3. r ; 4. equivalent; 5. higher than; 6. \leq ; 7. 1; 8. 1; 9. equal;

10. $\begin{bmatrix} b & 0 \\ 0 & a \end{bmatrix}$;

11. $|A| \cdot |I_r|$; 12. $\text{Adj}(AB)$; 13. $|A|^{n-1}$; 14. $A \cdot |B|$; 15. A ; 16. unique;

17. inverse; 18. unit; 19. no; 20. infinitely many; 21. trivial;

22. the rank of $A <$ number of unknowns; 23. consistent; 24. spectrum;

25. polynomial; 26. satisfies; 27. purely imaginary; 28. real; 29. real;

30. unit; 31. mutually reciprocal; 32. independent; 33. dependent;

34. $2x_1^2 + 3x_2^2 + 4x_3^2 - 4x_1x_2 + 10x_1x_3$.